PHILIPS

Data handbook

Electronic components and materials

Electron tubes

Part 5 February 1983

Cathode-ray tubes

ELECTRON TUBES

PART 5 - FEBRUARY 1983

CATHODE-RAY TUBES

DATA HANDBOOK SYSTEM

Our Data Handbook System is a comprehensive source of information on electronic components, sub-assemblies and materials; it is made up of four series of handbooks each comprising several parts.

ELECTRON TUBES	BLUE
SEMICONDUCTORS	RED
INTEGRATED CIRCUITS	PURPLE
COMPONENTS AND MATERIALS	GREEN

The several parts contain all pertinent data available at the time of publication, and each is revised and reissued periodically.

Where ratings or specifications differ from those published in the preceding edition they are pointed out by arrows. Where application information is given it is advisory and does not form part of the product specification.

If you need confirmation that the published data about any of our products are the latest available, please contact our representative. He is at your service and will be glad to answer your inquiries.

ELECTRON TUBES (BLUE SERIES)

The blue series of data handbooks is comprised of the following parts:

T1 **Tubes for r.f. heating**

T2 **Transmitting tubes for communications**

T3 **Klystrons, travelling-wave tubes, microwave diodes**

ET3 **Special Quality tubes, miscellaneous devices** (will not be reprinted)

T4 **Magnetrons**

T5 **Cathode-ray tubes**
Instrument tubes, monitor and display tubes, C.R. tubes for special applications

T6 **Geiger-Müller tubes**

T7 **Gas-filled tubes**
Segment indicator tubes, indicator tubes, dry reed contact units, thyratrons, industrial rectifying tubes, ignitrons, high-voltage rectifying tubes, associated accessories

T8 **Picture tubes and components**
Colour TV picture tubes, black and white TV picture tubes, colour monitor tubes for data graphic display, monochrome monitor tubes for data graphic display, components for colour television, components for black and white television and monochrome data graphic display

T9 **Photo and electron multipliers**
Photomultiplier tubes, phototubes, single channel electron multipliers, channel electron multiplier plates

T10 **Camera tubes and accessories, image intensifiers**

T11 **Microwave components and assemblies**

SEMICONDUCTORS (RED SERIES)

The red series of data handbooks is comprised of the following parts:

S1 **Diodes**
Small-signal germanium diodes, small-signal silicon diodes, voltage regulator diodes($<$ 1,5 W), voltage reference diodes, tuner diodes, rectifier diodes

S2 **Power diodes, thyristors, triacs**
Rectifier diodes, voltage regulator diodes ($>$ 1,5 W), rectifier stacks, thyristors, triacs

S3 **Small-signal transistors**

S4 **Low-frequency power transistors and hybrid IC modules**

S5 **Field-effect transistors**

S6 **R.F. power transistors and modules**

S7 **Microminiature semiconductors for hybrid circuits**

S8 **Devices for optoelectronics**
Photosensitive diodes and transistors, light-emitting diodes, displays, photocouplers, infrared sensitive devices, photoconductive devices.

S9 Taken into handbook T11 of the blue series

S10 **Wideband transistors and wideband hybrid IC modules**

INTEGRATED CIRCUITS (PURPLE SERIES)

The purple series of data handbooks is comprised of the following parts:

IC1 **Bipolar ICs for radio and audio equipment**

IC2 **Bipolar ICs for video equipment**

IC3 **ICs for digital systems in radio, audio and video equipment**

IC4 **Digital integrated circuits**
LOCMOS HE4000B family

IC5 **Digital integrated circuits — ECL**
ECL10 000 (GX family), ECL100 000 (HX family), dedicated designs

IC6* **Professional analogue integrated circuits**

IC7 **Signetics bipolar memories**

IC8 **Signetics analogue circuits**

IC9 **Signetics TTL logic**

* This handbook will be available later this year.

January 1983

COMPONENTS AND MATERIALS (GREEN SERIES)

The green series of data handbooks is comprised of the following parts:

C1 **Assemblies for industrial use**
PLC modules, PC20 modules, HNIL FZ/30 series, NORbits 60-, 61-, 90-series, input devices, hybrid ICs, peripheral devices

C2 **Television tuners, video modulators, surface acoustic wave filters**

C3 **Loudspeakers**

C4 **Ferroxcube potcores, square cores and cross cores**

C5 **Ferroxcube for power, audio/video and accelerators**

C6 **Electric motors and accessories**
Permanent magnet synchronous motors, stepping motors, direct current motors

C7 **Variable capacitors**

C8 **Variable mains transformers**

C9 **Piezoelectric quartz devices**
Quartz crystal units, temperature compensated crystal oscillators, compact integrated oscillators, quartz crystal cuts for temperature measurements

C10 **Connectors**

C11 **Non-linear resistors**
Voltage dependent resistors (VDR), light dependent resistors (LDR), negative temperature coefficient thermistors (NTC), positive temperature coefficient thermistors (PTC)

C12 **Variable resistors and test switches**

C13 **Fixed resistors**

C14 **Electrolytic and solid capacitors**

C15 **Film capacitors, ceramic capacitors**

C16 **Piezoelectric ceramics, permanent magnet materials**

GENERAL AND SCREEN TYPES

LIST OF SYMBOLS

Symbols denoting electrodes and electrode connections

Heater	f
Cathode	k
Grid Grids are distinguished by means of an additional numeral; the electrode nearest to the cathode having the lowest number	g
Deflection plates intended for deflection in horizontal direction	x_1, x_2
Deflection plates intended for deflection in vertical direction Sectioned deflection plates are indicated by an additional decimal e.g. $y_{1.1}$ $y_{1.2}$ and $y_{2.1}$ $y_{2.2}$	y_1, y_2
External conductive coating	m
Fluorescent screen	ℓ
Tube pin which must not be connected externally	i.c.
Tube pin which may be connected externally	n.c.

Symbols denoting voltages

Symbol for voltage, followed by an index denoting the relevant electrode	V
Heater voltage (r.m.s. value)	V_f
Peak value of a voltage	V_p
Peak-to-peak value of a voltage	$V_{(p-p)}$

Symbols denoting currents

Symbol for current followed by an index denoting the relevant electrode	I
Heater current (r.m.s. value)	I_f

Symbols denoting powers

Dissipation of the fluorescent screen	W_ℓ
Grid dissipation	W_g

Symbols denoting capacitances

See IEC Publication 100.

Symbols denoting resistances

Symbol for resistance followed by an index for the relevant electrode pair. When only one index is given the second electrode is the cathode	R

When R is replaced by Z the "resistance" should read "impedance"

Symbols denoting various quantities

Luminance	L
Frequency	f
Magnetic field strength	H
Deflection coefficient	M
Scan magnification	M_{sc}
Bandwidth	B
Line width	l.w.
Eccentricity	e
Pulse duration	t_p

OPERATIONAL RECOMMENDATIONS

GENERAL

Unless otherwise stated the published data are typical values.

TYPICAL OPERATION

Under this heading in the data sheets, the conditions are given which result in the specified performance. This performance represents the best compromise for the intended applications of the tube.

LIMITING VALUES

Unless otherwise stated the tubes are rated according to the absolute maximum rating system.

Limiting values are in accordance with the applicable rating system as defined by IEC publication 134. Reference may be made to one of the following 3 rating systems.

Absolute maximum rating system. Absolute maximum ratings are limiting values of operating and environmental conditions applicable to any electronic device of a specified type as defined by its published data, and should not be exceeded under the worst probable conditions.
These values are chosen by the device manufacturer to provide acceptable serviceability of the device, taking no responsibility for equipment variations, environmental variations, and the effects of changes in operating conditions due to variations in the characteristics of the device under consideration and of all other electronic devices in the equipment.

The equipment manufacturer should design so that, initially and throughout life, no absolute maximum value for the intended service is exceeded with any device under the worst probable operating conditions with respect to supply voltage variation, equipment components spread and variation, equipment control adjustment, load variations, signal variation, environmental conditions, and spread or variations in characteristics of the device under considerations and of all other electronic devices in the equipment.

Design-maximum rating system. Design-maximum ratings are limiting values of operating and environmental conditions applicable to a bogey electronic device* of a specified type as defined by its published data, and should not be exceeded under the worst probable conditions.

These values are chosen by the device manufacturer to provide acceptable serviceability of the device, taking responsibility for the effects of changes in operating conditions due to variations in the characteristics of the electronic device under consideration.

The equipment manufacturer should design so that, initially and throughout life, no design-maximum value for the intended service is exceeded with a bogey device under the worst probable operating conditions with respect to supply-voltage variation, equipment component variation, variation in characteristics of all other devices in the equipment, equipment control adjustment, load variation, signal variation and environmental conditions.

* A bogey tube is a tube whose characteristics have the published nominal values for the type. A bogey tube for any particular application can be obtained by considering only those characteristics which are directly related to the application.

Design-centre rating system. Design-centre ratings are limiting values of operating and environmental conditions applicable to a bogey electronic device* of a specified type as defined by its published data, and should not be exceeded under average conditions.

These values are chosen by the device manufacturer to provide acceptable serviceability of the device in average applications, taking responsibility for normal changes in operating conditions due to rated supply-voltage variation, equipment component spread and variation, equipment control adjustment, load variation, signal variation, environmental conditions, and variations or spread in the characteristics of all electronic devices.

The equipment manufacturer should design so that, initially, no design-centre value for the intended service is exceeded with a bogey electronic device* in equipment operating at the stated normal supply voltage.
If the tube data specify limiting values according to more than one rating system the circuit has to be designed so that none of these limiting values is exceeded under the relevant conditions.

In addition to the limiting values given in the individual data sheets the directives in the following paragraphs should be observed.

HEATER SUPPLY

The heater voltage must be within ± 7% of the nominal value when the supply voltage is at its nominal value, and when a tube having the published heater characteristics is employed. This figure is permissible only if the voltage variation is dependent upon more than one factor. In these circumstances the total tolerance may be taken as the square root of the sum of the squares of the individual deviations arising from the effect of the tolerances of the separate factors, providing none of these deviations exceeds ± 5%. Should the voltage variation depend on one factor only, the voltage variation must not exceed ± 5%.

For maximum cathode life it is recommended that the heater supply be stabilized at the nominal heater voltage. Any deviation from this heater voltage has a detrimental effect on tube performance and life, and should therefore be kept to a minimum. Such deviations may be caused by:

- mains voltage fluctuations;
- spread in the characteristics of components such as transformers, resistors, capacitors, etc.;
- spread in circuit adjustments;
- operational variations.

Cathode-ray tubes with a quick-heating cathode should not be used in series with other tubes.

CATHODE TO HEATER VOLTAGE

The voltage between cathode and heater should be as low as possible and never exceed the limiting values given in the data sheets of the individual tubes. Operation with the heater positive with respect to the cathode is not recommended.

In order to avoid excessive hum the a.c. component of the heater to cathode voltage should be as low as possible and never exceed 20 V r.m.s. (mains frequency). A d.c. connection should always be present between heater and cathode. Unless otherwise specified the maximum resistance should not exceed 1 MΩ; the maximum impedance at mains frequency should be less than 100 kΩ.

INTERMEDIATE ELECTRODES (between cathode and final accelerator)

In no circumstances should the tube be operated without a d.c. connection between each electrode and the cathode. The total effective impedance between each electrode and the cathode should be as low as possible and never exceed the published maximum value.

* A bogey tube is a tube whose characteristics have the published nominal values for the type. A bogey tube for any particular application can be obtained by considering only those characteristics which are directly related to the application.

ELECTRODE VOLTAGES

The reference point for electrode voltages is the cathode. For cathode drive service the reference point is grid 1.

Grid cut-off voltages

Values are given for the limits of grid cut-off voltage at the specified first accelerator voltage. The brightness control voltage should be arranged so that it can handle any tube within the limits shown, at the appropriate first accelerator voltage.

First accelerator voltage

The first accelerator electrode of a so-called unipotential lens provides independent focus and brightness controls by applying a fixed voltage. Care should be taken not to exceed the maximum and minimum limits for reasons of reliability and performance.

Focusing voltage

The focusing voltage (V_{g3}) should be adjusted to optimum spot size; the voltage may depend on the beam current.
For automatic pre-adjustment (autofocus) of oscilloscope tubes, ΔV_{g3} should be derived from the grid drive.

Astigmatism control voltage

To achieve optimum performance under all conditions it is desirable to apply a voltage for control of astigmatism (a difference in potential of this electrode and the y plates). The required range to cover any tube is given in the relevant data.

Deflection plate shield voltage

It is essential that the deflection plate shield voltage equals the mean y plate voltage.

Geometry control voltage

By varying the potential of the geometry control electrode, the necessary range of which is given in the relevant data, the occurrence of pin-cushion and barrel-pattern distortion can be controlled.

Deflection voltages

For optimum performance it is essential that true symmetrical voltages are applied. It should further be noted that the mean x and y-plate potentials must be equal. Moreover the deflection plate shield voltage, the mean astigmatism control voltage, if applicable the mean beam centring voltage and the geometry control voltage should also be equal to the mean x and y-plate potentials. If use is made of the full deflection capabilities of the tube, the deflection plates will intercept part of the electron beam near the edge of the scan. Therefore a low impedance deflection plate drive is necessary. (See also ELECTRODE CURRENTS AND CIRCUIT IMPEDANCES on the next page.)

Raster distortion and its determination

Limits of raster distortion are given for most tubes.

A graticule, consisting of concentric rectangles is aligned with the electrical x-axis of the tube. The edges of a raster will fall between these rectangles with optimum correction potentials applied.

Measuring procedure:
- Shift the x-trace to the centre of the graticule.
- Align horizontal centre line of graticule with the centre line of the x-trace.
- Shift x-trace vertically between upper and lower horizontal lines of graticule; the centre of the x-trace now will not fall outside the area bounded by the horizontal graticule lines.
- Without moving the graticule, switch to a vertical trace and shift this trace horizontally (left and right) between the pairs of vertical lines of the graticule; the centre of the y-trace will not fall outside the area bounded by the vertical graticule lines.
- Focus and astigmatism will be adjusted for optimum performance.
- Pattern geometry correction will be adjusted for optimum performance in the sense of minimizing simultaneously the deviation of the centre of x and y-trace respectively.

Linearity

The linearity is defined as the sensitivity at a deflection of 75% of the useful scan with respect to deviations from the sensitivity at a deflection of 25% of the useful scan. These sensitivities will not differ by more than the indicated value.

Post deflection shield voltage

In order to optimize contrast in mesh tubes a fixed negative voltage with respect to the geometry control voltage should be applied. The range is given in the data.

Final accelerator voltage

Tubes with PDA are designed for a given final accelerator voltage to first accelerator voltage ratio. Operation at higher or lower ratios may result in changes in deflection uniformity, pattern distortion and useful scan.

High tension supply

In order to avoid damage to the screen it is important that a deflection voltage, e.g. the time base voltage, is applied prior to the high tension.

ELECTRODE CURRENTS AND CIRCUIT IMPEDANCES

In each electrode currents caused by interception of a part of the electron beam, leakage or secondary emission, may occur in both directions. For oscilloscope tubes currents up to 10 μA can be expected in the focusing electrode and the deflection plates. In addition, if use is made of the full deflection capabilities, each deflection plate may intercept up to 50% of the beam current.

For oscilloscope tubes with beam-limiting apertures, the grid 2 and/or grid 4 circuit impedance should be less than 10 kΩ.

For all tubes the control grid circuit resistance should be less than 1 MΩ.

CAPACITANCES

Unless otherwise stated the values given are nominal values measured at the contacts of a cold tube. The contacts and measuring leads are screened.

LINE WIDTH

The line width is measured with the shrinking raster method. Focusing and astigmatism voltages should be adjusted to minimize the horizontal and vertical trace widths simultaneously at the screen centre. The raster width should be reduced until the line structure is just discernible. This raster width, divided by the number of lines in the display, is the measure of the line width.

USEFUL SCREEN AREA

This is the area on the inner side of the faceplate which is provided with phosphor; it may remain uncovered and thus visible from the outside.

USEFUL SCAN AREA

This is the part of the useful screen area in which the specified performance applies.

LUMINESCENT SCREEN

To prevent permanent screen damage, care should be taken:

- not to operate the tube with a stationary picture at high beam currents for extended periods;
- not to operate the tube with a stationary or slowly moving spot except at extremely low beam currents.

MOUNTING

Unless otherwise stated the tubes can be mounted in any position. However, a tube should not be supported by the base alone or near the base region, and under no circumstances should the socket be allowed to support the tube.

The tube socket should not be rigidly mounted but should have flexible leads and be allowed to move freely. The socket should not support any circuitry.

Shielding

Oscilloscope tubes need a magnetic shielding for proper operation. Especially for types with an internal permanent magnetic lens system (IMC), a magnetic induction at the tube neck greater than 0,02 T (200 gauss), which corresponds to a magnetic field strength of $1,6 \times 10^4$ A/m, must be avoided.

HANDLING

Handling (or destroying) tubes should be done by qualified personnel.

The tubes are evacuated, which implies that mechanical damage must be avoided; care should be taken not to scratch or knock any part of the tube.

Remember when replacing or servicing a tube that a residual electrical charge may be carried by the final accelerator contact and also the external coating if not earthed. Before removing the tube from the equipment, earth the external coating and short the final accelerator contact to the coating.

PHOTOMETRIC UNITS

S.I. photometric units

quantity	symbol	S.I. unit	remarks
luminous intensity	I	cd (candela)	
luminous flux	ϕ	lm (lumen)	
quantity of light	Q	lm · s	
luminance	L	cd/m^2	$1\ cd/m^2 = 1$ nit
luminous exitance	M	lm/m^2	formerly luminous emittance
illuminance	E	lx (lux)	formerly illumination

Other photometric units; conversion factors

1 stilb $= 1\ cd/cm^2 = 10^4\ cd/m^2 = 4\pi$ lumen/cm^2

1 lambert $= \frac{1}{\pi}\ cd/cm^2 = \frac{10^4}{\pi}\ cd/m^2 = 4$ lumen/cm^2

1 foot lambert $= \frac{1}{\pi}\ cd/ft^2 = 3{,}426\ cd/m^2$

1 foot candle $= 10{,}764$ lux

TYPE DESIGNATION

Pro Electron type designation code

The CRT type number begins with a single letter followed by two sets of digits, and ends with one or two letters.

The first letter indicates the prime application of the tube:

D : Oscilloscope tube, single trace

E : Oscilloscope tube, multiple trace

F : Radar display tube, direct view

L : Storage display tube

M : TV display tube for professional application, direct view

P : Display tube for professional application, projection

Q : Flying spot scanner tube

The first group of digits indicates the diameter or diagonal of the screen in cm.

The second group of digits is a two or three-figure serial number indicating a particular design or development.

The final group of letters indicates the properties of the phosphor screen (see section "Screen types").

For CRTs with internal graticule a suffix consisting of two or more figures follows the type designation, separated from it by an oblique stroke.

Example:

D14 – 360 GH/93

D	14	360	GH	/93
oscilloscope tube, single trace	face diagonal	design number	screen phosphor	internal graticule

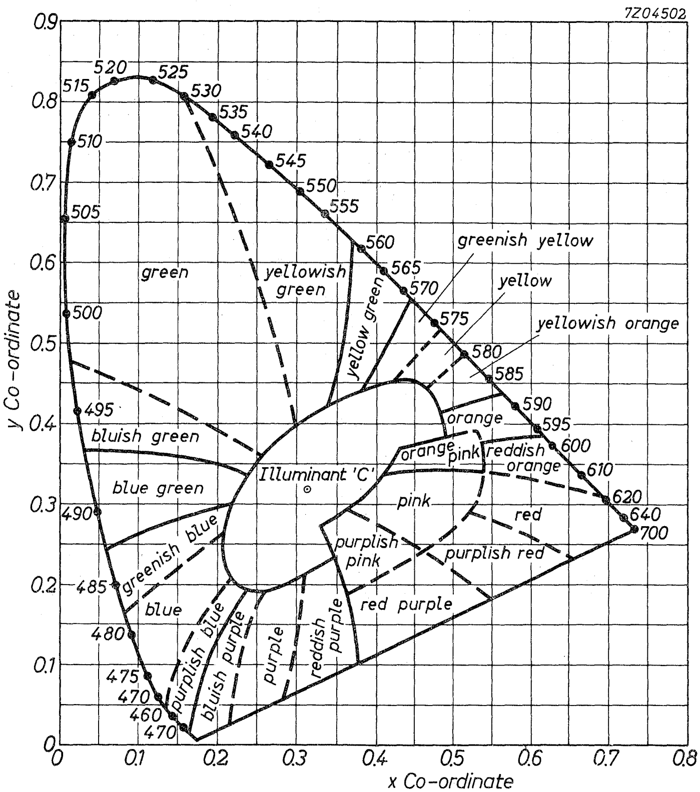
SCREEN TYPES

new system	old system	fluorescent colour	phosphorescent colour	persistence	equivalent JEDEC designation
BA	C	purplish-blue	–	very short	–
BE	B	blue	blue	medium short	P11
BF	U	purplish-blue	–	medium short	–
GH	H	green	green	medium short	P31
GJ	G	yellowish-green	yellowish-green	medium	P1
GK	G	yellowish-green	yellowish-green	medium	–
GM	P	purplish-blue	yellowish-green	long	P7
GP	–	bluish-green	green	medium short	P2
GR	–	green	green	long	P39
GU	–	white	white	very short	–
GY	–	green	green	–	P43
KC	–	yellow-green	yellow-green	medium short	–
LA	D	orange	orange	medium	–
LB	E	orange	orange	long	–
LC	F	orange	orange	very long	–
LD	L	orange	orange	very long	P33
W	W	white	–	–	P4
WA	–	white	–	–	
WE	–	white	white	medium short	P45
X	X	tri-colour screen	–	–	–
YA	Y	yellowish-orange	yellowish-orange	medium	–

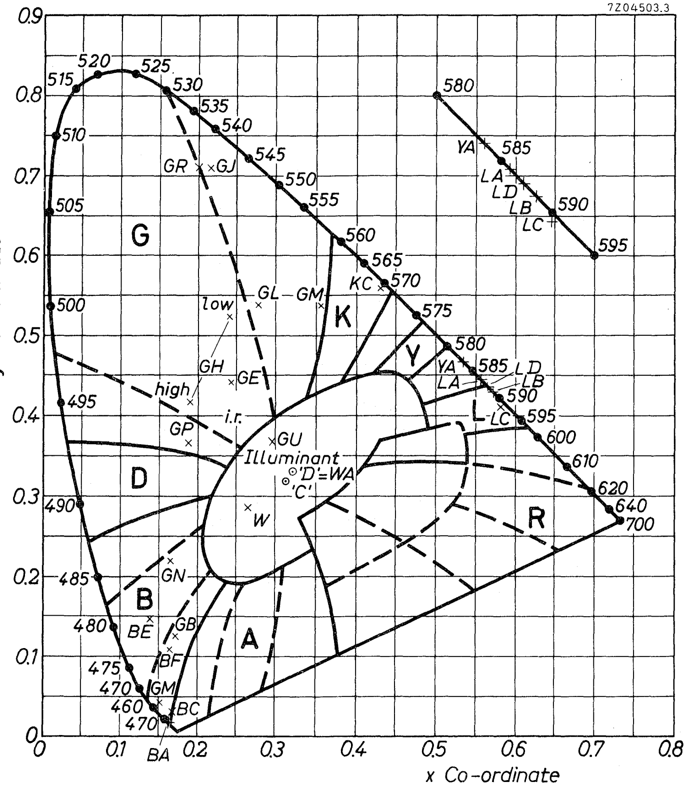
The phosphor information given in this section is based in general upon the original phosphor registration (TEPAC and/or PRO ELECTRON) and can be used as a selection guide. Slight differences may occur between the actual phosphor properties and the registered data.

Survey of applications and persistence of screens

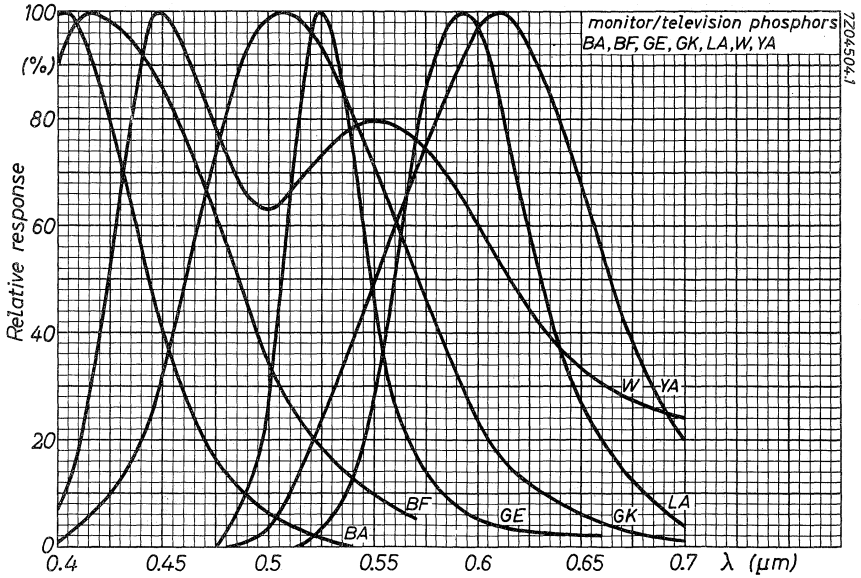
application	phosphor	conditions (display: spot)				persistence		remark
		screen voltage	screen current (peak value)	pulse width	repetition time	relative level of luminance		
						10%	1%	
oscilloscope tubes	BE	4 kV	20 μA	2 μs	10 ms	34 μs	220 μs	
	GH	4 kV	20 μA	2 μs	10 ms	38 μs	250 μs	
	GJ	4 kV	2,5 μA	spot switched off after 5 s		24,5 ms		
	GM	4 kV	2 μA	raster switched off after 5 s		0,4 s	3 s	yellow filter
	GP	4 kV	2 μA	100 μs	single shot	100 μs		
	GY	4 kV	20 μA	2 μs	10 ms	1,5 ms	3 ms	
monitor tubes	GR, W, WA, WE, KC	see relevant curves for persistence						
projection tubes	BF, YA	see relevant curves for persistence						
flying-spot scanner tubes	BA, GU	see relevant curves for persistence						

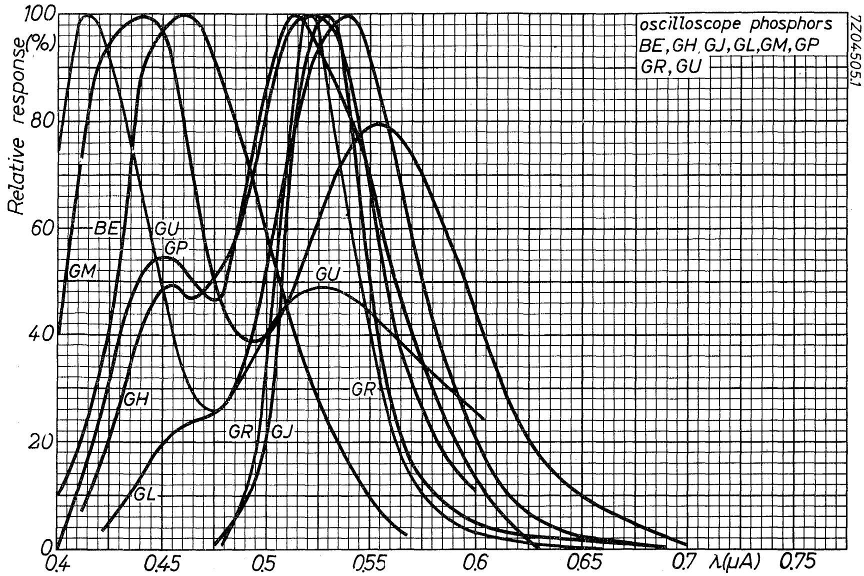

7Z04502
0.9
0.8
0.7
0.6
0.5
0.4
0.3
0.2
0.1
0
y Co-ordinate
520
525
515
530
535
540
510
545
550
555
505
560
565
570
575
580
585
590
595
600
610
620
640
700
500
495
490
485
480
475
470
460
470
green
yellowish
green
yellow green
greenish yellow
yellow
yellowish orange
orange
orange
pink
reddish
orange
bluish green
blue green
Illuminant 'C'
pink
red
greenish blue
purplish
pink
purplish red
blue
red purple
purplish blue
bluish purple
purple
reddish
purple
0
0.1
0.2
0.3
0.4
0.5
0.6
0.7
0.8
x Co-ordinate

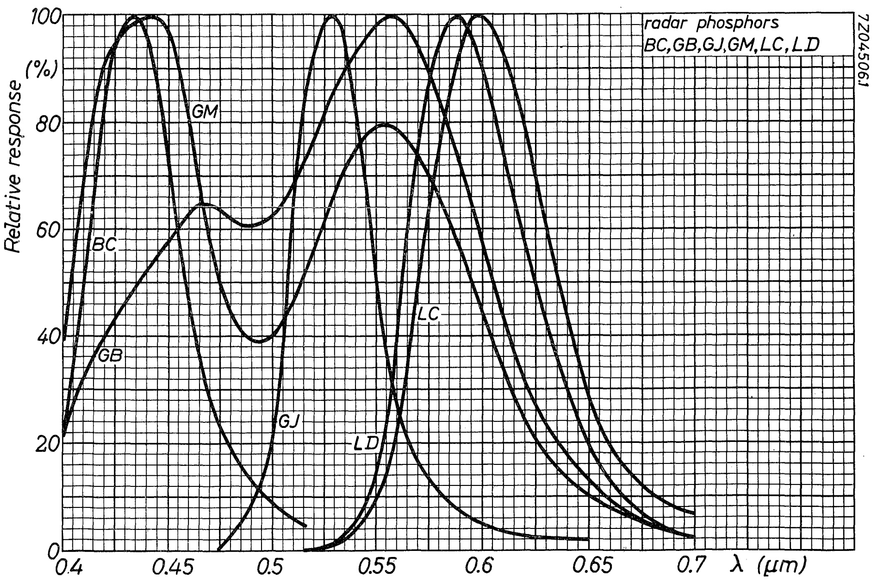
Kelly Chart

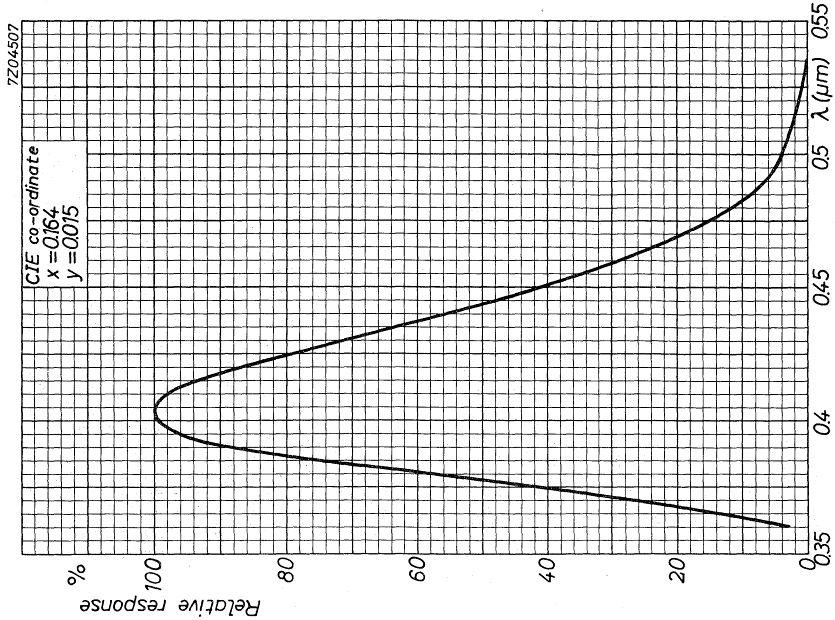


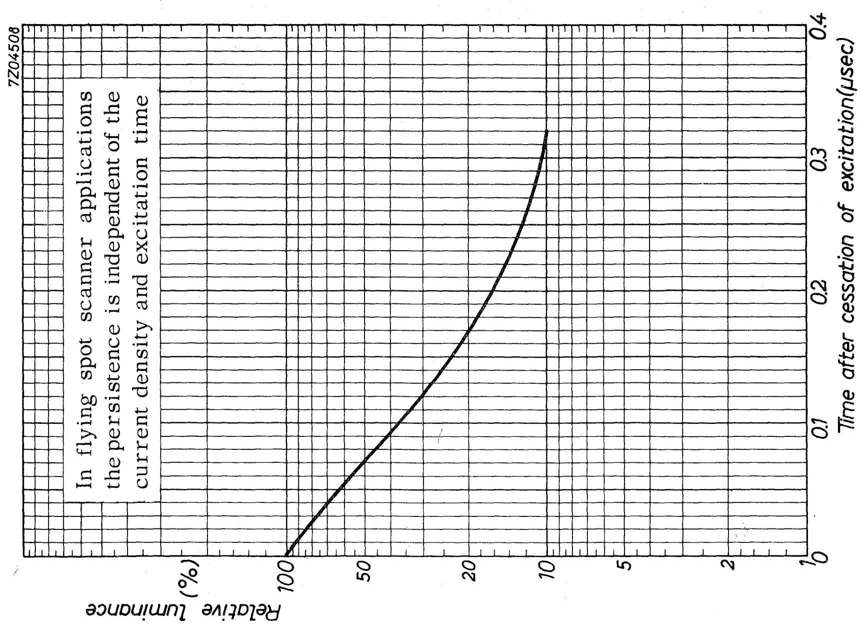
Co-ordinates of individual phosphors

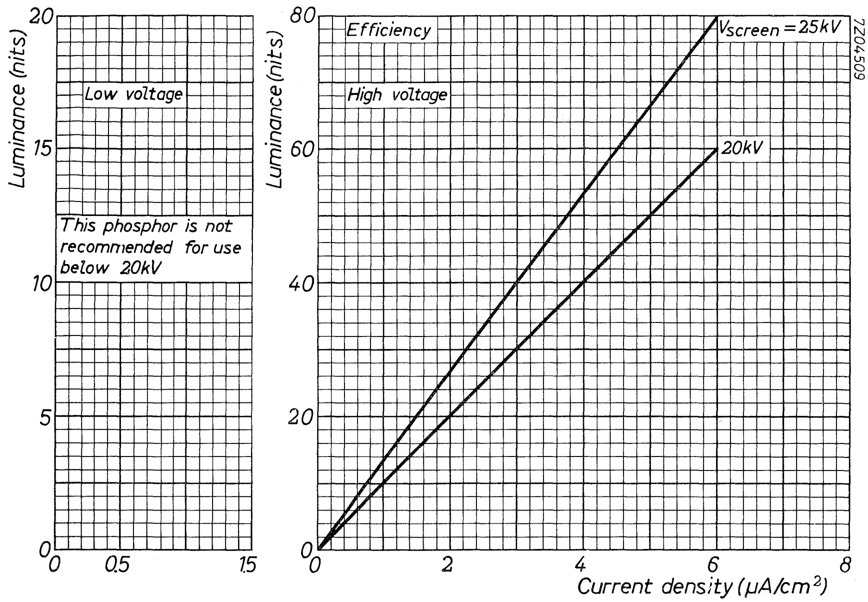

monitor/television phosphors
BA, BF, GE, GK, LA, W, YA
7Z04504.1
100
(%)
80
60
40
20
0
Relative response
0.4
0.45
0.5
0.55
0.6
0.65
0.7
λ (μm)
BA
BF
GE
GK
LA
W
YA

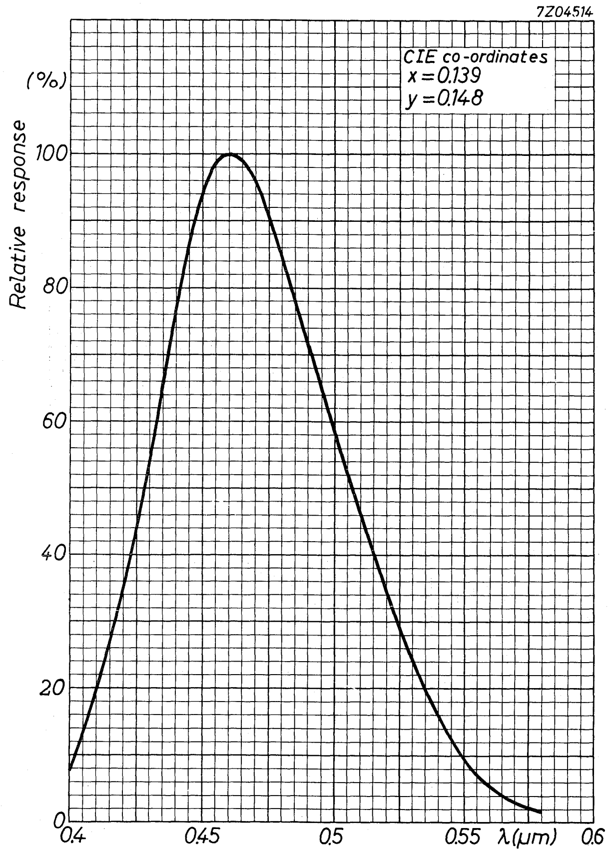

oscilloscope phosphors
BE, GH, GJ, GL, GM, GP
GR, GU
7Z04505.1
Relative response (%)
100
80
60
40
20
0
BE
GU
GP
GM
GU
GH
GR
GR
GJ
GL
0.4
0.45
0.5
0.55
0.6
0.65
0.7
λ(μA)
0.75

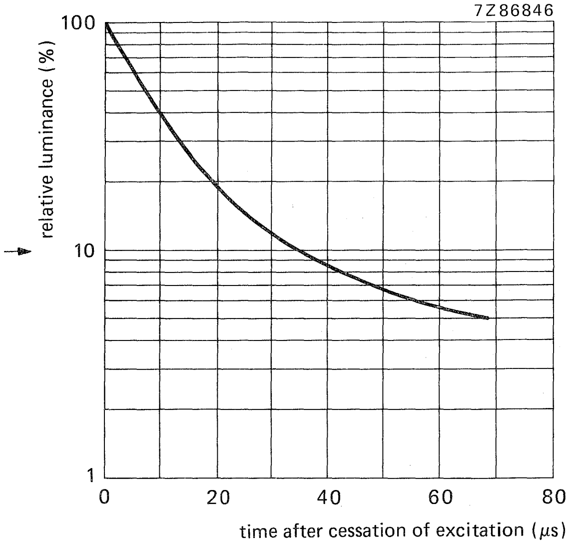

radar phosphors
BC, GB, GJ, GM, LC, LD
7Z04506.1
Relative response (%)
100
80
60
40
20
0
GM
BC
GB
LC
GJ
LD
0.4
0.45
0.5
0.55
0.6
0.65
0.7
λ (μm)


7Z04507
CIE co-ordinate
x = 0.164
y = 0.015
Relative response
%
100
80
60
40
20
0
0.35
0.4
0.45
0.5
0.55
λ (μm)

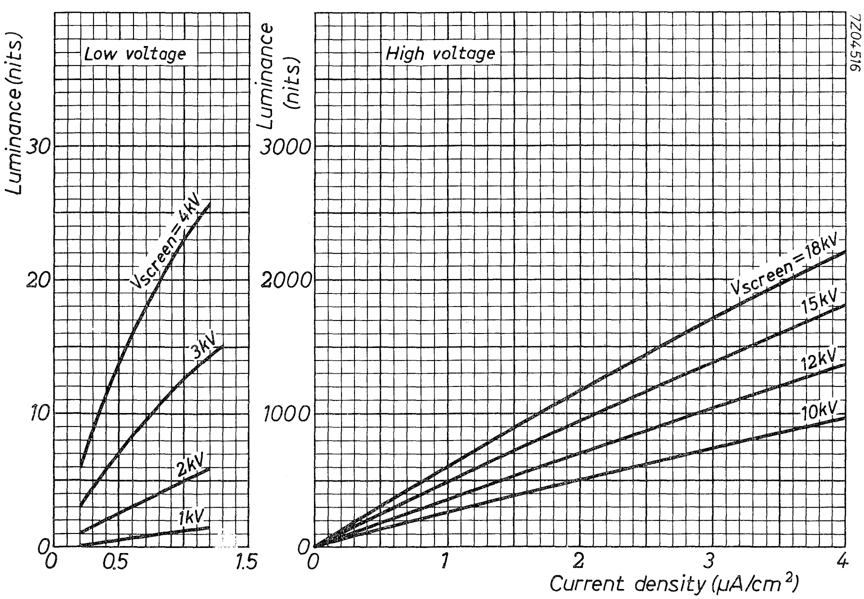

7Z04508
In flying spot scanner applications the persistence is independent of the current density and excitation time
Relative luminance (%)
100
50
20
10
5
2
1
0
0.1
0.2
0.3
0.4
Time after cessation of excitation (μsec)

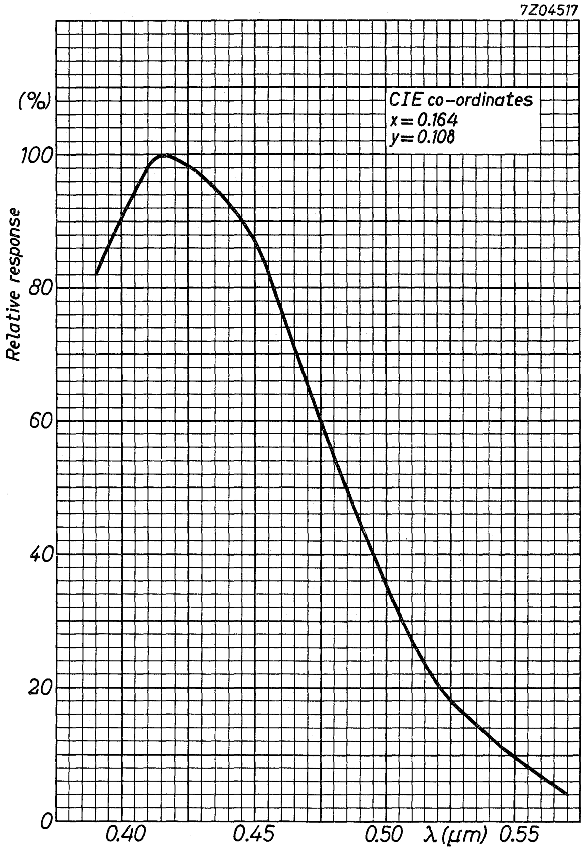

Luminance (nits)
20
15
10
5
0
Low voltage
This phosphor is not recommended for use below 20kV
0
0.5
1.5
Luminance (nits)
80
60
40
20
0
Efficiency
High voltage
V_{screen} = 25kV
20kV
7Z04509
0
2
4
6
8
Current density ($\mu A/cm^2$)

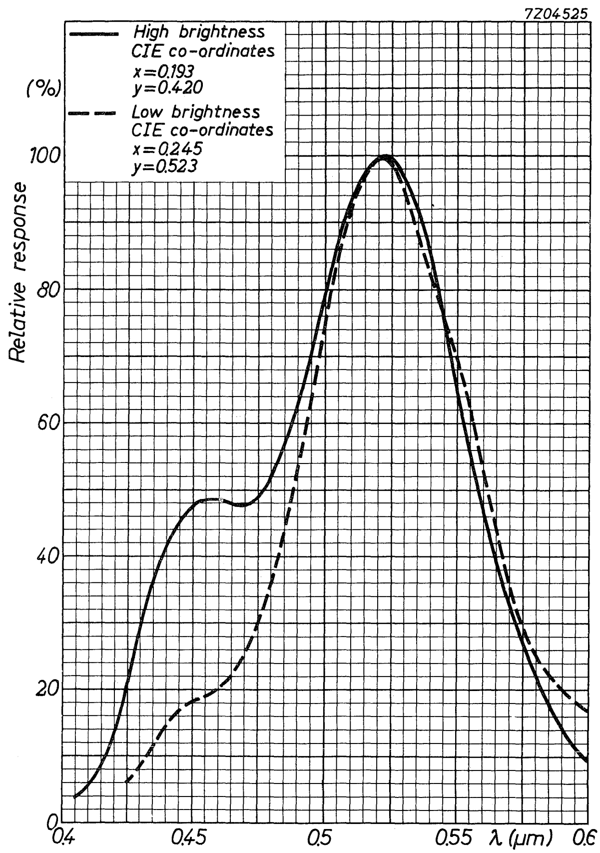

7Z04514
CIE co-ordinates
x = 0.139
y = 0.148
(%)
Relative response
100
80
60
40
20
0
0.4
0.45
0.5
0.55
λ(μm)
0.6

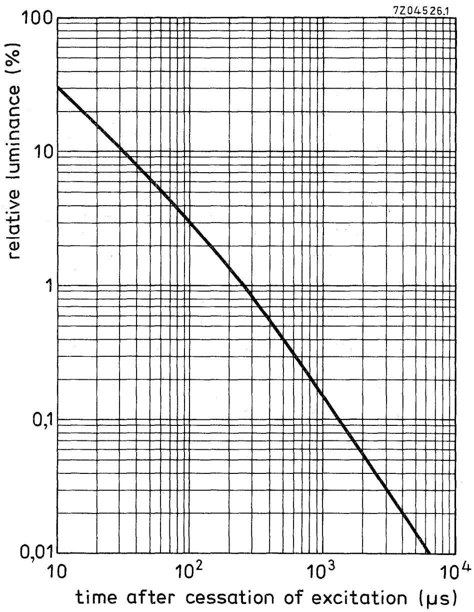


Screen voltage	4 kV
Screen current	20 μA
Pulse width	2 μs
Repetition time	10 ms



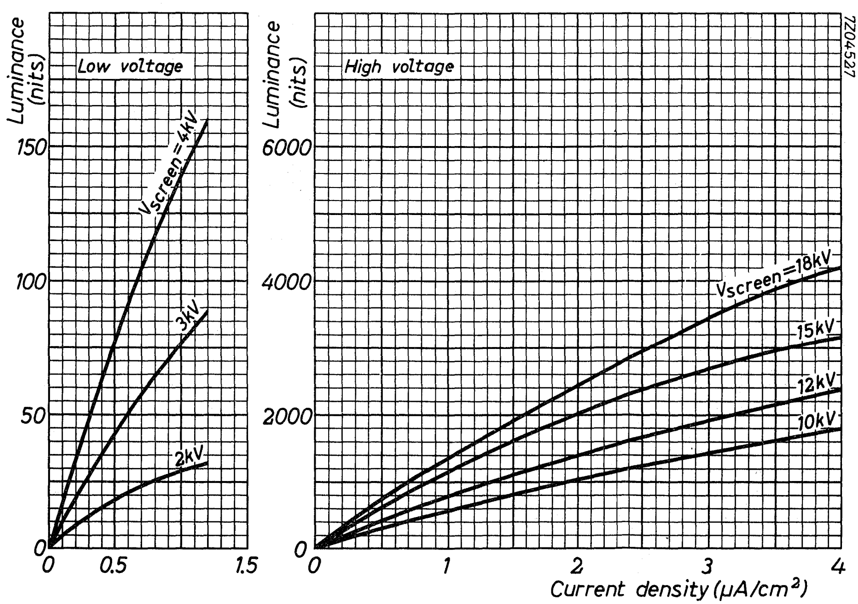

7Z04517
CIE co-ordinates
x = 0.164
y = 0.108
(%)
Relative response
100
80
60
40
20
0
0.40
0.45
0.50
λ (μm)
0.55

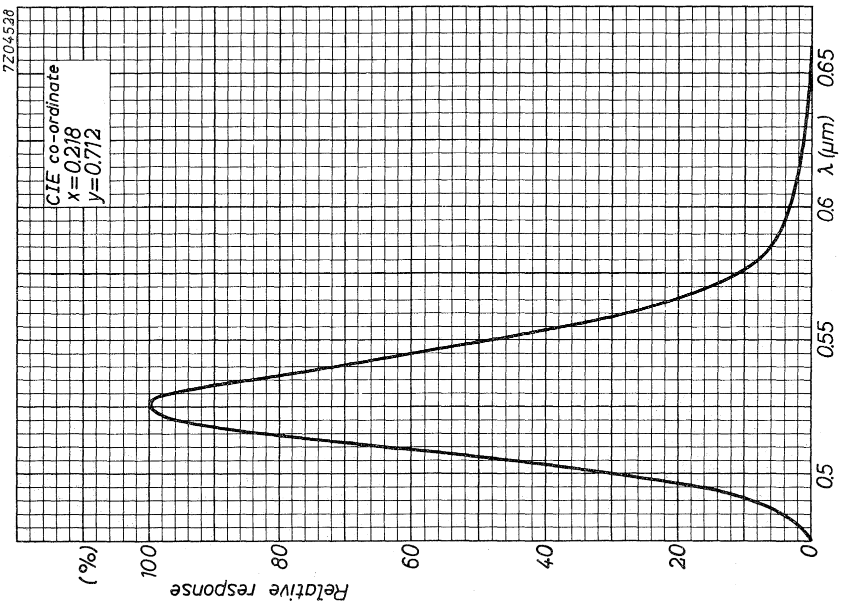

7Z04525
High brightness
CIE co-ordinates
x=0.193
y=0.420
Low brightness
CIE co-ordinates
x=0.245
y=0.523
(%)
Relative response
100
80
60
40
20
0
0.4
0.45
0.5
0.55
λ (μm)
0.6

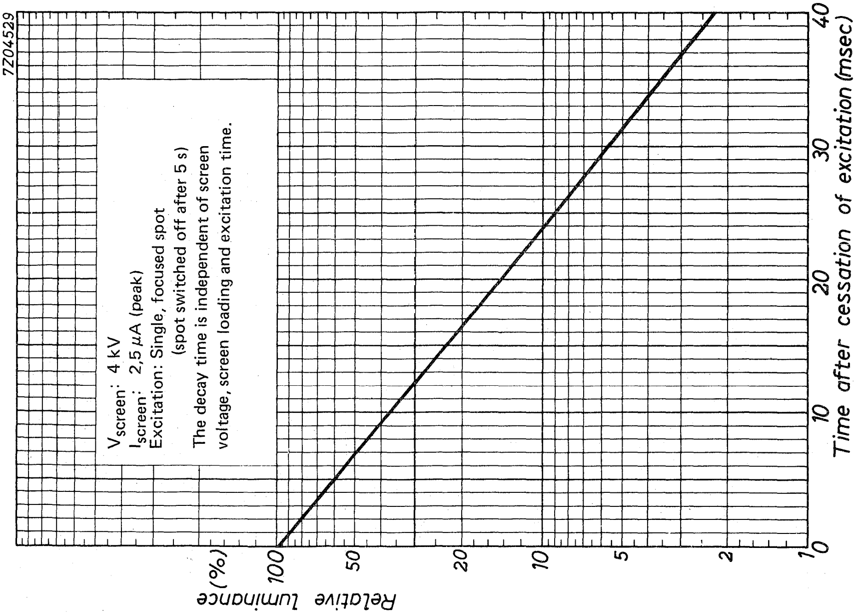


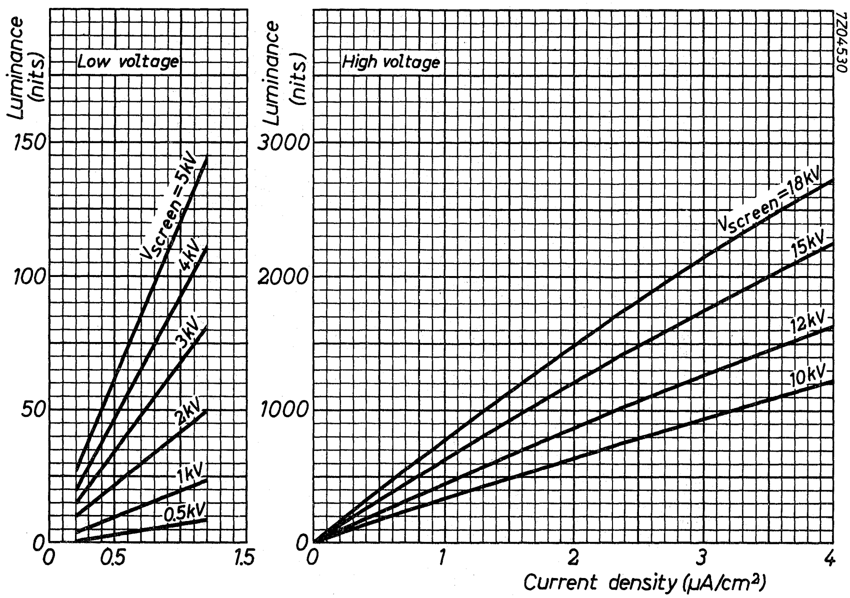
Screen voltage	4	kV
Screen current	20	μA
Pulse width	2	μs
Repetition time	10	ms
Excitation	single focused spot	

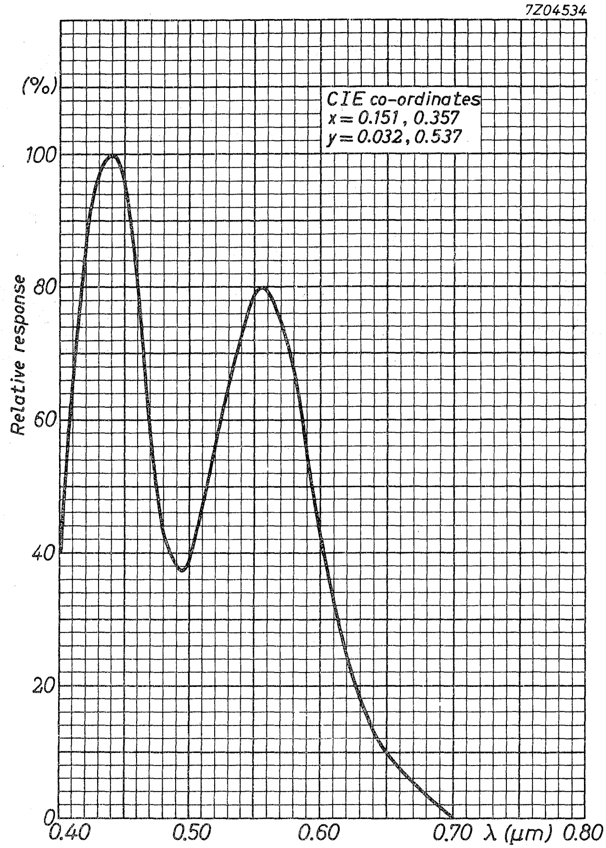
At lower screen voltage, lower screen loading or longer excitation time, the decay time will be longer.

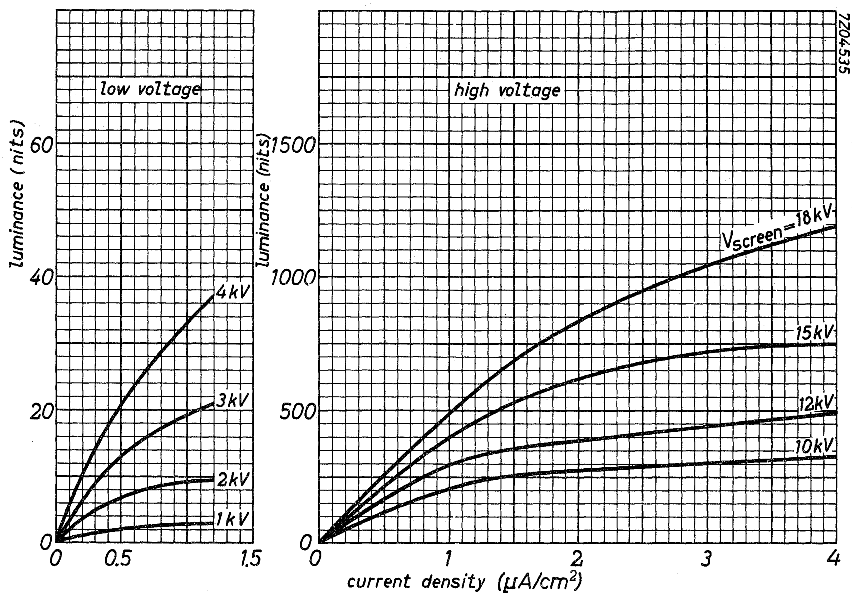


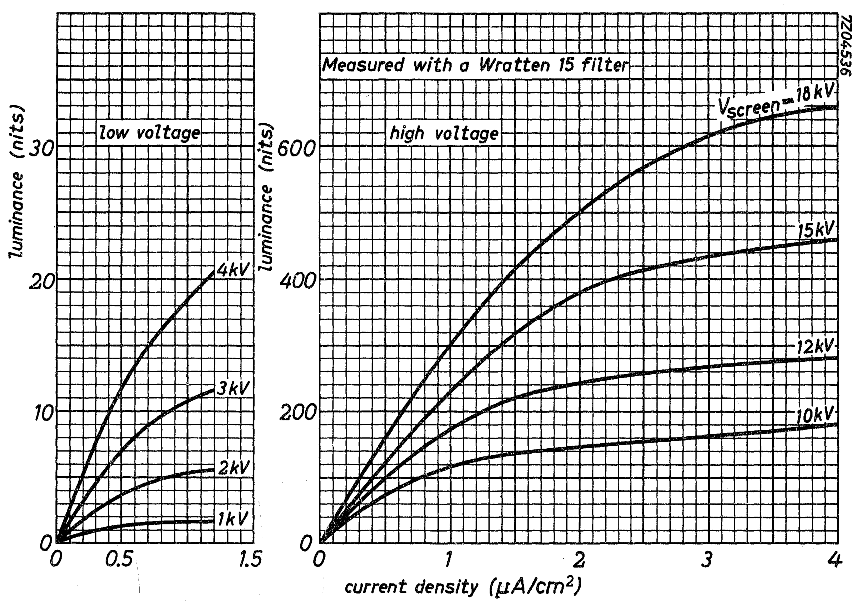

7Z04538
CIE co-ordinate
x=0.218
y=0.712
Relative response (%)
100
80
60
40
20
0
0.5
0.55
0.6
0.65
λ (μm)

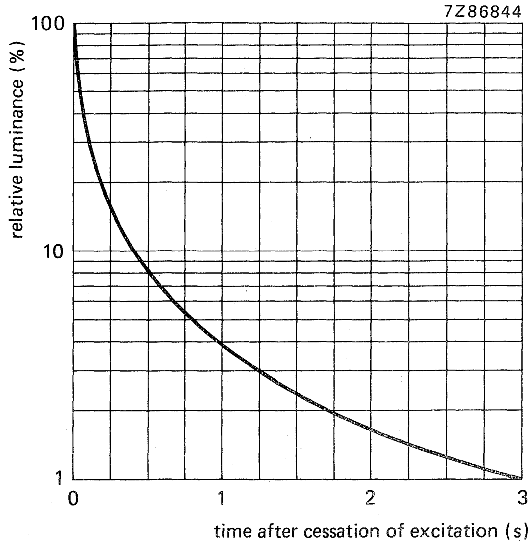

7Z04529
V_{screen}: 4 kV
I_{screen}: 2,5 μA (peak)
Excitation: Single, focused spot
(spot switched off after 5 s)
The decay time is independent of screen voltage, screen loading and excitation time.
Relative luminance (%)
100
50
20
10
5
2
1
0
10
20
30
40
Time after cessation of excitation (msec)


Luminance (nits)
Low voltage
150
100
50
0
0
0.5
1.5
Vscreen=5kV
4kV
3kV
2kV
1kV
0.5kV
Luminance (nits)
High voltage
3000
2000
1000
0
0
1
2
3
4
Vscreen=18kV
15kV
12kV
10kV
Current density (μA/cm²)
7Z04530

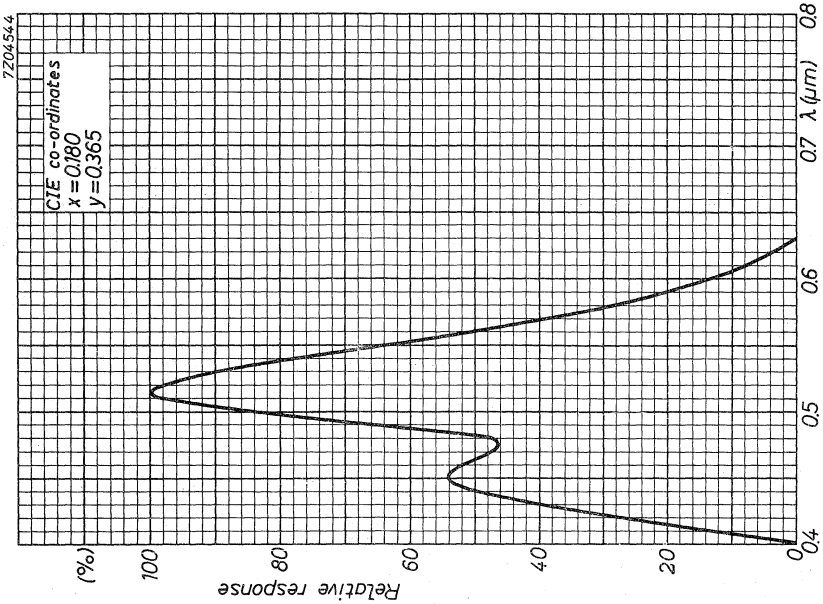

7Z04534
(%)
CIE co-ordinates
x = 0.151, 0.357
y = 0.032, 0.537
100
80
60
40
20
0
Relative response
0.40
0.50
0.60
0.70 λ (μm) 0.80

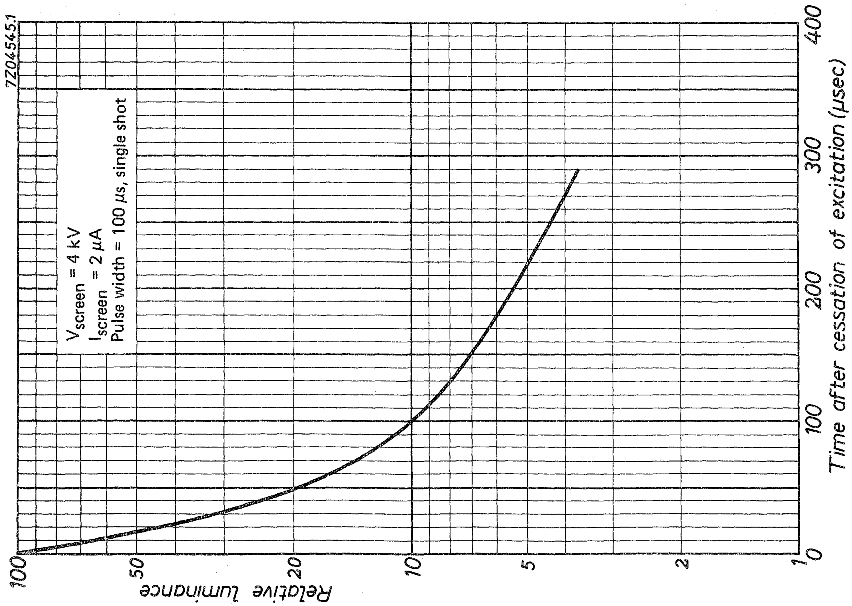

7Z04535
low voltage
luminance (nits)
60
40
20
0
4kV
3kV
2kV
1kV
0
0.5
1.5
high voltage
luminance (nits)
1500
1000
500
0
V_{screen}=18kV
15kV
12kV
10kV
0
1
2
3
4
current density (μA/cm²)

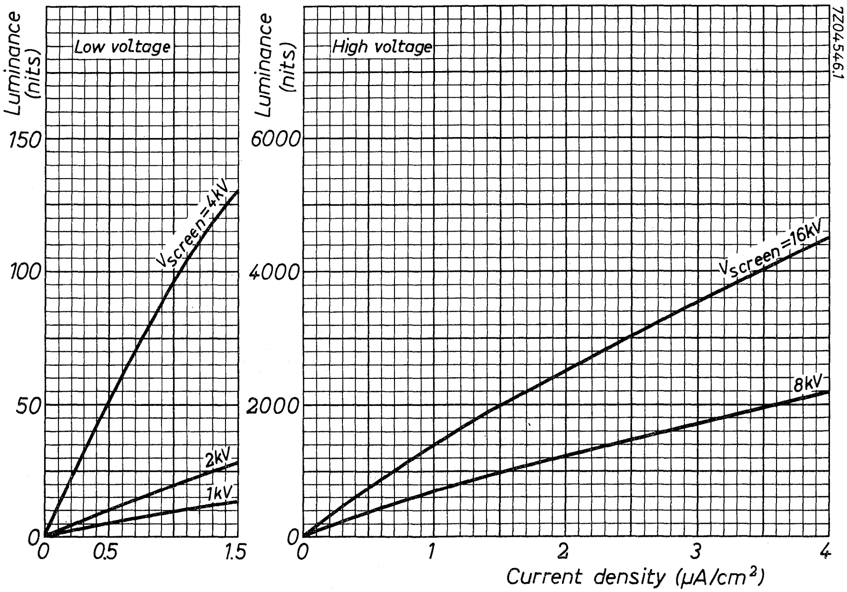

7Z04536
Measured with a Wratten 15 filter
low voltage
luminance (nits)
30
20
10
0
4kV
3kV
2kV
1kV
0
0.5
1.5
high voltage
luminance (nits)
600
400
200
0
V_{screen}=18kV
15kV
12kV
10kV
0
1
2
3
4
current density (μA/cm²)

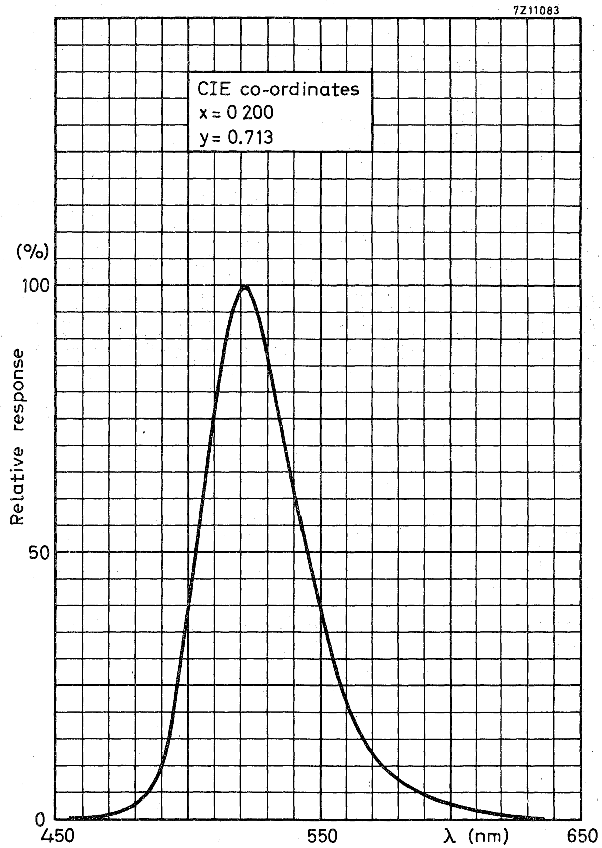


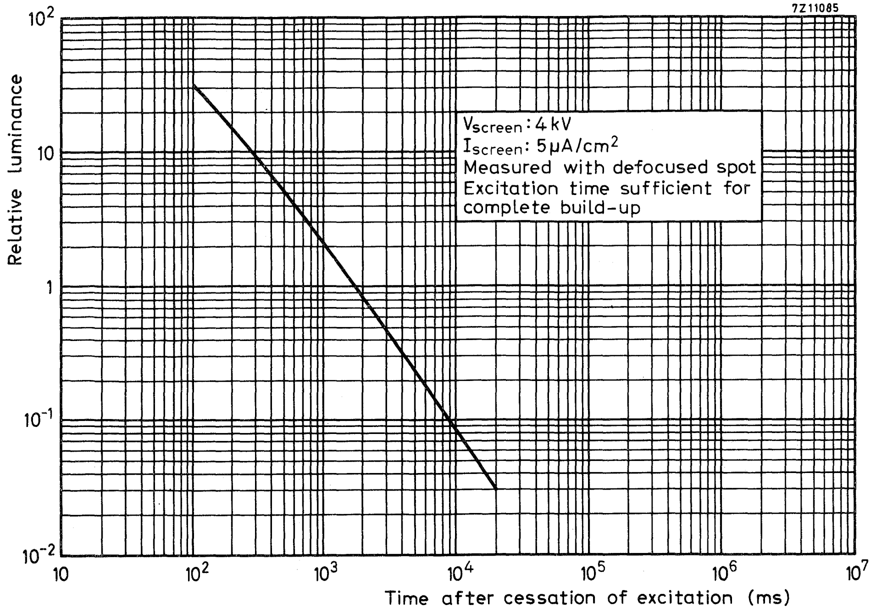
Screen voltage	4 kV
Screen current	2 μA
Raster	2 cm x 2 cm
Scanning time	5 s
Yellow filter	GG495

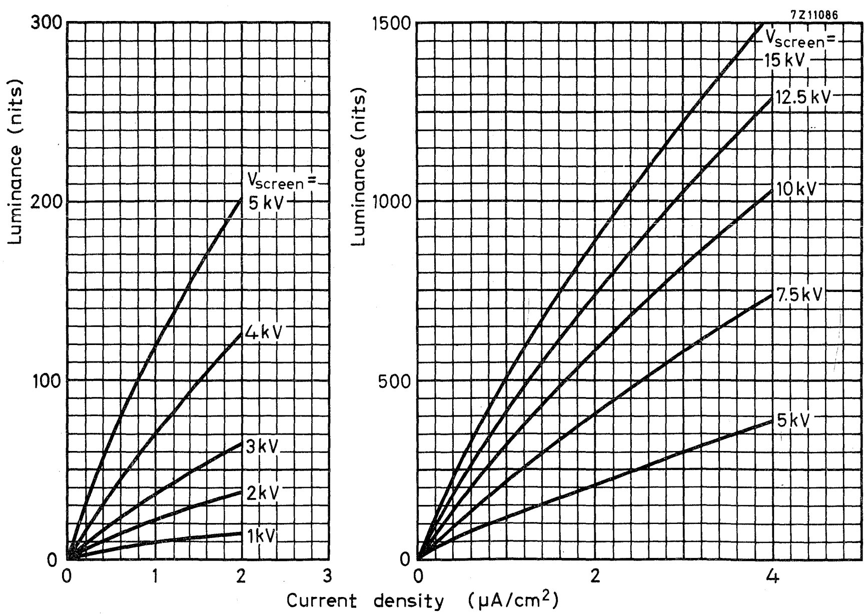

7Z04544
CIE co-ordinates
x = 0.180
y = 0.365
Relative response
(%)
100
80
60
40
20
0
0.4
0.5
0.6
0.7
0.8
λ (μm)

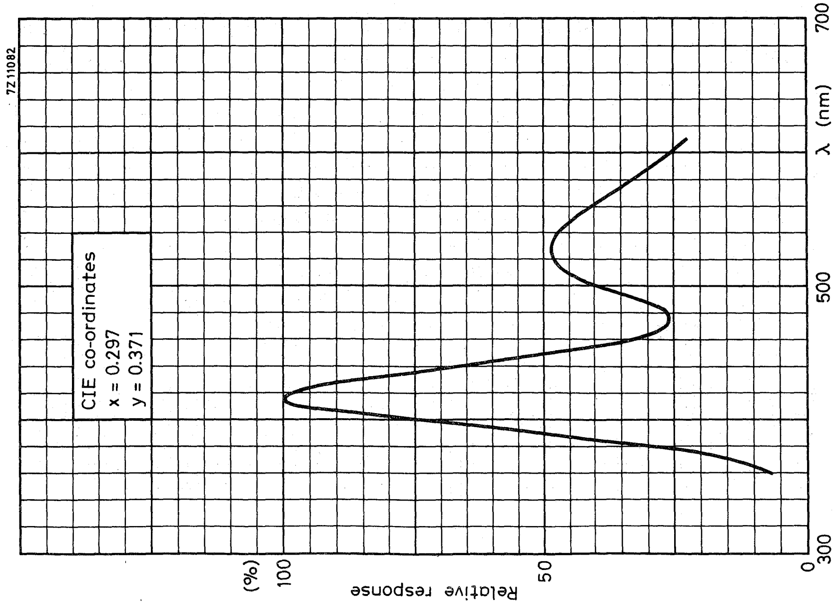

7Z04545.1
V_{screen} = 4 kV
I_{screen} = 2 μA
Pulse width = 100 μs, single shot
Relative luminance
100
50
20
10
5
2
1
0
100
200
300
400
Time after cessation of excitation (μsec)

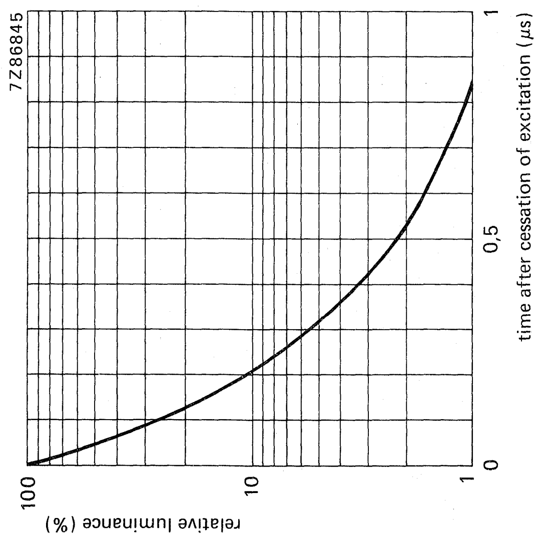

Low voltage
Luminance (nits)
150
100
50
0
0
0.5
1.5
Vscreen=4kV
2kV
1kV
High voltage
Luminance (nits)
6000
4000
2000
0
0
1
2
3
4
Vscreen=16kV
8kV
Current density (μA/cm²)
7Z04546.1


7Z11083
CIE co-ordinates
x = 0 200
y = 0.713
(%)
100
Relative response
50
0
450
550
λ (nm)
650

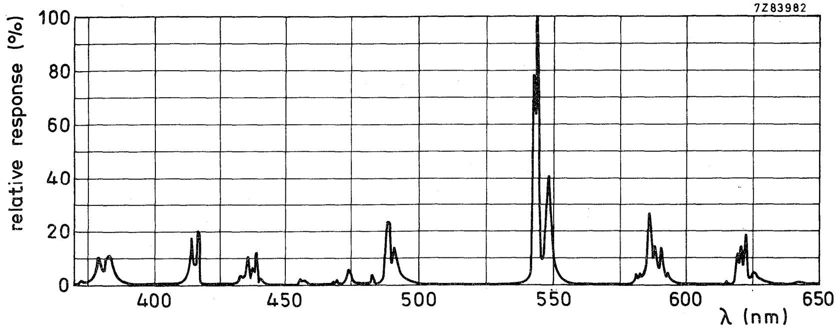

7Z11085
Relative luminance
10^2
10
1
10^{-1}
10^{-2}
10
10^2
10^3
10^4
10^5
10^6
10^7
Time after cessation of excitation (ms)
V_{screen}: 4 kV
I_{screen}: 5 µA/cm²
Measured with defocused spot
Excitation time sufficient for
complete build-up

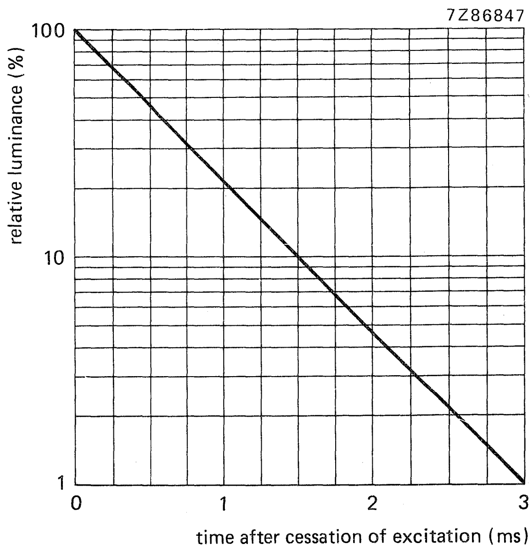

7Z11086
Luminance (nits)
300
200
100
0
1
2
3
V_{screen} =
5 kV
4 kV
3 kV
2 kV
1 kV
1500
1000
500
4
15 kV
12.5 kV
10 kV
7.5 kV
Current density (µA/cm²)


7Z11082
CIE co-ordinates
x = 0.297
y = 0.371
Relative response
(%)
100
50
0
300
500
700
λ (nm)

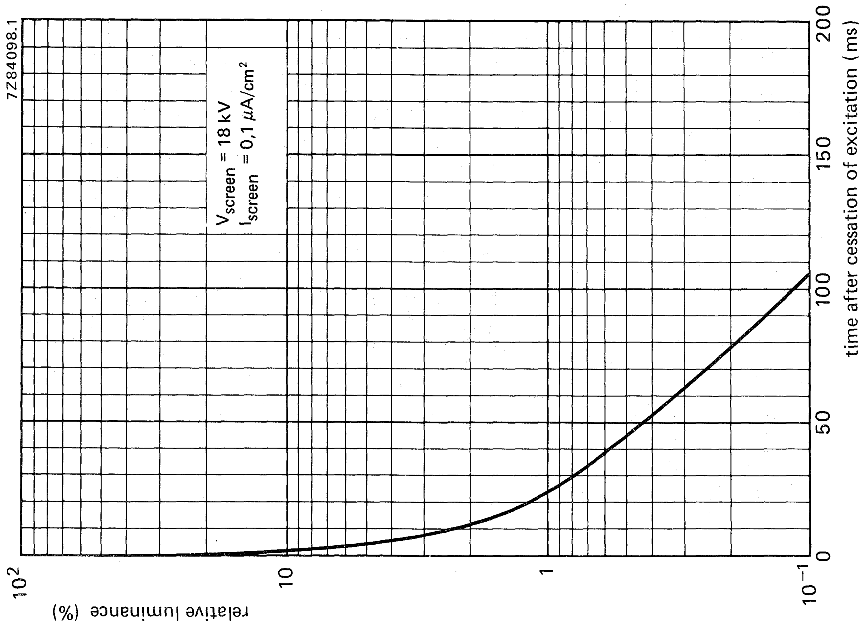

7Z86845
relative luminance (%)
100
10
1
0
0,5
1
time after cessation of excitation (μs)

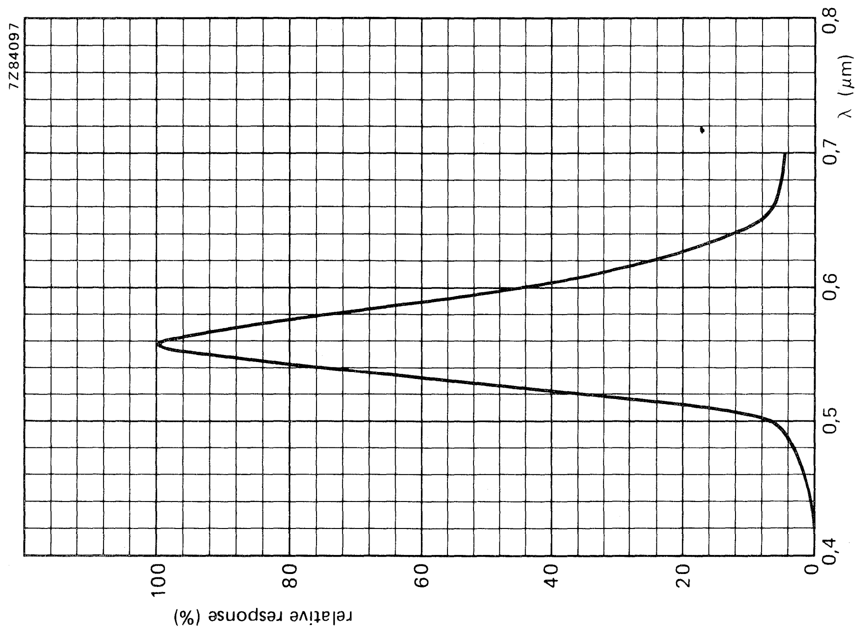
CIE co-ordinates x = 0,325 y = 0,512

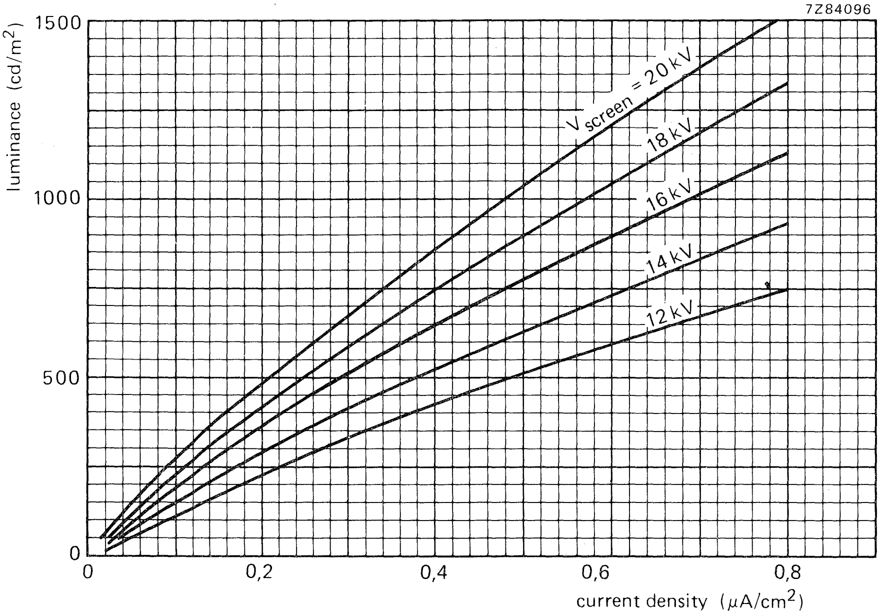


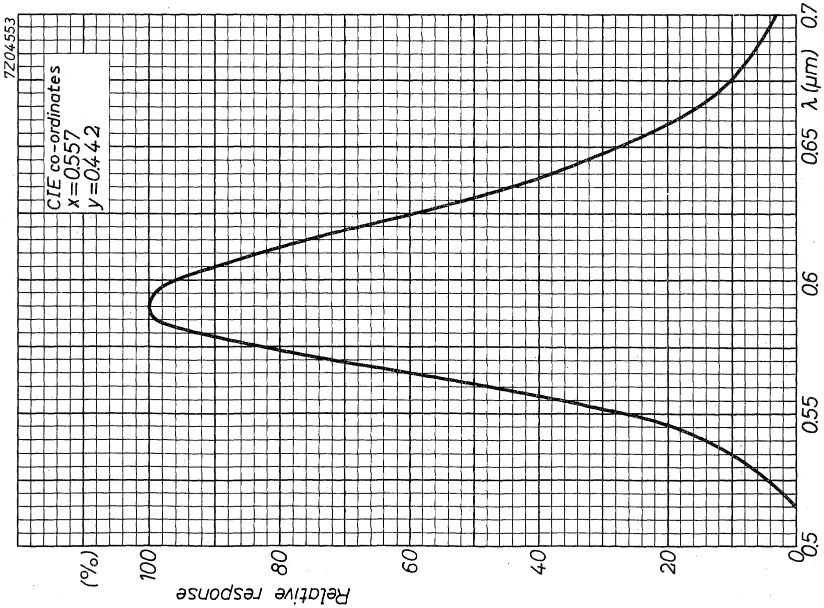


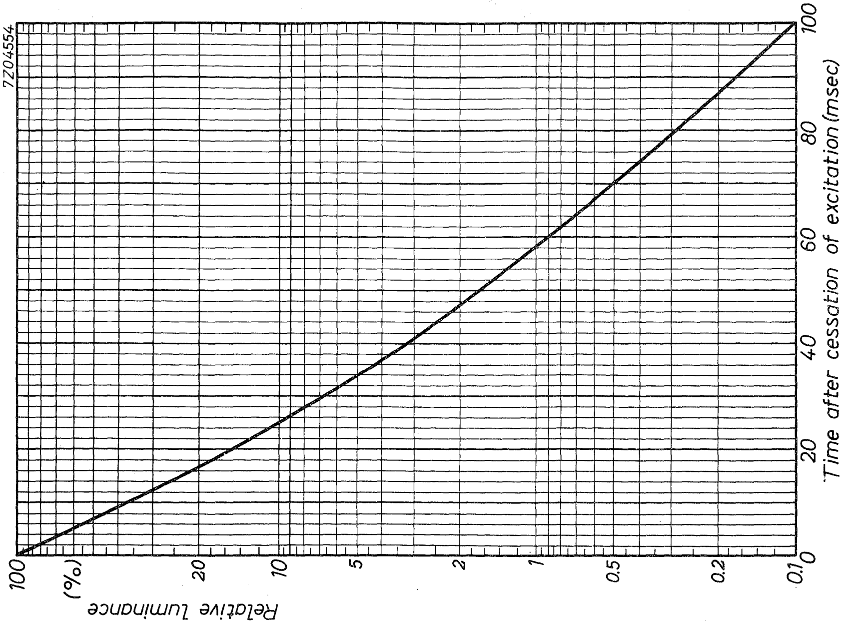
Screen voltage	4 kV
Screen current	20 μA
Pulse width	2 μs
Repetition time	10 ms

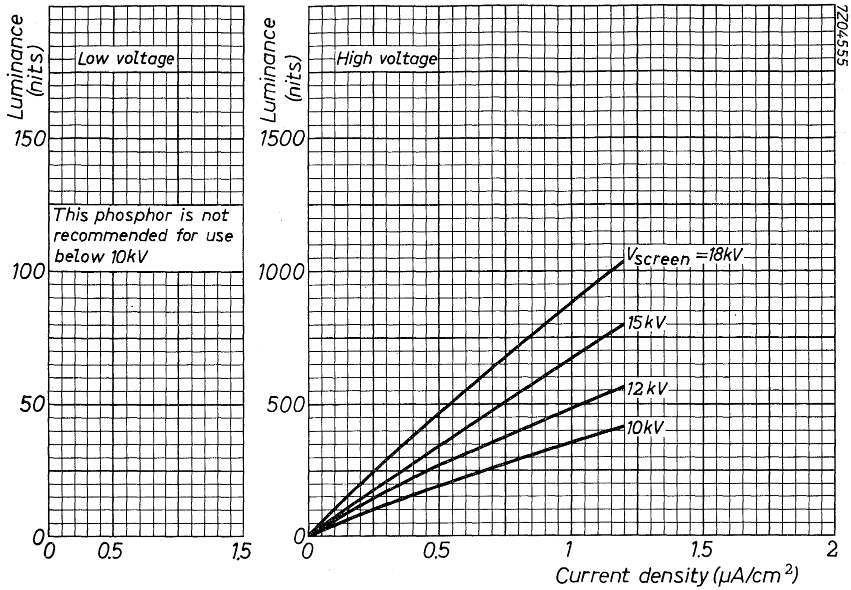

7Z84098.1
V_{screen} = 18 kV
I_{screen} = 0,1 μA/cm^2
relative luminance (%)
10^2
10
1
10^{-1}
0
50
100
150
200
time after cessation of excitation (ms)

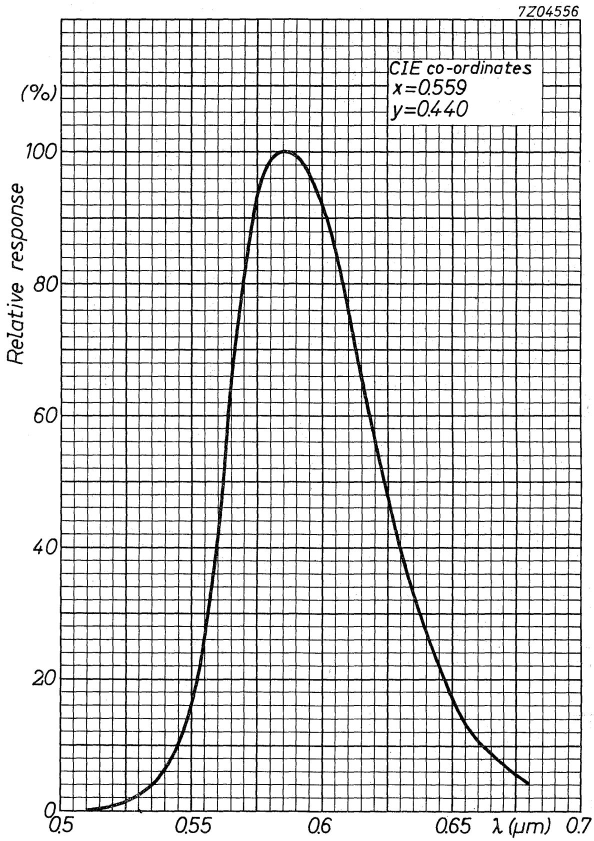

7Z84097
relative response (%)
100
80
60
40
20
0
0,4
0,5
0,6
0,7
0,8
λ (μm)

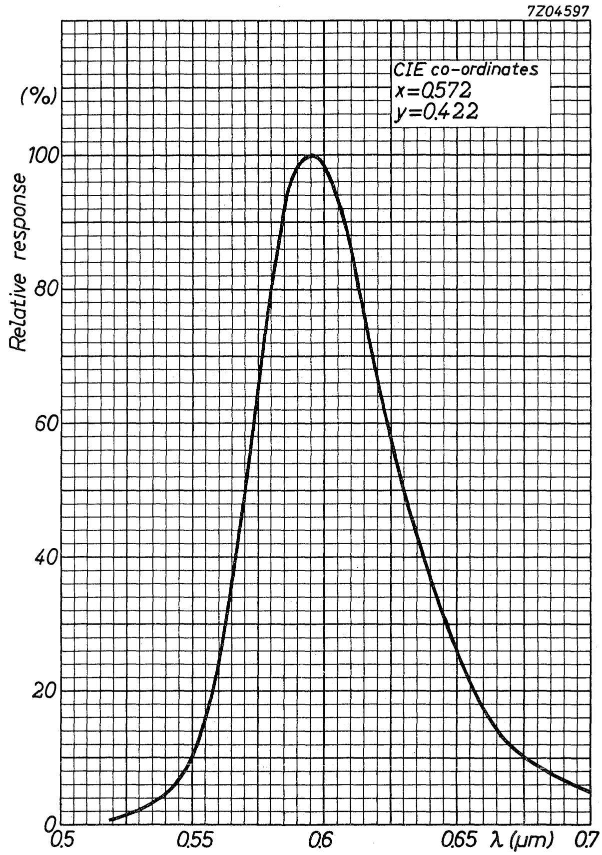

7Z84096
luminance (cd/m²)
1500
1000
500
0
V screen = 20 kV
18 kV
16 kV
14 kV
12 kV
0
0,2
0,4
0,6
0,8
current density (μA/cm²)

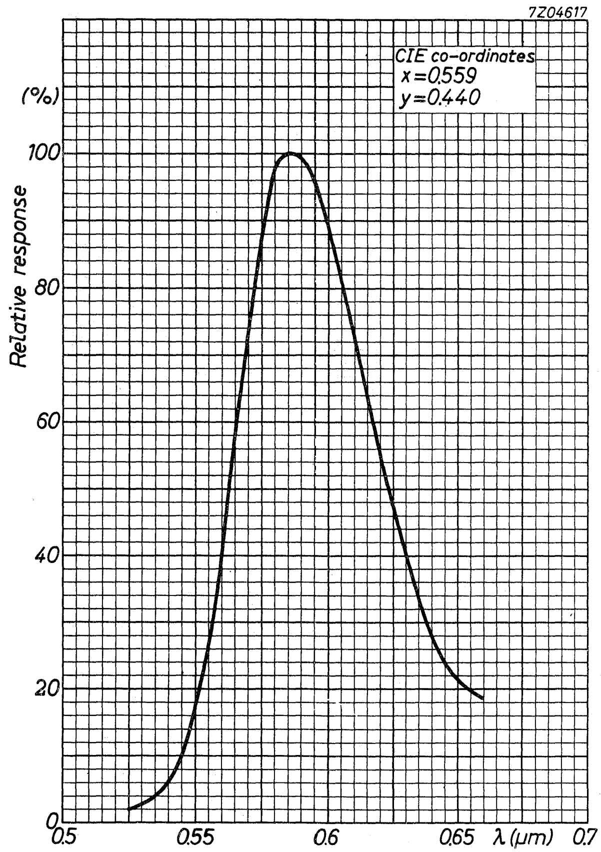

7Z04553
CIE co-ordinates
x=0.557
y=0.442
λ (μm)
0.5
0.55
0.6
0.65
0.7
Relative response
(%)
0
20
40
60
80
100

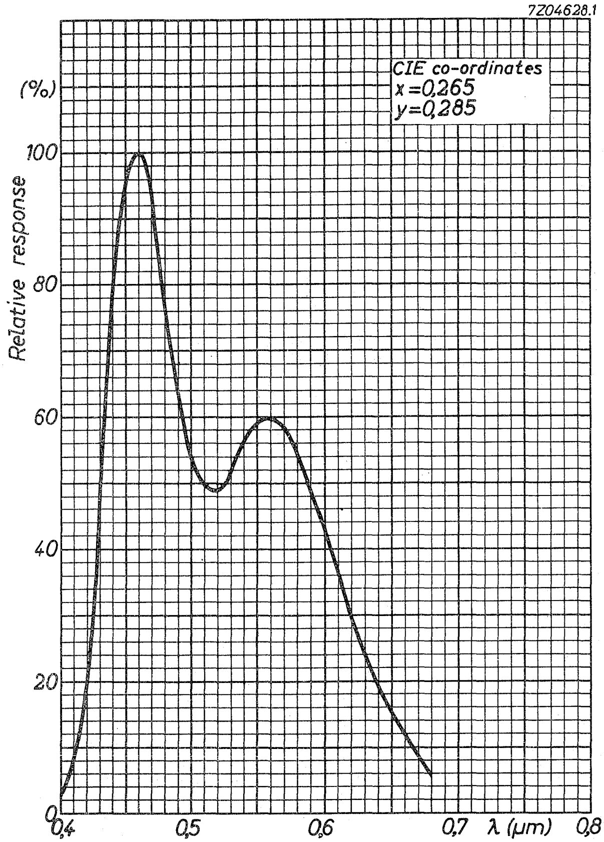

7Z04554
Time after cessation of excitation (msec)
0
20
40
60
80
100
Relative luminance
(%)
100
20
10
5
2
1
0.5
0.2
0.1

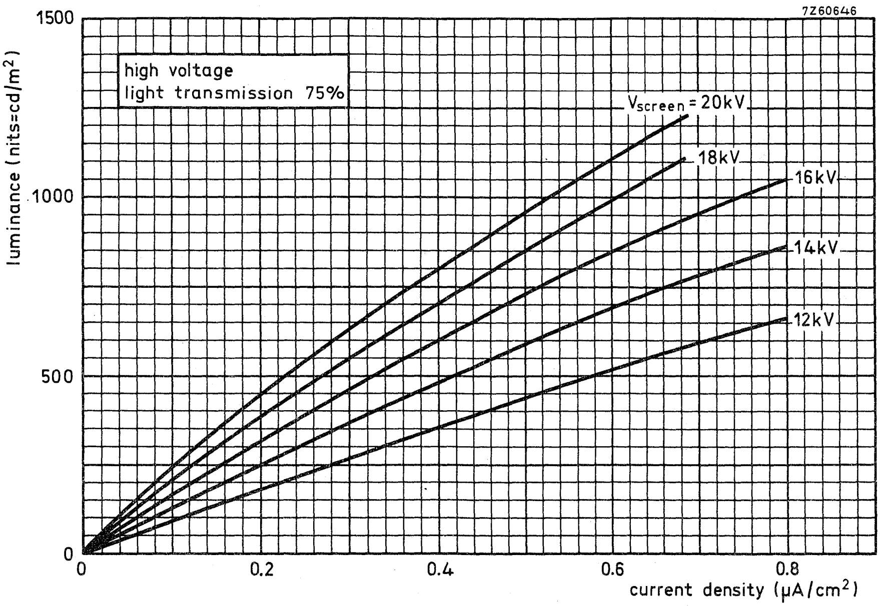

Luminance (nits)
Low voltage
This phosphor is not recommended for use below 10kV
150
100
50
0
0
0.5
1.5
Luminance (nits)
High voltage
7Z04555
1500
1000
500
0
0
0.5
1
1.5
2
Current density (μA/cm²)
Vscreen =18kV
15kV
12kV
10kV

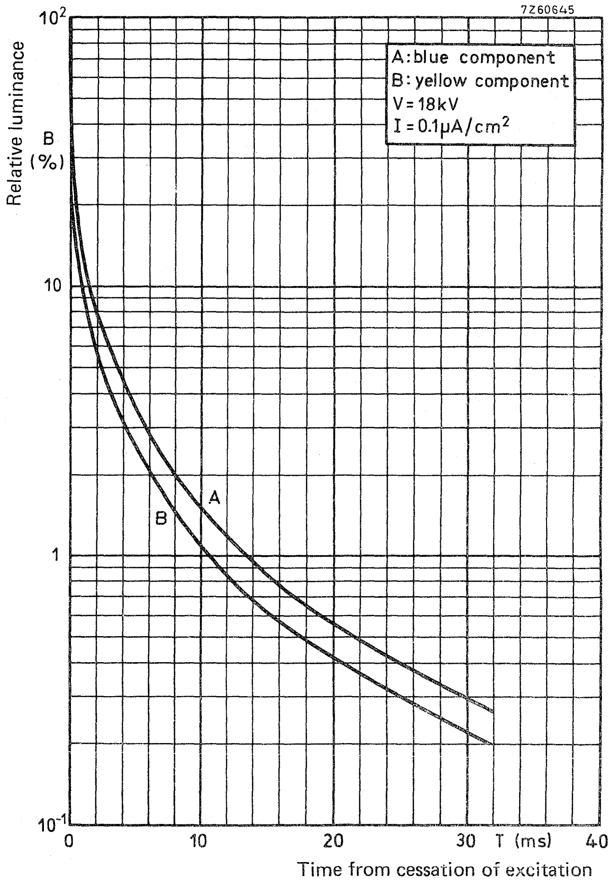

7Z04556
CIE co-ordinates
x=0.559
y=0.440
(%)
Relative response
100
80
60
40
20
0
0.5
0.55
0.6
0.65
λ (μm)
0.7

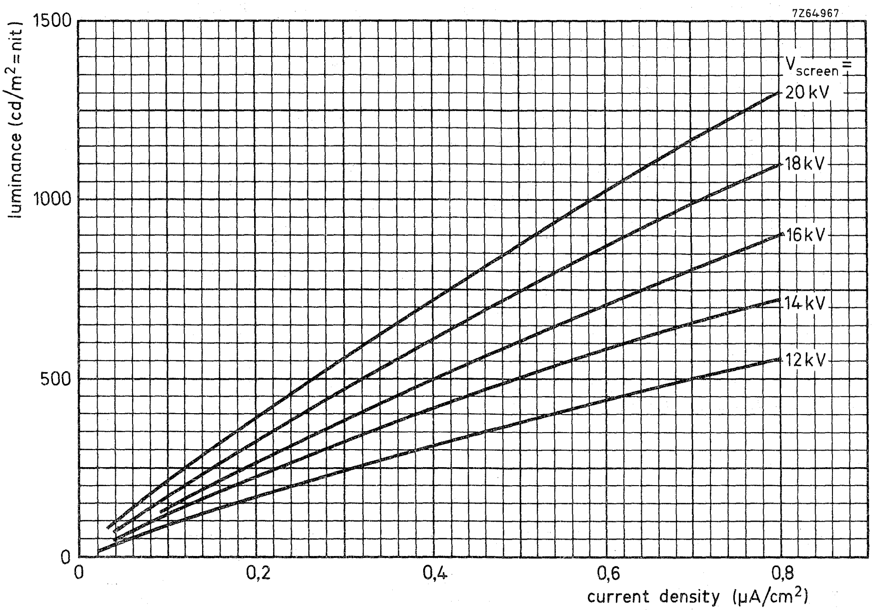

7Z04597
CIE co-ordinates
x=0.572
y=0.422
(%)
Relative response
100
80
60
40
20
0
0.5
0.55
0.6
0.65
λ (μm)
0.7

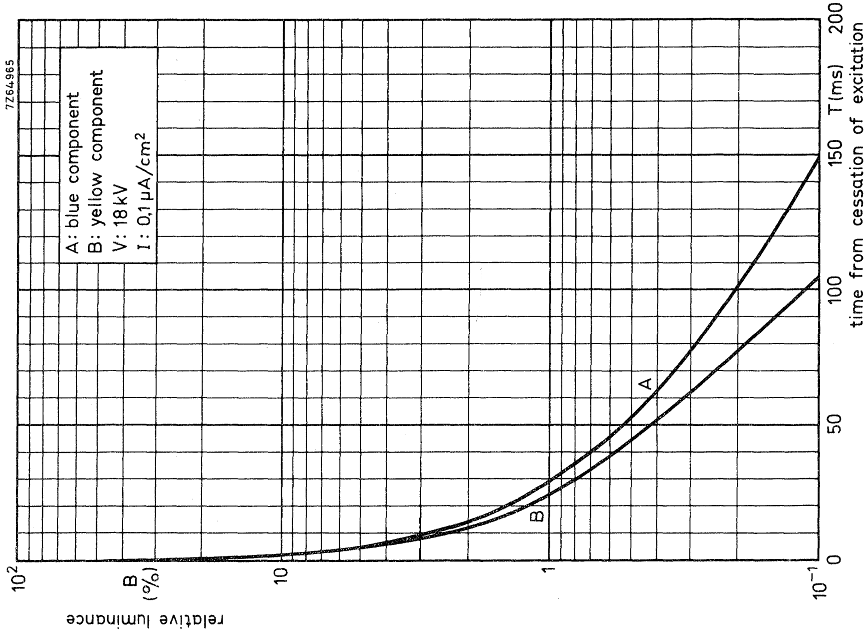

7Z04617
CIE co-ordinates
x=0.559
y=0.440
(%)
Relative response
100
80
60
40
20
0
0.5
0.55
0.6
0.65
λ (µm)
0.7

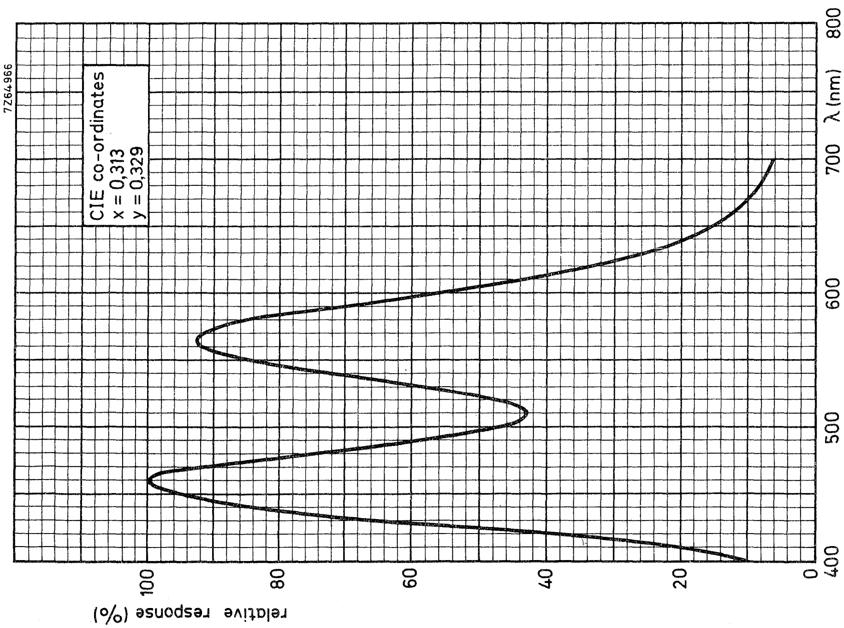

7Z04628.1
CIE co-ordinates
x = 0,265
y = 0,285
(%)
Relative response
100
80
60
40
20
0
0,4
0,5
0,6
0,7
λ (μm)
0,8


7Z60646
high voltage
light transmission 75%
V_{screen} = 20kV
18kV
16kV
14kV
12kV
luminance (nits=cd/m²)
1500
1000
500
0
0
0.2
0.4
0.6
0.8
current density (μA/cm²)

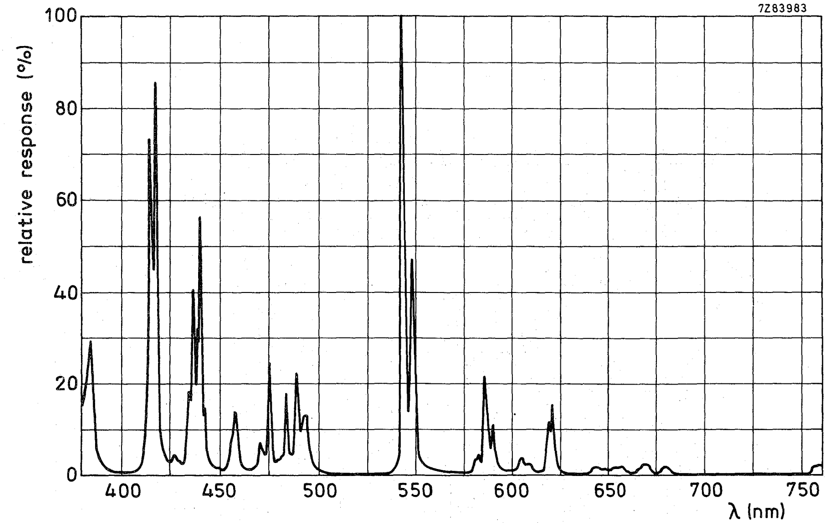

7Z60645
A: blue component
B: yellow component
V = 18kV
I = 0.1μA/cm²
Relative luminance
B
(%)
10²
10
1
10⁻¹
A
B
0
10
20
30
T (ms)
40
Time from cessation of excitation

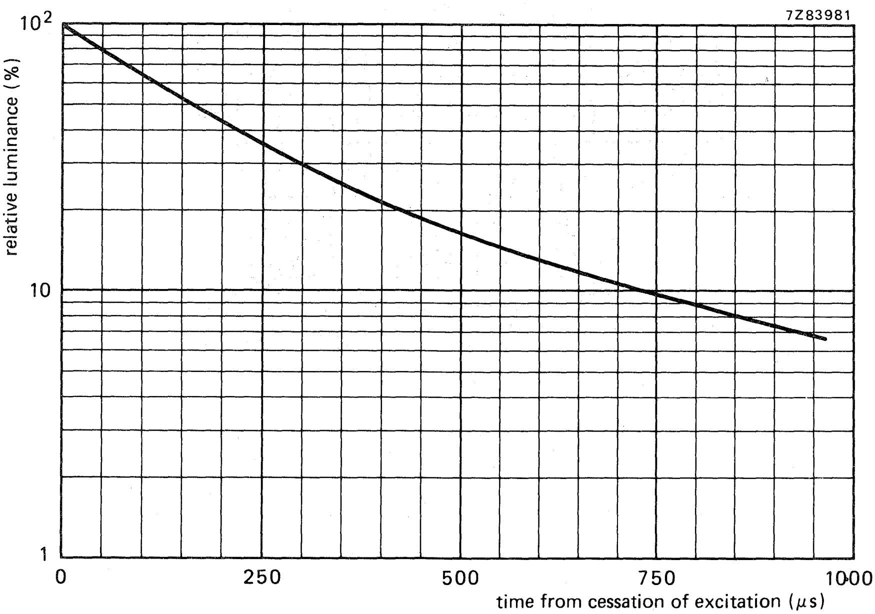

7Z64967
luminance (cd/m2=nit)
1500
1000
500
0
Vscreen =
20 kV
18 kV
16 kV
14 kV
12 kV
0
0,2
0,4
0,6
0,8
current density (μA/cm2)


7Z64965
A: blue component
B: yellow component
V: 18 kV
I: 0,1 μA/cm²
A
B
10^2
B (%)
10
1
10^{-1}
relative luminance
0
50
100
150
200
T (ms)
time from cessation of excitation

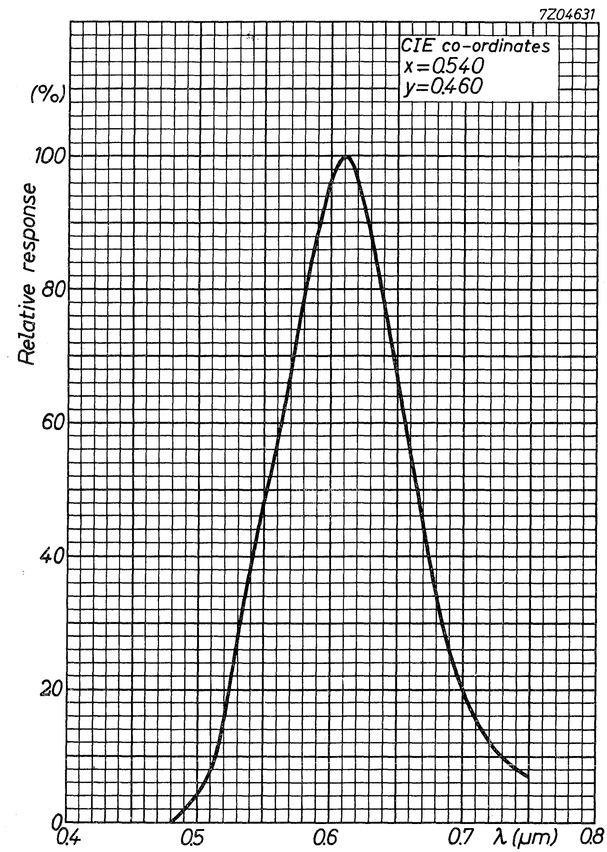

7Z64966
CIE co-ordinates
x = 0,313
y = 0,329
100
80
60
40
20
0
relative response (%)
400
500
600
700
800
λ (nm)

CIE co-ordinates x = 0,265 y = 0,285





Measured with defocused spot; pulse duration: 5 ms, V_{screen}: 5 kV, I_{screen} = 5 μA.


7Z04631
CIE co-ordinates
x=0.540
y=0.460
(%)
Relative response
100
80
60
40
20
0
0.4
0.5
0.6
0.7
λ (μm)
0.8

INSTRUMENT TUBES

SURVEY OF INSTRUMENT TUBES

	monoaccelerator tubes	post-deflection accelerator tubes	large bandwidth tubes	direct-view storage tubes
PREFERRED TYPES: recommended for new design				
	D7–221GH D7–222GH D10–180GY D10–181GY D14–360.. D14–360../93	D12–120GH/115 D14–120GH D14–121GH D14–261GH D14–262GH D14–292GH D14–302GH/93 D14–370GH/93* D14–380GH/93* E14–100GH		L14–131GH/55 L14–140GH/95 L14–150GH/95
MAINTENANCE TYPES: no longer recommended for equipment production				
	D7–190.. D7–191.. D10–160.. D10–161.. D13–480.. D13–481.. D14–251GH D14–252GH	D10–170.. D14–162GH/09 D18–120..	D13–500GH/01 D14–240GH/37	L14–111GH/55
OBSOLESCENT TYPES: available until present stocks are exhausted.				
	DG7–5 DG7–6 DG7–31 DG7–32 DH3–91	D . 7–11 D13–27.. E10/12.. E10–130..		

* Development types.

November 1982

INSTRUMENT CATHODE-RAY TUBE

7 cm diameter flat faced monoaccelerator oscilloscope tube primarily intended for use in inexpensive oscilloscopes and monitoring devices.

QUICK REFERENCE DATA			
Accelerator voltage	$V_{g2,g4,g5,\ell}$	1000	V
Display area		60 x 50	mm^2
Deflection coefficient, horizontal	M_x	29	V/cm
vertical	M_y	11.5	V/cm

SCREEN

	colour	persistence
D7-190GH	green	medium short
D7-190GM	yellowish green	long

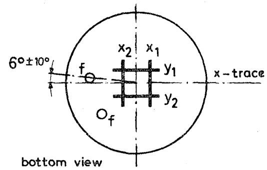
Useful screen diameter	min.	64	mm
Useful scan			
horizontal	min.	60	mm
vertical	min.	50	mm

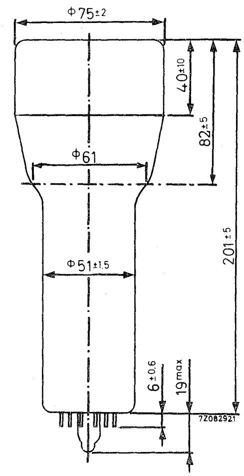
The useful scan may be shifted vertically to a maximum of 4mm with respect to the geometric centre of the faceplate.

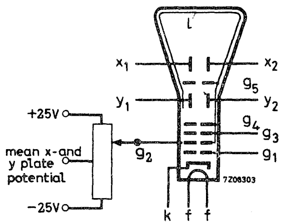
HEATING: Indirect by A.C. or D.C.; parallel supply

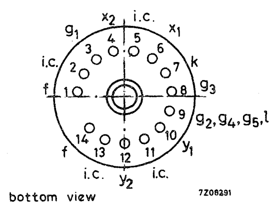
Heater voltage	V_f	6.3	V
Heater current	I_f	300	mA

MECHANICAL DATA (Dimensions in mm)









Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Dimensions and connections

See also outline drawing

Overall length	max.	225	mm
Face diameter	max.	77	mm

Base 14 pin all glass

Net weight	approx.	260	g

Accessories

Socket (supplied with tube)	type	55566
Mu-metal shield	type	55534

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	4	pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	4	pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	3.5	pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	3	pF
x_1 to x_2	C_{x1x2}	1.6	pF
y_1 to y_2	C_{y1y2}	1.1	pF
Control grid to all other elements	C_{g1}	5.5	pF
Cathode to all other elements	C_k	4.0	pF

FOCUSING electrostatic

DEFLECTION 3) double electrostatic

x plates symmetrical

y plates symmetrical

If use is made of the full deflection capabilities of the tube the deflection plates will intercept part of the electron beam, hence a low impedance deflection plate drive is desirable.

Angle between x and y traces $90 \pm 1^{\circ}$

LINE WIDTH 3)

Measured with the shrinking raster method in the centre of the screen under typical operating conditions, adjusted for optimum spot size at a beam current $I_\ell = 10\ \mu A$. 1)

Line width l.w. 0.28 mm

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1) As the construction of this tube does not permit a direct measurement of the beam current, this current should be determined as follows:
a) under typical operating conditions, apply a small raster display (no overscan), adjust V_{g1} for a beam current of approx. 10 μA and adjust V_{g3} and $V_{g2,g4,g5,\ell}$ for optimum spot quality at the centre of the screen.
b) under these conditions, but no raster, the deflection plate voltages should be changed to
$V_{y1} = V_{y2} = 1000$ V; $V_{x1} = 300$ V; $V_{x2} = 700$ V, thus directing the total beam current to x2.
Measure the current on x_2 and adjust V_{g1} for $I_{x2} = 10\,\mu A$ (being the beam current I_ℓ)
c) set again for the conditions under a), without touching the V_{g1} control. Now a raster display with a true 10 μA screen current is achieved.
d) focus optimally in the centre of the screen (do not adjust the astigmatism control) and measure the line width.

3) See page 4

TYPICAL OPERATING CONDITIONS 3)

Accelerator voltage	$V_{g2,g4,g5,\ell}$		1000	V
Astigmatism control voltage	$\Delta V_{g2,g4,g5,\ell}$		± 25	V 1)
Focusing electrode voltage	V_{g3}		100 to 180	V
Control grid voltage for visual extinction of focused spot	V_{g1}	max.	−35	V
Grid drive for 10 μA screen current		approx.	10	V
Deflection coefficient, horizontal	M_x		29	V/cm
		max.	31	V/cm
vertical	M_y		11,5	V/cm
		max.	12,5	V/cm
Deviation of linearity of deflection		max.	1	% 2)
Geometry distortion		see note 4		
Useful scan, horizontal		min.	60	mm
vertical		min.	50	mm

LIMITING VALUES (Absolute max. rating system)

Accelerator	$V_{g2,g4,g5,\ell}$	max.	2200	V
		min.	900	V
Focusing electrode voltage	V_{g3}	max.	2200	V
Control grid voltage, negative	$-V_{g1}$	max.	200	V
		min.	0	V
Cathode to heater voltage	V_{kf}	max.	125	V
	$-V_{kf}$	max.	125	V
Grid drive, average		max.	20	V
Screen dissipation	W_ℓ	max.	3	mW/cm^2
Control grid circuit resistance	R_{g1}	max.	1	MΩ

1) All that will be necessary when putting the tube into operation is to adjust the astigmatism control voltage once for optimum spot shape in the screen centre. The control voltage will always be in the range stated, provided the mean x plate and certainly the mean y plate potential was made equal to $V_{g2,g4,g5,\ell}$ with zero astigmatism correction.
2) The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.
3) The mean x and certainly the mean y plate potential should be equal to $V_{g2,g4,g5,\ell}$ with astigmatism adjustment set to zero.
4) A graticule, consisting of concentric rectangles of 40 mm x 50 mm and 39,2 mm x 49 mm is aligned with the electrical x-axis of the tube. The edges of a raster will fall between these rectangles.

INSTRUMENT CATHODE-RAY TUBE

7 cm diameter flat-faced monoaccelerator oscilloscope tube with low heater consumption.

QUICK REFERENCE DATA

Accelerator voltage	$V_{g2, g4, g5 (\ell)}$	1000	V
Display area		60 x 50	mm^2
Deflection coefficient			
horizontal	M_x	29	V/cm
vertical	M_y	11,5	V/cm

The D7—191 is equivalent to the type D7—190.. except for the following.

HEATING

Indirect by a.c. or d.c.; parallel supply.

Heater voltage	V_f	6,3	V
Heater current	I_f	95	mA

LIMITING VALUES (Absolute maximum rating system)

Cathode to heater voltage				
positive	$V_{k/f}$	max.	100	V
negative	$-V_{k/f}$	max.	15	V

CAPACITANCES

Cathode to all other elements	C_k	2,3	pF

INSTRUMENT CATHODE-RAY TUBE

7 cm diagonal, rectangular flat faced mono accelerator oscilloscope tube primarily for use in inexpensive oscilloscopes and monitors. This tube features a low heater power consumption.

QUICK REFERENCE DATA

Accelerator voltage	$V_{g2,\ g4,\ g5(\ell)}$	1000	V
Display area		60 mm x 36	mm
Deflection coefficient			
horizontal	M_x	12,5	V/cm
vertical	M_y	20	V/cm

The D7–221GH is equivalent to the type D7–222GH except for the following.

HEATING

Indirect by a.c. or d.c. *

Heater voltage	V_f	6,3	V
Heater current	I_f	95	mA

LIMITING VALUES (Absolute maximum rating system)

Cathode to heater voltage				
positive	V_{kf}	max.	100	V
negative	$-V_{kf}$	max.	15	V

CAPACITANCES

Cathode to all other elements	C_k	3,7	pF

* Not to be connected in series with other tubes.

INSTRUMENT CATHODE-RAY TUBE

7 cm diagonal, rectangular flat faced mono accelerator oscilloscope tube primarily for use in inexpensive oscilloscopes and monitors. This tube features a 1,5 W cathode with short warm-up time (quick-heating cathode).

QUICK REFERENCE DATA

Accelerator voltage	$V_{g2, g4, g5 (\ell)}$	1000 V
Display area		60 mm x 36 mm
Deflection coefficient		
horizontal	M_x	12,5 V/cm
vertical	M_y	20 V/cm

OPTICAL DATA

Screen		
phosphor type		GH, colour green
persistence		medium short
Useful screen dimensions		⩾ 60 mm x 36 mm
Useful scan		
horizontal	⩾	60 mm
vertical	⩾	36 mm
Spot eccentricity in horizontal and vertical directions	<	5 mm

HEATING

Indirect by a.c. or d.c. *

Heater voltage	V_f	6,3 V
Heater current	I_f	240 mA

MECHANICAL DATA

Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Net mass approx. 350 g

Base 12-pin all glass; JEDEC B12–246

* Not to be connected in series with other tubes.

Dimensions and connections

See also outline drawing		
Overall length	⩽	225 mm
Faceplate dimensions	⩽	72,5 x 49 mm

Accessories

→ Socket, supplied with tube	type 55589/55594
Mu-metal shield	type 55535

FOCUSING	electrostatic

DEFLECTION	double electrostatic
x-plates	symmetrical
y-plates	symmetrical
Angle between x and y-traces	$90 \pm 1^{\circ}$
Angle between x-trace and horizontal axis of the face	$\leqslant 3^{\circ}$ *

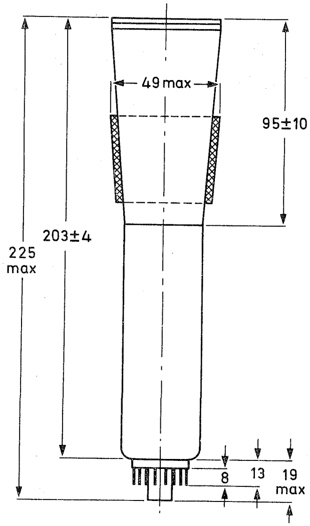
If use is made of the full deflection capabilities of the tube the deflection plates will block part of the electron beam, hence a low impedance deflection plate drive is desirable.

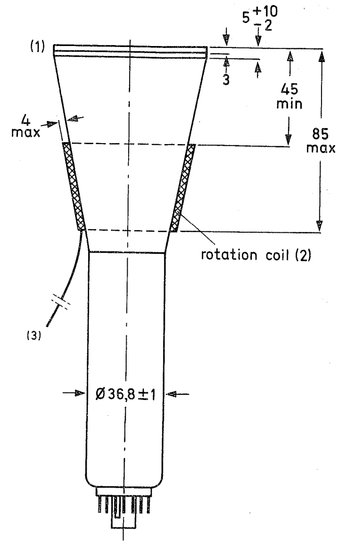
CAPACITANCES

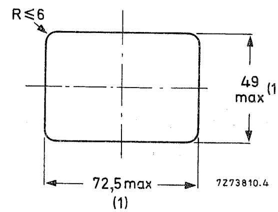
x_1 to all other elements except x_2	$C_{x1(x2)}$	4,0 pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	4,1 pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	4,2 pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	5,4 pF
x_1 to x_2	C_{x1x2}	1,6 pF
y_1 to y_2	C_{y1y2}	1,8 pF
Control grid to all other elements	C_{g1}	7,0 pF
Cathode to all other elements	C_k	4,2 pF

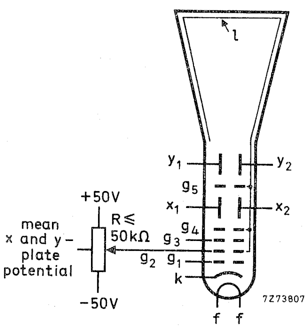
* The tube is provided with a rotation coil, concentrically wound around the tube neck, enabling the alignment of the x-trace with the mechanical x-axis of the screen. The coil has 1000 turns and a maximum resistance of 250 Ω. Under typical operating conditions, a maximum of 10 ampere-turns are required for the maximum rotation of 3°. This means the required current is 10 mA maximum at a required voltage of 2,5 V maximum.

DIMENSIONS AND CONNECTIONS

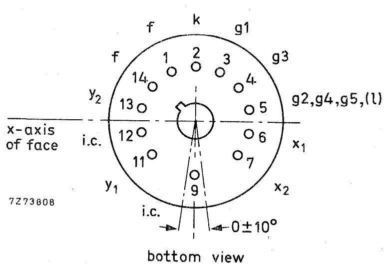


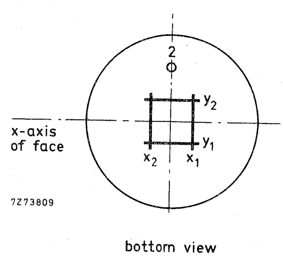






(1) The bulge at the frit seal does not exceed the maximum dimensions.
(2) The coil is fixed to the envelope by means of adhesive tape.
(3) The length of the connecting leads of the rotation coil is min. 350 mm.





TYPICAL OPERATION

Conditions (note 1)

Accelerator voltage	$V_{g2,\,g4,\,g5(\ell)}$		1000 V	
Astigmatism control voltage	$\Delta V_{g2,\,g4,\,g5(\ell)}$		±50 V	(note 2)
Focusing electrode voltage	V_{g3}		100 to 180 V	
Cut-off voltage for visual extinction of focused spot	$-V_{g1}$		11 to 35 V	

Performance

Useful scan				
horizontal		>	60 mm	
vertical		>	36 mm	
Deflection coefficient				
horizontal	M_x		12,5 V/cm	
		<	13,8 V/cm	
vertical	M_y		20 V/cm	
		<	22 V/cm	
Line width	l.w.		0,28 mm	(note 3)
Deviation of linearity of deflection		<	2 %	(note 4)
Grid drive for 10 μA screen current	V_d	≈	10 V	
Geometry distortion	see note 5			

NOTES

1. The mean x-plate potential and the mean y-plate potential should be equal to $V_{g2,\,g4,\,g5(\ell)}$ (with astigmatism control voltage set to zero).
2. When putting the tube into operation the astigmatism control voltage should be adjusted only once for optimum spot size in the centre of the screen. The control voltage will be within the stated range, provided the conditions of note 1 are adhered to.
3. Measured with the shrinking raster method in the centre of the screen under typical operating conditions, adjusted for optimum spot size at a beam current I_ℓ = 10 μA.

   As the construction of the tube does not permit a direct measurement of the beam current, this current should be determined as follows.
   a) Under typical operating conditions, apply a small raster display (no overscan), adjust V_{g1} for a beam current of approx. 10 μA and adjust V_{g3} and $V_{g2,\,g4,\,g5(\ell)}$ for optimum spot quality at the centre of the screen.
   b) Under these conditions, but without raster, the deflection plate voltages should be changed to: $V_{x1} = V_{x2}$ = 1000 V; V_{y1} = 300 V; V_{y2} = 700 V, thus directing the total beam current to y_2. Measure the current on y_2 and adjust V_{g1} for I_{y2} = 10 μA.
   c) Set again for the conditions under a), without touching the V_{g1} control. The screen current of the resulting raster display is now 10 μA.
   d) Focus optimally in the centre of the screen (do not adjust the astigmatism control) and measure the line width.
4. The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.
5. A graticule, consisting of concentric rectangles of 57,0 mm x 33,0 mm and 56 mm x 31,6 mm is aligned with the electrical x-axis of the tube. The edges of a raster will fall between these rectangles.

LIMITING VALUES (Absolute maximum rating system)

Accelerator voltage	$V_{g2, g4, g5(\ell)}$	max.	2200	V
Focusing electrode voltage	V_{g3}	max.	2200	V
Control grid voltage	$-V_{g1}$	max.	200	V
		min.	0	V
Cathode to heater voltage				
positive	V_{kf}	max.	125	V
negative	$-V_{kf}$	max.	125	V
Grid drive, averaged over 1 ms	V_d	max.	20	V
Screen dissipation	W_{ℓ}	max.	3	mW/cm^2
Control grid circuit resistance	R_{g1}	max.	1	MΩ

INSTRUMENT CATHODE-RAY TUBE

10 cm diameter flat faced monoaccelerator oscilloscope tube primarily intended for use in inexpensive oscilloscopes and read-out devices.

QUICK REFERENCE DATA			
Accelerator voltage	$V_{g_2,g_4,g_5(\ell)}$	1500	V
Display area		80 x 60	mm^2
Deflection coefficient, horizontal	M_x	32	V/cm
vertical	M_y	13.7	V/cm

SCREEN

	colour	persistence
D10-160GH	green	medium short
D10-160GM	yellowish green	long

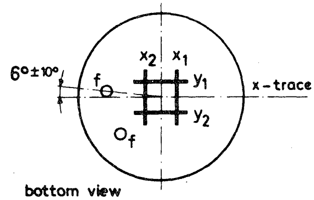
Useful screen diameter	min.	85	mm
Useful scan			
horizontal	min.	80	mm
vertical	min.	60	mm

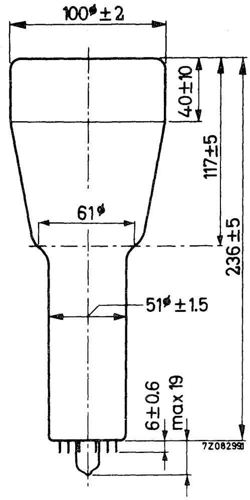
The useful scan may be shifted vertically to a max. of 5 mm with respect to the geometric centre of the faceplate.

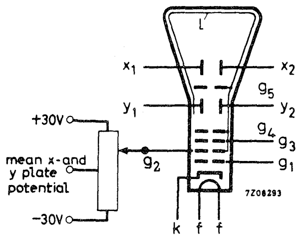
HEATING: Indirect by A.C. or D.C.; parallel supply

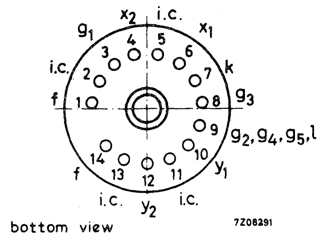
Heater voltage	V_f	6.3	V
Heater current	I_f	300	mA

MECHANICAL DATA (Dimensions in mm)









Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Dimensions and connections

See also outline drawing

Overall length	max.	260	mm
Face diameter	max.	102	mm

Base 14 pin all glass

Net weight approx. 400 g

Accessories

Socket (supplied with tube)	type	55566
Mu metal shield	type	55547

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	4	pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	4	pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	3.5	pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	3	pF
x_1 to x_2	C_{x1x2}	1.6	pF
y_1 to y_2	C_{y1y2}	1.1	pF
Control grid to all other elements	C_{g1}	5.5	pF
Cathode to all other elements	C_k	4	pF

FOCUSING electrostatic

DEFLECTION 3) double electrostatic

x plates symmetrical

y plates symmetrical

If use is made of the full deflection capabilities of the tube the deflection plates will intercept part of the electron beam, hence a low impedance deflection plate drive is desirable.

Angle between x and y traces 90 ± 1^{o}

LINE WIDTH

Measured with the shrinking raster method in the centre of the screen under typical operating conditions, adjusted for optimum spot size at a beam current $I_\ell = 10\ \mu A$. 1)

Line width	l.w.	0.27	mm

[1]) As the construction of this tube does not permit a direct measurement of the beam current, this current should be determined as follows:
a) under typical operating conditions, apply a small raster display (no overscan), adjust V_{g1} for a beam current of approx. 10 μA and adjust V_{g3} and $V_{g2,g4,g5,\ell}$ for optimum spot quality at the centre of the screen.
b) under these conditions, but no raster, the deflection plate voltages should be changed to
$V_{y1} = V_{y2} = 1500$ V; $V_{x1} = 800$ V; $V_{x2} = 1200$ V, thus directing the total beam current to x2.
Measure the current on x_2 and adjust V_{g1} for $I_{x2} = 10\ \mu A$ (being the beam current I_ℓ)
c) set again for the conditions under a), without touching the V_{g1} control. Now a raster display with a true 10 μA screen current is achieved.
d) focus optimally in the centre of the screen (do not adjust the astigmatism control) and measure the line width.

[3]) See page 4

TYPICAL OPERATING CONDITIONS [3]

Accelerator voltage	$V_{g2,g4,g5,\ell}$	1500	V
Astigmatism control voltage	$\Delta V_{g2,g4,g5,\ell}$	± 30	V [1]
Focusing electrode voltage	V_{g3}	140 to 275	V
Control grid voltage for visual extinction of focused spot	V_{g1}	max. −50	V
Grid drive for 10 μA screen current		approx. 10	V
Deflection coefficient, horizontal	M_x	32 max. 34	V/cm V/cm
vertical	M_y	13.7 max. 14.5	V/cm V/cm
Deviation of linearity of deflection		max. 1	% [2]
Geometry distortion		see note 4	
Useful scan, horizontal		min. 80	mm
vertical		min. 60	mm

LIMITING VALUES (Absolute max. rating system)

Accelerator voltage	$V_{g2,g4,g5,\ell}$	max. 2200 min. 1350	V V
Focusing electrode voltage	V_{g3}	max. 2200	V
Control grid voltage, negative	$-V_{g1}$	max. 200 min. 0	V V
Cathode to heater voltage	V_{kf} $-V_{kf}$	max. 125 max. 125	V V
Grid drive, average		max. 20	V
Screen dissipation	W_ℓ	max. 3	mW/cm^2
Control grid circuit resistance	R_{g1}	**max. 1**	MΩ

[1] All that will be necessary when putting the tube into operation is to adjust the astigmatismcontrol voltage once for optimum spot shape in the screen centre. The control voltage will always be in the range stated, provided the mean x plate and centainly the mean y plate potential was made equal to $V_{g2,g4,g5,\ell}$ with zero astigmatism correction.

[2] The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.

[3] The mean x and certainly the mean y plate potentials should be equal to $V_{g2,g4,g5,\ell}$ with astigmatism adjustment set to zero.

[4] A graticule, consisting of concentric rectangles of 50 mm x 60 mm and 49 mm x 58.6 mm is aligned with the electrical x-axis of the tube. The edges of a raster will fall between these rectangles.

INSTRUMENT CATHODE-RAY TUBE

10 cm diameter flat-faced monoaccelerator oscilloscope tube with low heater consumption.

QUICK REFERENCE DATA

Accelerator voltage	$V_{g2, g4, g5\,(\ell)}$	1500	V
Display area		80 x 60	mm^2
Deflection coefficient			
horizontal	M_x	32	V/cm
vertical	M_y	13,7	V/cm

The D10—161.. is equivalent to the type D10—160.. except for the following.

HEATING

Indirect by a.c. or d.c.; parallel supply

Heater voltage	V_f	6,3	V
Heater current	I_f	95	mA

LIMITING VALUES (Absolute maximum rating system)

Cathode to heater voltage				
positive	$V_{+k/f-}$	max.	100	V
negative	$V_{-k/f+}$	max.	15	V

CAPACITANCES

Cathode to all other elements	C_k	2,3	pF

INSTRUMENT CATHODE-RAY TUBE

10 cm diameter flat faced oscilloscope tube with mesh, designed for compact, transistorized oscilloscopes of 10 MHz to 30 MHz bandwidth.

QUICK REFERENCE DATA			
Final accelerator voltage	$V_{g7(\ell)}$	6	kV
Display area		80 x 60	mm^2
Deflection coefficient, horizontal	M_x	13	V/cm
vertical	M_y	3,5	V/cm

SCREEN

	colour	persistence
D10-170GH	green	medium short

Useful screen diameter	min.	85	mm
Useful scan at $V_{g7(\ell)}/V_{g2,\ g4} = 6$			
horizontal	min.	80	mm
vertical	min.	60	mm

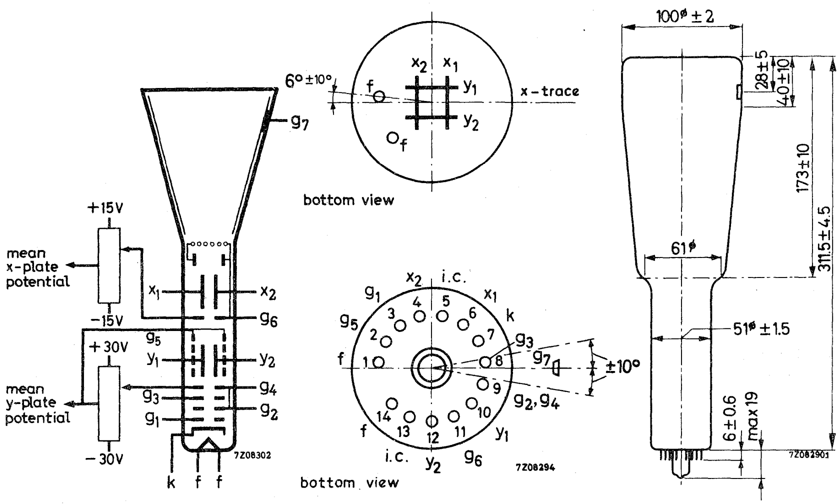
The useful scan may be found shifted vertically to a max. of 5 mm with respect to the geometric centre of the faceplate.

HEATING: Indirect by a.c. or d.c.; parallel supply

Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

MECHANICAL DATA

Dimensions in mm



Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Dimensions and connections

See also outline drawing

Overall length (socket included)	max.	335	mm
Face diameter	max.	102	mm

Net weight	approx.	500	g

Base 14 pin all glass

Accessories

Socket (supplied with tube)	type	55566
Final accelerator contact connector	type	55563A
Mu-metal shield	type	55548

CAPACITANCES

x_1 to all other elements except x_2	$C_{x_1(x_2)}$	7	pF
x_2 to all other elements except x_1	$C_{x_2(x_1)}$	7	pF
y_1 to all other elements except y_2	$C_{y_1(y_2)}$	5	pF
y_2 to all other elements except y_1	$C_{y_2(y_1)}$	5	pF
x_1 to x_2	$C_{x_1x_2}$	2.5	pF
y_1 to y_2	$C_{y_1y_2}$	1.5	pF
Control grid to all other elements	C_{g_1}	[illegible]	[illegible]
Cathode to all other elements	C_k	[illegible]	[illegible]

FOCUSING electrostatic

DEFLECTION double electrostatic

x plates	symmetrical
y plates	symmetrical

If use is made of the full deflection capabilities of the tube the deflection plates will intercept part of the electron beam; hence a low impedance deflection plate drive is desirable.

Angle between x and y traces $90 \pm 1^{\circ}$

LINE WIDTH

Measured with the shrinking raster method over the whole screen area under typical operating conditions, adjusted for optimum spot size at a beam current $I_{\ell} = 10\ \mu A$.

Line width	l.w.	0.42	mm

TYPICAL OPERATING CONDITIONS

Final accelerator voltage	$V_{g_7(\ell)}$	6000	V
Interplate shield voltage	V_{g_6}	1000	V
Geometry control voltage	ΔV_{g_6}	± 15	V [1]
Deflection plate shield voltage	V_{g_5}	1000	V [2]
Focusing electrode voltage	V_{g_3}	170 to 230	V
First accelerator voltage	V_{g_2,g_4}	1000	V
Astigmatism control voltage	$\Delta V_{g_2,g_4}$	± 30	V [3]
Control grid voltage for visual extinction of focused spot	V_{g_1}	-16 to -40	V
Deflection coefficient, horizontal	M_x	av. 13 max. 14	V/cm
vertical	M_y	av. 3.5 max. 3.8	V/cm
Deviation of linearity of deflection		max. 2	% [4]
Geometry distortion		see note 5	
Useful scan, horizontal		min. 80	mm
vertical		min. 60	mm

LIMITING VALUES (Absolute maximum rating system)

Final accelerator voltage	$V_{g_7(\ell)}$	max. 6600 min. 4000	V V
Interplate shield voltage and geometry control electrode voltage	V_{g_6}	max. 2200	V
Deflection plate shield voltage	V_{g_5}	max. 2200	V
Focusing electrode voltage	V_{g_3}	max. 2200	V
First accelerator and astigmatism control electrode voltage	V_{g_2,g_4}	max. 2200 min. 900	V V
Control grid voltage, negative	$-V_{g_1}$	max. 200 min. 0	V V
Cathode to heater voltage	V_{kf} $-V_{kf}$	max. 125 max. 125	V V
Voltage between astigmatism control electrode and any deflection plate	$V_{g_4/x}$ $V_{g_4/y}$	max. 500 max. 500	V V
Grid drive, average		max. 20	V
Screen dissipation	W_ℓ	max. 3	mW/cm^2
Ratio $V_{g_7(\ell)}/V_{g_2,g_4}$	$V_{g_7(\ell)}/V_{g_2,g_4}$	max. 6	
Control grid circuit resistance	R_{g1}	**max. 1**	MΩ

For notes see page 5.

Notes

1) This tube is designed for optimum performance when operating at a ratio $V_{g_7}/V_{g_2,g_4} = 6$.
The geometry electrode voltage should be adjusted within the indicated range (values with respect to the mean x-plate potential). A negative control voltage will cause some pincushion distortion and less background light, a positive control voltage will give some barrel distortion and a slight increase of background light.

2) The deflection plate shield voltage should be equal to the mean y-plate potential. The mean x- and y-plate potentials should be equal for optimum spot quality.

3) The astigmatism control electrode voltage should be adjusted for optimum spot shape. For any necessary adjustment its potential will be within the stated range.

4) The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.

5) A graticule, consisting of concentric rectangles of 60 mm x 60 mm and 58.6 mm x 58.6 mm, is aligned with the electrical x-axis of the tube.
With optimum correction potentials applied the edges of a raster lie between these rectangles.

INSTRUMENT CATHODE-RAY TUBE

- mono accelerator
- 10 cm diagonal rectangular flat face
- dynamic deflection defocusing correction
- internal magnetic correction for astigmatism and vertical eccentricity
- quick-heating cathode
- for portable oscilloscopes with up to 25 MHz bandwidth, and read-out devices

QUICK REFERENCE DATA

Accelerator voltage	$V_{g2(\ell)}$	2000	V
Minimum useful scan area		70 x 56	mm
Deflection coefficient			
horizontal	M_x	36	V/cm
vertical	M_y	23	V/cm

OPTICAL DATA

Screen				
type	GY, colour green			
persistence	medium short			
Useful screen area	$\geqslant$	70 x 56	mm	
Useful scan area	$\geqslant$	70 x 56	mm	
Spot eccentricity				
in horizontal direction	$\leqslant$	6	mm	
in vertical direction	$\leqslant$	3	mm	note 2, page 7

HEATING

Indirect by a.c. or d.c.*			
Heater voltage	V_f	6,3	V
Heater current	I_f	240	mA
Heating time to attain 10% of the cathode current at equilibrium conditions	approx.	5	s

* Not to be connected in series with other tubes.

MECHANICAL DATA

Dimensions and connections (see also outline drawing)

Overall length (socket included)	≤ 240 mm
→ Faceplate dimensions	82 ± 1 mm x 69 ± 1 mm
Net mass	approx. 450 g
Base	12 pin, all glass, JEDEC B12-246

Mounting

The tube can be mounted in any position. It must not be supported by the base alone or near the base region and under no circumstances should the socket be allowed to support the tube.

→ **Accessories**

Socket with solder tags	type 55589/55594
Socket with printed-wiring pins	type 55595

FOCUSING	electrostatic
DEFLECTION	double electrostatic
x-plates	symmetrical
y-plates	symmetrical

If use is made of the full deflection capabilities of the tube the deflection plates will block part of the electron beam, hence a low impedance deflection plate drive is desirable.

DYNAMIC DEFLECTION DEFOCUSING CORRECTION

The tube has a special electrode, positioned between the x and y-plates, for dynamic correction of deflection defocusing, to improve the uniformity of the extremely good line width up to the screen edges. If use is made of this dynamic correction, a negative voltage proportional to, and approx. 50% of, the negative horizontal deflection plate voltage should be applied to this electrode (grid 6).
The correction-circuit impedance must be $\leqslant$ 100 kΩ. To prevent distortion, the output impedances of the x-amplifiers should be $\leqslant$ 10 kΩ.
If no correction is required, grid 6 should be connected to mean x-plate potential ($V_{g2(\ell)}$).

Angle between x and y-traces	90 ± 1^o
Angle between x-trace and x-axis of the face plate	$\leqslant 5^o$*

CAPACITANCES (approx. values)

x_1 to all other elements except x_2	$C_{x1(x2)}$	4,5 pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	4,5 pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	3,5 pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	3,5 pF
x_1 to x_2	C_{x1x2}	2 pF
y_1 to y_2	C_{y1y2}	1 pF
Control grid to all other elements	C_{g1}	6 pF
Cathode to all other elements	C_k	2,7 pF

* The tube has a trace rotation coil, fixed onto the lower cone part. The coil has 1000 turns and a typical resistance of 165 Ω at 20 °C (max. 250 Ω at 80 °C). Approx. 5 mA causes 1° trace rotation. Thus maximum required voltage is approx. 11 V for tube tolerances (± 5°) and earth magnetic field with reasonable shielding (± 2°).

DIMENSIONS AND CONNECTIONS

Dimensions in mm

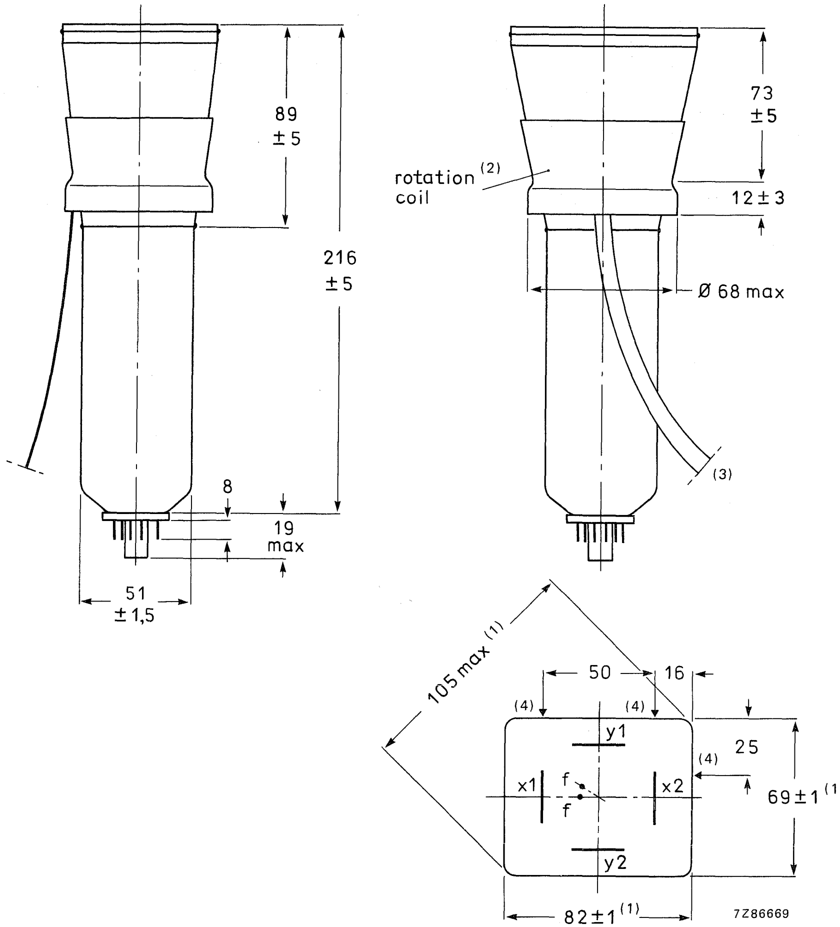


Fig. 1 Outlines; for notes see bottom of opposite page.

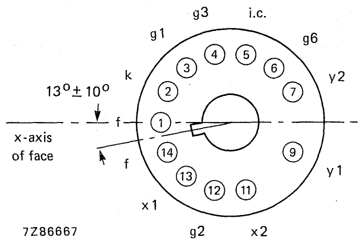


Fig. 2 Pin arrangement; bottom view.

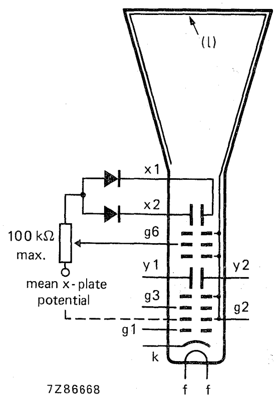


Fig. 3 Electrode configuration.

Notes to the drawing on opposite page.

1. Dimensions of face plate only. The complete assembly of face plate and cone (frit seal included) will pass through an opening of 85 mm x 72 mm (diagonal 107 mm).
2. The coil is fixed to the envelope with resin and adhesive tape.
3. The length of the connecting leads of the rotation coil is min. 350 mm.
4. Reference points on face plate for screen alignment.

TYPICAL OPERATION*

Conditions (note 1)

Accelerator voltage	$V_{g2(\ell)}$	2000 V	
Astigmatism control voltage	$\Delta V_{g2(\ell)}$	0 V	note 2
Focusing electrode voltage	V_{g3}	220 to 360 V	
Cut-off voltage for visual extinction of focused spot	$-V_{g1}$	22 to 65 V	

Performance

Useful scan			
horizontal		$\geqslant$ 70 mm	
vertical		$\geqslant$ 56 mm	
Deflection coefficient			
horizontal	M_x	36 V/cm $\leqslant$ 39 V/cm	
vertical	M_y	23 V/cm $\leqslant$ 25,5 V/cm	
Line width at 10 μA beam current	l.w.	$\approx$ 0,2 mm	note 3
Deviation of linearity of deflection		$\leqslant$ 2 %	note 4
Geometry distortion		see note 5	
Grid drive for 10 μA screen current	V_d	$\approx$ 10 V	

LIMITING VALUES (Absolute maximum rating system)

Accelerator voltage	$V_{g2(\ell)}$	max. 2200 V
Focusing electrode voltage	V_{g3}	max. 2200 V
Voltage between accelerator electrode and grid 6	$V_{g2/g6}$	max. ± 500 V
Voltage between accelerator electrode and any deflection plate	$V_{g2/x/y}$	max. ± 500 V
Control grid voltage	$-V_{g1}$	max. 200 V min. 0 V
Cathode to heater voltage		
positive	V_{kf}	max. 125 V
negative	$-V_{kf}$	max. 125 V
Grid drive, averaged over 1 ms	V_d	max. 20 V
Screen dissipation	W_ℓ	max. 3 mW/cm^2
Control grid circuit resistance	R_{g1}	max. 1 MΩ

* Notes are on page 7.

NOTES

1. The mean x-plate potential and the mean y-plate potential should be equal to $V_{g2(\ell)}$.
2. The tube features internal magnetic correction for spot shaping (astigmatism) and vertical eccentricity calibration. Correction is obtained at V_{g2} = 1800 to 2200 V; optimum at V_{g2} = 2000 V.
3. Measured with the shrinking raster method within the useful scan under typical operating conditions, adjusted for optimum focus and dynamic correction applied.

   As the construction of the tube does not permit a direct measurement of the beam current, this current should be determined as follows:

   a) Under typical operating conditions, apply a small raster display (no overscan), adjust V_{g1} for a beam current of approx. 10 μA and adjust V_{g3} for smallest spot size at the centre of the screen. When measuring the beam current, grid 6 should be connected to g2-potential and the diodes should be disconnected from the x-plates.

   b) Under these conditions, but without raster, the deflection plate voltages should be changed to: $V_{y1} = V_{y2}$ = 2000 V; V_{x1} = 1300 V; V_{x2} = 1700 V, thus directing the total beam current to x_2. Measure the current on x_2 and adjust V_{g1} for I_{x2} = 10 μA.

   c) Set again for the conditions under a), without touching the V_{g1} control. The screen current of the resulting raster display is now 10 μA.
   Adjust V_{g3} for optimum focus in the centre of the screen and apply dynamic correction to grid 6 for optimum vertical line width.
4. The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.
5. A graticule consisting of concentric rectangles of 70 mm x 56 mm and 68,4 mm x 54,4 mm is aligned with the face plate (using the reference points). With optimum trace rotation correction, horizontal and vertical lines will fall between these rectangles.

INSTRUMENT CATHODE-RAY TUBE

- mono accelerator
- 10 cm diagonal rectangular flat face
- dynamic deflection defocusing correction
- internal magnetic correction for astigmatism and vertical eccentricity
- low heater power consumption
- for portable oscilloscopes with up to 25 MHz bandwidth, and read-out devices

QUICK REFERENCE DATA

Accelerator voltage	$V_{g2(\ell)}$	2000	V
Minimum useful scan area		70 x 56	mm
Deflection coefficient			
horizontal	M_x	36	V/cm
vertical	M_y	23	V/cm

The D10-181GY is equivalent to type D10-180GY except for the following.

HEATING

Indirect by a.c. or d.c.*

Heater voltage	V_f	6,3	V
Heater current	I_f	95	mA

LIMITING VALUES (Absolute maximum rating system)

Cathode to heater voltage				
positive	V_{kf}	max.	100	V
negative	$-V_{kf}$	max.	15	V

CAPACITANCES

Cathode to all other elements	C_k	2,5	pF

* Not to be connected in series with other tubes.

INSTRUMENT CATHODE-RAY TUBE

12 cm diagonal rectangular flat-faced oscilloscope tubes with mesh and metal-backed screen with internal graticule. For use in compact oscilloscopes.

QUICK REFERENCE DATA

Final accelerator voltage	$V_{g8(\ell)}$	10 kV
Minimum useful scan area		80 mm x 64 mm
Deflection coefficient		
horizontal	M_x	15,6 V/div
vertical	M_y	4,1 V/div

OPTICAL DATA

Screen	metal-backed phosphor
type	GH, colour green
persistence	medium short
Useful screen area	⩾ 80 mm x 64 mm
Useful scan area	⩾ 80 mm x 64 mm
Spot eccentricity in horizontal and vertical directions	⩽ 0,6 div
Internal graticule	type 115; see Fig. 5

HEATING

Indirect by a.c. or d.c.*

Heater voltage	V_f	6,3 V
Heater current	I_f	95 mA

* Not to be connected in series with other tubes.

MECHANICAL DATA

Dimensions and connections (see also outline drawing)

Overall length (socket included)	$\leqslant$ 335 mm
Faceplate dimensions	86 ± 2 mm x 98 ± 2 mm
Net mass	approx. 700 g
Base	14 pin, all glass

Mounting

The tube can be mounted in any position. It should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Accessories

Socket, supplied with tube	type 55566
Side contact connector (5 required)	type 55561
Final accelerator contact connector	type 55563A

FOCUSING	electrostatic
DEFLECTION	double electrostatic
x-plates	symmetrical
y-plates	symmetrical
Angle between x and y-traces	90 ± 1°
Angle between x-trace and x-axis of the internal graticule	$\leqslant$ 5° *

If use is made of the full deflection capabilities of the tube the deflection plates will block part of the electron beam, hence a low impedance deflection plate drive is desirable.

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	5,3 pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	5,3 pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	3,6 pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	3,6 pF
x_1 to x_2	C_{x1x2}	2,1 pF
y_1 to y_2	C_{y1y2}	1,7 pF
Control grid to all other elements	C_{g1}	5,5 pF
Cathode to all other elements	C_k	4,5 pF

* The tube has a rotation coil, concentrically wound around the tube neck, to allow alignment of the x-trace with the mechanical x-axis of the screen. The coil has 1000 turns and a maximum resistance of 150 Ω. Under typical operating conditions, approx. 50 ampere-turns are required for the maximum rotation of 5°.

DIMENSIONS AND CONNECTIONS

Dimensions in mm

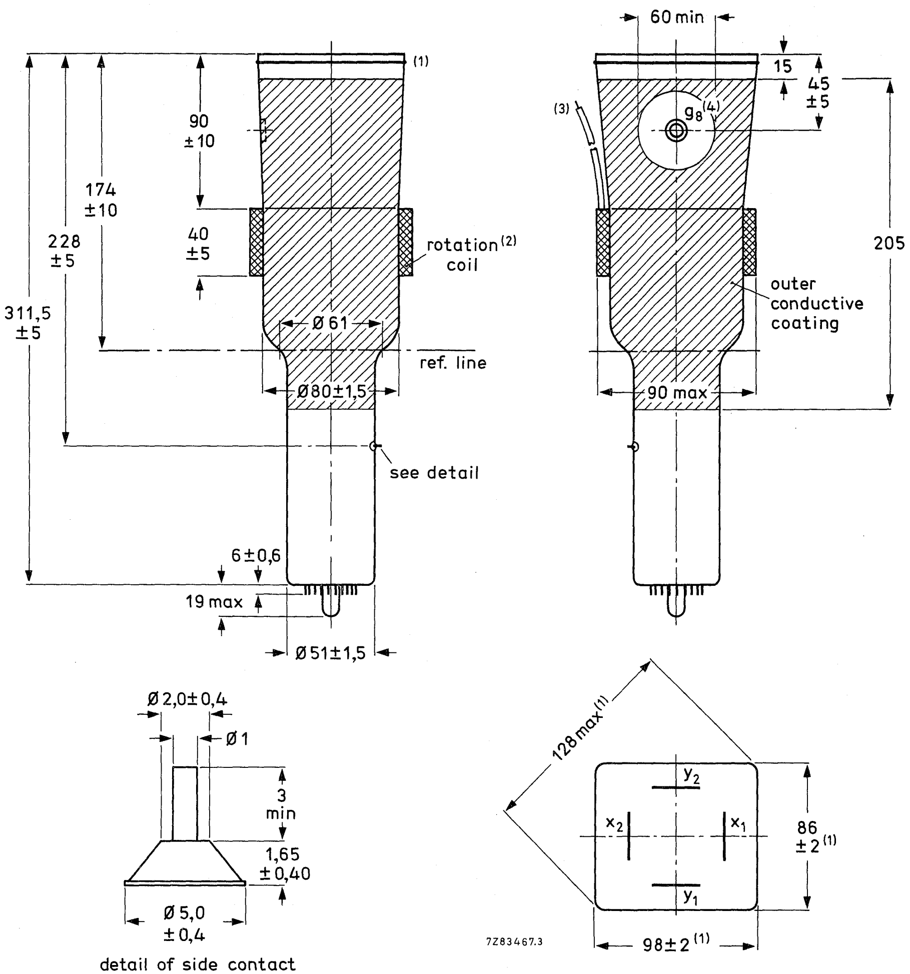


Fig. 1 Outlines.

1. The bulge at the frit seal may increase the indicated maximum dimensions by not more than 2,8 mm.
2. The coil is fixed to the envelope by means of adhesive tape.
3. Connection cable, comprising two wires for connection of the rotation coil, and one green wire for earthing the outer conductive coating. Minimum cable length is 120 mm.
4. The centre of the final accelerator contact is situated within a square of 10 mm x 10 mm around the true geometrical position.

DIMENSIONS AND CONNECTIONS (continued)

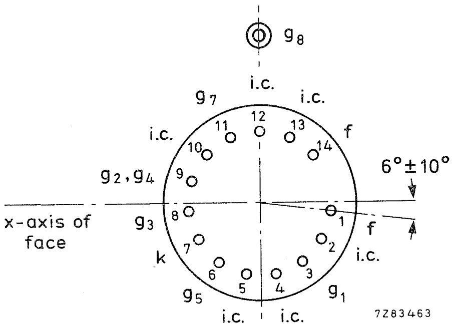


Fig. 2 Pin arrangement; bottom view.

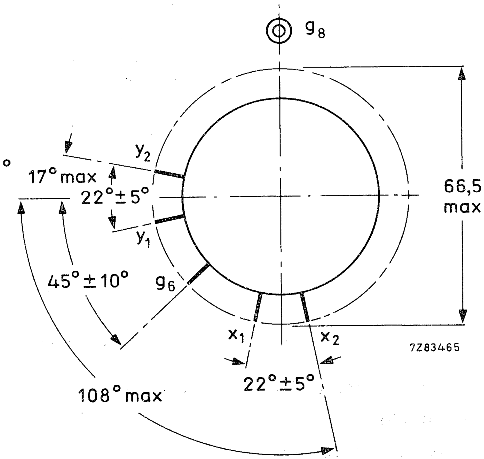


Fig. 3 Side-contact arrangement; bottom view.

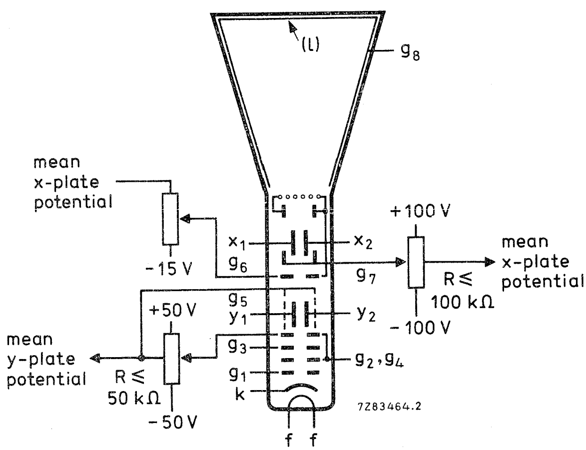


Fig. 4 Electrode configuration.

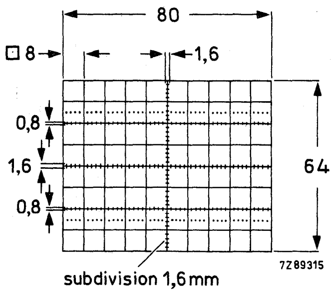


Fig. 5 Internal graticule.
Line width = 0,15 mm;
dot diameter = 0,32 mm.

TYPICAL OPERATION (for notes see page 6)

Conditions

Final accelerator voltage	$V_{g8(\ell)}$	10	kV
Geometry control electrode voltage	V_{g7}	1500 ± 100	V (note 1)
Post deflection shield and interplate shield voltage	V_{g6}	1500	V
Background illumination control voltage	ΔV_{g6}	0 to −15	V (note 1)
Deflection plate shield voltage	V_{g5}	1500	V (note 2)
Focusing electrode voltage	V_{g3}	250 to 350	V
First accelerator voltage	$V_{g2,g4}$	1500	V
Astigmatism control electrode voltage	$\Delta V_{g2,g4}$	± 50	V (note 3)
Cut-off voltage for visual extinction of focused spot	$-V_{g1}$	18 to 60	V

Performance

Useful scan			
horizontal		⩾ 80	mm
vertical		⩾ 64	mm
Deflection coefficient			
horizontal	M_x	15,6	V/div
		⩽ 17	V/div
vertical	M_y	4,1	V/div
		⩽ 4,5	V/div
Line width	l.w.	typ. 0,35	mm (note 4)
Grid drive for 10 μA screen current	V_d	approx. 12	V
Geometry distortion		see note 5	
Deviation of deflection linearity		⩽ 2%; see note 6	

LIMITING VALUES (Absolute maximum rating system)

Final accelerator voltage	$V_{g8(\ell)}$	max.	11 kV
Geometry control electrode voltage	V_{g7}	max.	2200 V
Post deflection shield and inter-plate shield voltage	V_{g6}	max.	2200 V
Deflection plate shield voltage	V_{g5}	max.	2200 V
Focusing electrode voltage	V_{g3}	max.	2200 V
First accelerator and astigmatism voltage	$V_{g2,g4}$	max.	2200 V
		min.	1350 V
Control grid voltage	$-V_{g1}$	max.	200 V
		min.	0 V
Cathode to heater voltage			
positive	V_{kf}	max.	100 V
negative	$-V_{kf}$	max.	15 V
Voltage between astigmatism control electrode and any deflection plate	$V_{g4/x}$	max.	500 V
	$V_{g4/y}$	max.	500 V
Grid drive, averaged over 1 ms	V_d	max.	20 V
Screen dissipation	W_ℓ	max.	8 mW/cm^2
Control grid circuit resistance	R_{g1}	max.	1 MΩ

Notes

1. The tube is designed for optimum performance when operating at a ratio $V_{g8(\ell)}/V_{g2,g4} = 6{,}7$.
   The geometry control electrode voltage V_{g7} should be adjusted within the indicated range (values with respect to the mean x-plate potential).
   A negative control voltage V_{g6} (with respect to the mean x-plate potential) will cause some pincushion distortion and less background light, a positive control voltage will give some barrel distortion, and a slight increase of background light. By the use of the two voltages V_{g6} and V_{g7}, the best compromise between background light and raster distortion can be found.
2. The deflection plate shield voltage should be equal to the mean y-plate potential. The mean x-plate and y-plate potentials should be equal for optimum spot quality.
3. The astigmatism control electrode voltage should be adjusted for optimum spot shape. For any necessary adjustment its potential will be within the stated range.
4. Measured with the shrinking raster method in the centre of the screen, under typical operating conditions, adjusted for optimum spot size, at a beam current of 10 μA.
5. A graticule consisting of concentric rectangles of 80 mm x 64 mm and 78,2 mm x 62,6 mm is aligned with the electrical x-axis of the tube. With optimum corrections applied, the edges of a raster will fall between these rectangles.
6. The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.

INSTRUMENT CATHODE-RAY TUBE

13 cm diameter flat faced short oscilloscope tube (max. 35 cm) with post-deflection acceleration by means of a helical electrode. The tube is provided with deflection blanking.

QUICK REFERENCE DATA				
Final accelerator voltage	$V_{g7(\ell)}$	=	3000	V
Display area			8 cm x full scan	
Deflection coefficient, horizontal	M_x	=	24	V/cm
vertical	M_y	=	11.5	V/cm

SCREEN

	Colour	Persistence
D13-27GH	green	medium short

Useful screen diameter min. 114 mm

Useful scan at $V_{g7(\ell)}/V_{g5} = 2$

horizontal full scan

vertical min. 80 mm

The useful scan may be shifted vertically to a max. of 4 mm with respect to the geometric centre of the faceplate.

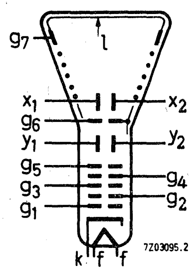
HEATING

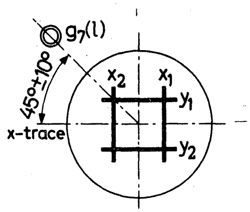
Indirect by A.C. or D.C.; parallel supply

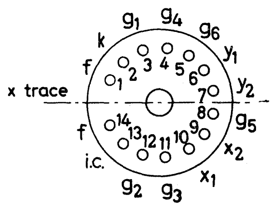
Heater voltage	V_f	=	6.3	V
Heater current	I_f	=	300	mA

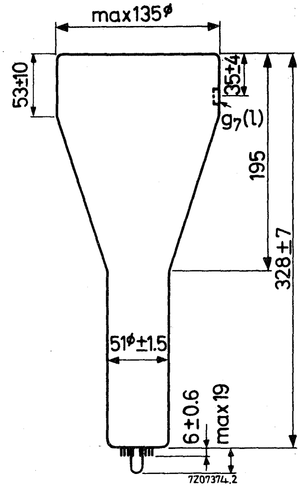
MECHANICAL DATA

Dimensions in mm









Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Base 14 pin all glass

Dimensions and connections

Overall length (also with socket type 55566)	max.	354	mm
Face diameter	max.	135	mm

Net weight	approx.	680	g

Accessories

Socket (supplied with tube)	type	55566
Final accelerator contact connector	type	55563A
Mu metal shield	type	55557

CAPACITANCES

x_1 to all other elements except x_2	$C_{x_1(x_2)}$	=	4.5	pF
x_2 to all other elements except x_1	$C_{x_2(x_1)}$	=	4.5	pF
y_1 to all other elements except y_2	$C_{y_1(y_2)}$	=	5	pF
y_2 to all other elements except y_1	$C_{y_2(y_1)}$	=	5.5	pF
x_1 to x_2	$C_{x_1x_2}$	=	2.5	pF
y_1 to y_2	$C_{y_1y_2}$	=	1.2	pF
Grid No.1 to all other elements	C_{g_1}	=	5.5	pF
Cathode to all other elements	C_k	=	5	pF
Grid No.3 to all other elements	C_{g_3}	=	10	pF

FOCUSING electrostatic

DEFLECTION double electrostatic

x plates symmetrical

y plates symmetrical

If use is made of the full deflection capabilities of the tube the deflection plates will intercept part of the electron beam; hence a low impedance deflection plate drive is desirable.

Angle between x and y traces $90^\circ \pm 1^\circ$

LINE WIDTH

Measured with the shrinking raster method in the centre of the screen.

Final accelerator voltage	$V_{g_7(\ell)}$	=	3000	V
Astigmatism control electrode voltage	V_{g_5}	=	1500	V 2)
First accelerator voltage	V_{g_2}	=	1500	V
Beam current	$I_{g_7(\ell)}$	=	10	µA
Line width	l.w.	=	0.25	mm

HELIX

Post deflection accelerator helix resistance min. 50 MΩ
The helix is connected between $g_7(\ell)$ and g_6

---

2) See page 5

TYPICAL OPERATING CONDITIONS

Final accelerator voltage	$V_{g_7(\ell)}$	=	3000	V
Geometry control electrode voltage	V_{g_6}	=	1500 ± 75	V [1]
Astigmatism control electrode voltage	V_{g_5}	=	1500 ± 75	V [2]
Focusing electrode voltage	V_{g_4}	=	300 to 550	V
Deflection blanking electrode voltage	V_{g_3}	=	1500	V
Deflection blanking control voltage	ΔV_{g_3}	=	max. -60	V [3]
First accelerator voltage	V_{g_2}	=	1500	V
Control grid voltage for visual extinction of focused spot	V_{g_1}	=	-38 to -135	V
Deflection coefficient				
horizontal	M_x	=	21 to 27	V/cm
vertical	M_y	=	9.8 to 12.2	V/cm
Deviation of linearity of deflection		=	max. 2	% [4]
Geometry distortion			See note 5	
Useful scan				
horizontal			full scan	
vertical		=	min. 80	mm

CIRCUIT DESIGN VALUES

Focusing voltage	V_{g_4}	=	200 to 370	V per kV of V_{g_5}
Control grid voltage for visual extinction of focused spot	$-V_{g_1}$	=	25 to 90	V per kV of V_{g_2}
Deflection coefficient at $V_{g_7(\ell)}/V_{g_5} = 2$				
horizontal	M_x	=	14 to 18	V/cm per kV of V_{g_5}
vertical	M_y	=	6.5 to 8.2	V/cm per kV of V_{g_5}
Control grid circuit resistance	R_{g_1}	=	max. 1.5	MΩ
Deflection plate circuit resistance	R_x, R_y	=	max. 50	kΩ
Focusing electrode current	I_{g_4}	=	-15 to +10	μA [6]

Notes see page 5

LIMITING VALUES (Absolute max. rating system)

Final accelerator voltage	$V_{g_7(\ell)}$	= max. = min.	3300 1800	V V
Geometry control electrode voltage	V_{g_6}	= max.	1700	V
Astigmatism control electrode voltage	V_{g_5}	= max. = min.	1700 1200	V V
Focusing electrode voltage	V_{g_4}	= max.	1200	V
Deflection blanking electrode voltage	V_{g_3}	= max.	1700	V
First accelerator voltage	V_{g_2}	= max.	1700	V
Control grid voltage				
negative	$-V_{g_1}$	= max.	200	V
positive	$-V_{g_1}$	= min.	0	V
Voltage between astigmatism control electrode and any deflection plate	$V_{g_5/x}$	= max.	500	V
	$V_{g_5/y}$	= max.	500	V
Screen dissipation	W_{ℓ}	= max.	3	mW/cm^2
Ratio $V_{g_7(\ell)}/V_{g_5}$	$V_{g_7(\ell)}/V_{g_5}$	= max.	2	
Cathode current, average	I_k	= max.	300	μA

1) This tube is designed for optimum performance when operating at the ratio $V_{g_7(\ell)}/V_{g_5} = 2$. Operation at other ratio may result in changes in deflection uniformity and geometry distortion. The geometry control electrode voltage should be adjusted for optimum performance. For any necessary adjustment its potential will be within the stated range.

2) The astigmatism control electrode voltage should be adjusted for optimum spot shape. For any necessary adjustment its potential will be within the stated range.

3) For beam blanking of a beam current of 10 μA.

4) The sensitivity at a deflection of less than 75% of the usefull scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.

5) A graticule, consisting of concentric rectangles of 100 mm x 60 mm and 97 mm x 58 mm is aligned with the electrical x axis of the tube. The edges of a raster will fall between these rectangles with optimum correction potentials applied.

6) Values to be taken into account for the calculation of the focus potentiometer.

INSTRUMENT CATHODE-RAY TUBE

13 cm diameter flat faced monoaccelerator oscilloscope tube primarily intended for use in inexpensive oscilloscopes and read-out devices.

QUICK REFERENCE DATA			
Accelerator voltage	$V_{g_2,g_4,g_5(\ell)}$	2000	V
Display area		100 x 80	mm^2
Deflection coefficient, horizontal	M_x	31.3	V/cm
vertical	M_y	14.4	V/cm

SCREEN

	colour	persistence
D13-480GH	green	medium short
D13-480GM	yellowish green	long

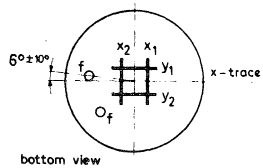
Useful screen diameter	min.	114	mm
Useful scan			
horizontal	min.	100	mm
vertical	min.	80	mm

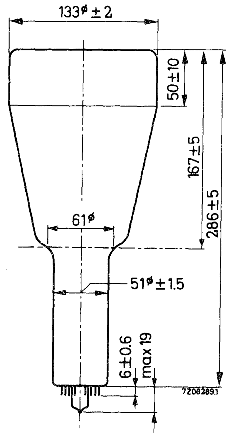
The useful scan may be shifted vertically to a max. of 6 mm with respect to the geometric centre of the faceplate.

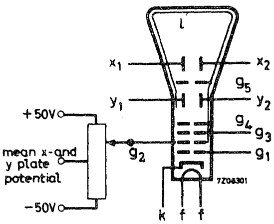
HEATING: Indirect by A.C. or D.C.; parallel supply

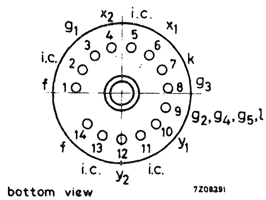
Heater voltage	V_f	6.3	V
Heater current	I_f	300	mA

MECHANICAL DATA (Dimensions in mm)









Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Dimensions and connections

See also outline drawing

Overall length	max.	310	mm
Face diameter	max.	135	mm

Base 14 pin all glass

Net weight	approx.	650	g

Accessories

Socket (supplied with tube)	type	55566
Mu-metal shield	type	55580

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	4	pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	4	pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	3.5	pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	3	pF
x_1 to x_2	C_{x1x2}	1.6	pF
y_1 to y_2	C_{y1y2}	1.1	pF
Control grid to all other elements	C_{g1}	5.5	pF
Cathode to all other elements	C_k	4	pF

FOCUSING electrostatic

DEFLECTION double electrostatic

x plates symmetrical

y plates symmetrical

If use is made of the full deflection capabilities of the tube the deflection plates will intercept part of the electron beam, hence a low impedance deflection plate drive is desirable.

Angle between x and y traces $90 \pm 1^{\circ}$

LINE WIDTH 3)

Measured with the shrinking raster method in the centre of the screen under typical operating conditions, adjusted for optimum spot size at a beam current I_ℓ = 10 μA.1)

Line width	l.w.	0.30	mm

1) As the construction of this tube does not permit a direct measurement of the beam current, this current should be determined as follows:
a) under typical operating conditions, apply a small raster display (no overscan), adjust V_{g1} for a beam current of approx. 10 μA and adjust V_{g3} and $V_{g2,g4,g5,\ell}$ for optimum spot quality at the centre of the screen.
b) under these conditions, but no raster, the deflection plate voltages should be changed to
$V_{y1} = V_{y2} = 2000$ V; $V_{x1} = 1300$ V; $V_{x2} = 1700$ V, thus directing the total beam current to x2.
Measure the current on x_2 and adjust V_{g1} for $I_{x2} = 10$ μA (being the beam current I_ℓ)
c) set again for the conditions under a), without touching the V_{g1} control. Now a raster display with a true 10 μA screen current is achieved.
d) focus optimally in the centre of the screen (do not adjust the astigmatism control) and measure the line width.

3) See page 4

TYPICAL OPERATING CONDITIONS 3)

Accelerator voltage	$V_{g2,g4,g5,\ell}$	2000	V
Astigmatism control voltage	$\Delta V_{g2,g4,g5,\ell}$	± 50	V 1)
Focusing electrode voltage	V_{g3}	220 to 370	V
Control grid voltage for visual extinction of focused spot	V_{g1}	max. −65	V
Grid drive for 10 μA screen current		approx. 10	V
Deflection coefficient, horizontal	M_x	31.3	V/cm
		max. 33	V/cm
vertical	M_y	14.4	V/cm
		max. 15.5	V/cm
Deviation of linearity of deflection		max. 1	% 2)
Geometry distortion		see note 4	
Useful scan, horizontal		min. 100	mm
vertical		min. 80	mm

LIMITING VALUES (Absolute max. rating system)

Accelerator voltage	$V_{g2,g4,g5,\ell}$	max. 2200	V
		min. 1500	V
Focusing electrode voltage	V_{g3}	max. 2200	V
Control grid voltage, negative	$-V_{g1}$	max. 200	V
		min. 0	V
Cathode to heater voltage	V_{kf}	max. 125	V
	$-V_{kf}$	max. 125	V
Grid drive, average		max. 20	V
Screen dissipation	W_{ℓ}	max. 3	mW/cm^2
Control grid circuit resistance	R_{g1}	**max. 1**	MΩ

1) All that will be necessary when putting the tube into operation is to adjust the astigmatism control voltage once for optimum spot shape in the screen centre. The control voltage will always be in the range stated, provided the mean x and certainly the mean y plate potential was made equal to $V_{g2,g4,g5,\ell}$ with zero astigmatism correction.

2) The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.

3) The mean x and certainly the mean y plate potential should be equal to $V_{g2,g4,g5,\ell}$ with astigmatism adjustment set to zero.

4) A graticule, consisting of concentric rectangles of 70 mm x 85 mm and 68.8 mm x 83 mm as aligned with the electrical x-axis of the tube. The edges of a raster will fall between these ractangles.

INSTRUMENT CATHODE-RAY TUBE

13 cm diameter flat-faced monoaccelerator oscilloscope tube with low heater consumption.

QUICK REFERENCE DATA

Accelerator voltage	$V_{g2, g4, g5\,(\ell)}$	2000 V
Display area		100 x 80 mm^2
Deflection coefficient		
horizontal	M_x	31,3 V/cm
vertical	M_y	14,4 V/cm

The D13–481.. is equivalent to the type D13–480.. except for the following.

HEATING

Indirect by a.c. or d.c.; parallel

Heater voltage	V_f	6,3 V
Heater current	I_f	95 mA

LIMITING VALUES (Absolute maximum rating system)

Cathode to heater voltage			
positive	$V_{+k/f-}$	max.	100 V
negative	$V_{-k/f+}$	max.	15 V

CAPACITANCES

Cathode to all other elements	C_k	2,3 pF

INSTRUMENT CATHODE-RAY TUBE

The D13-500GH/01 is a wide-band oscilloscope tube designed for observation and measurement of high frequency phenomena.
This tube has a rectangular 13 cm diagonal flat face with aluminized screen and internal graticule, post-deflection accelerator with mesh, vertical deflection by means of a symmetrical helix system, scan magnification in the vertical direction by means of an electrostatic quadrupole lens and correction coils for trace alignment, vertical shift of the display area and correction of the orthogonality of traces.

QUICK REFERENCE DATA			
Final accelerator voltage	$V_{g13(\ell)}$	15	kV
Display area		100 x 60	mm^2
Deflection coefficient, horizontal	M_x	13.5	V/cm
vertical	M_y	1.7	V/cm
Bandwidth of the vertical deflection system	B	800	MHz

SCREEN

	colour	persistence
D13-500GH/01	green	medium short

Useful screen dimensions	min.	100 x 60	mm^2
Useful scan at $V_{g13(\ell)}/V_{g2} = 6$			
horizontal	min.	100	mm
vertical	min.	60	mm
Eccentricity in horizontal direction	max.	7	mm
Eccentricity in vertical direction	max.	6	mm

The scanned raster can be shifted in vertical direction and aligned with the internal graticule by means of correction coils mounted on the tube (see page 14).

For illumination of the internal graticule see page 16.

DESCRIPTION

General

The D13-500GH/01 has been primarily designed for wide-band high-frequency applications. It combines high brightness, high deflection sensitivity and a large bandwidth of the vertical deflection system.

In order to obtain the high sensitivity, the post-deflection acceleration system embodies a mesh. The sensitivity in the vertical direction has been further increased by means of an electrostatic quadrupole lens that has been inserted between the vertical deflection system and the horizontal deflection plates. The large bandwidth has been obtained by using, for the vertical deflection, a delay-line system instead of deflection plates. With the typical operating conditions, 2500 V first accelerator voltage and 15 000 V final accelerator voltage, the vertical and the horizontal deflection factors are about 2 V/cm and 15 V/cm respectively, with a 10×6 cm^2 display area.

The bulb has a rectangular face and the screen is aluminized. To eliminate parallax errors, an internal graticule is incorporated. Correction coils have been provided to permit image rotation, correction of the orthogonality of traces and the adjustment of the vertical useful scan with respect to the graticule.

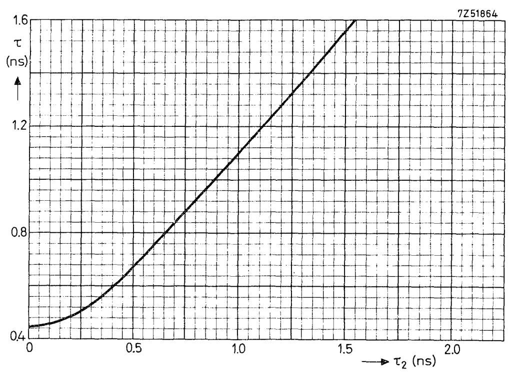


Fig. 1
Rise time of the display τ as a function of the rise time of the input signal τ_2

The vertical deflection system

For the vertical deflection, a delay-line system is used so that transit-time effects are practically eliminated. The system consists of two flattened helices to which a symmetrical deflection signal should be applied. Under these conditions, the characteristic impedance of each helix is 150 Ω. The input and output terminals are brought out on opposite sides of the neck on the same plane. The input terminals are connected to the beginning of the helices by means of a matched, internal two-wire transmission line. The output of the deflection system should be properly terminated in order to avoid signal reflections.

With the typical operating conditions, the band-width of the deflection system, i.e. the frequency at which the sensitivity is 3 dB below its value at D.C., is about 800 MHz. Even above this frequency, the response decreases only gradually so that, for narrow-band applications, the tube can be used with reduced vertical sensitivity up to about 2000 MHz.

The rise time τ_1, i.e. the time interval during which the display of an ideal step-function signal applied to the input goes from 10% to 90% of its final value, is about 0.45 ns. If the input signal has the rise-time τ_2, the rise-time τ of the display is approximately given by

$$\tau = \sqrt{\tau_1^2 + \tau_2^2}$$

In Fig.1, τ has been plotted as a function of τ_2, with $\tau_1 = 0.45$ ns. If, for example, the tube is used in combination with an amplifier and the rise-time of the display is to be 1.4 ns (corresponding with 250 MHz band-width), the rise-time of the amplifier should be 1.33 ns. It can be seen that in this region the rise-time of the display is almost equal to the amplifier rise-time, without a significant contribution of the cathode-ray tube.

If the tube is to be used without an amplifier in order to make use of its full bandwidth capabilities, care should be taken to ensure good symmetry of the input signal.

Fig.2 shows how the tube can be connected to a 50 Ω coaxial input. A matched power divider is used which delivers two identical output signals. One of these is inverted by means of a pulse inverter. An additional length of 50 Ω cable should be inserted into the path of the non-inverted signal having the same delay time as the pulse inverter so that the two signals arrive at the input of the deflection system at the same time. The 75 Ω shunt resistors serve to obtain a correct termination of the 50 Ω lines. Since each branch of the power divider has 6 dB attenuation, the sensitivity, measured at the 50 Ω input, is also 2 V/cm.

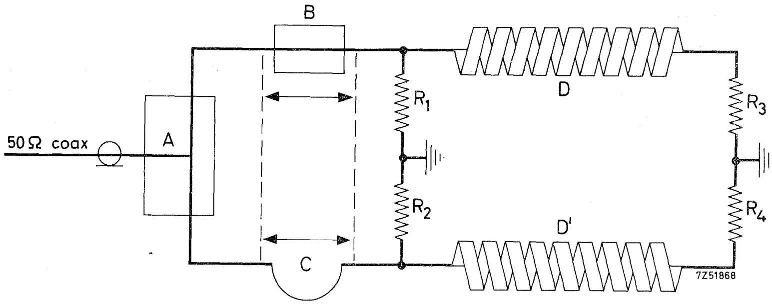


Fig.2
Connection to an asymmetrical 50 Ω input

A: Power divider — R_1, R_2: Resistors 75 Ω
B : Inverter — R_3, R_4: Resistors 150 Ω
C: Cable — D , D' : Deflection system

Note: Delay of inverter B and cable C are equal.

Scan magnifier and focusing system

As already mentioned, an electrostatic quadrupole lens, i.e. an electron lens which has two mutually perpendicular planes of symmetry, divergent in one plane and convergent in the other, is used for the magnification of the vertical deflection. This lens is inserted between the vertical deflection system and the horizontal deflection plates, with its plane of divergence in the direction of the vertical deflection. Therefore, it magnifies the vertical deflection without affecting the horizontal deflection.

Because of the astigmatic properties of this quadrupole lens, a conventional, rotationally symmetrical focusing lens cannot be used. Instead of this, two more electrostatic quadrupole lenses are incorporated so that focusing is accomplished by means of three quadrupole lenses, with alternating orientation of their planes of convergence and divergence. The focusing action is schematically shown in Fig.3. The strength of the scan-magnifier lens is controlled by applying to the electrode g_9 a negative voltage with respect to g_2. Within a certain range of this voltage, corresponding to a scan-magnification factor Msc, i.e. the ratio of the deviations on the screen with and without scan magnification respectively, between 1.8 and 2 the combined effect of the three lenses will yield an approximately circular spot at moderate beam currents. (At high beam currents, when space-charge repulsion causes an increase of spot size, the width of the vertical lines will be smaller than that of the horizontal lines).

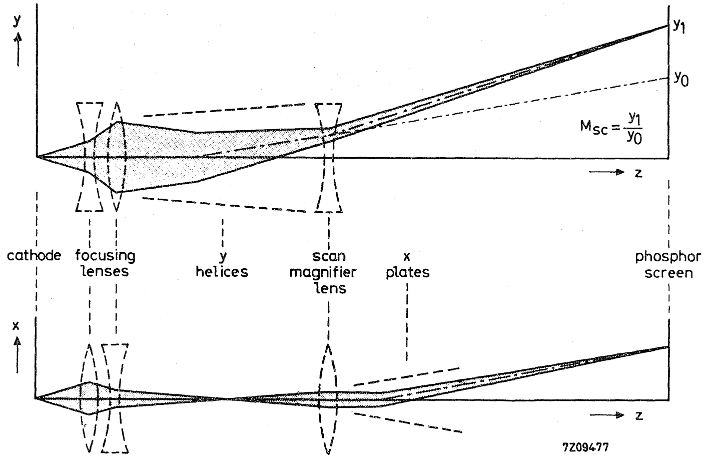


Fig.3

In this range, line-width at a fixed value of screen current, and screen current at a fixed value of grid No.1 voltage, are increasing functions of the scan-magnification factor. Figs.4 and 5 show the average relative change with respect to the values at Msc = 1.9 which, generally, is the most suitable compromise.

For minimum defocusing of vertical lines near the upper and lower edge of the display area, the electrode g_8 should be kept at a positive voltage with respect to g_2 (about 200 V with 2500 V first accelerator voltage). As this voltage also has some effect on the scan-magnification factor, both g_8 and g_9 should be connected to g_2 when the deviation without scan magnification is being measured.

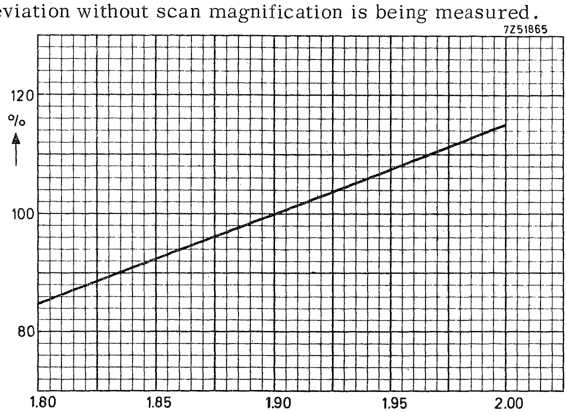


Fig.4

Line-width as a function of the scan-magnification factor (approximately)
Line-width at M_{sc} = 1.9 is 100%, I_{screen} = const.

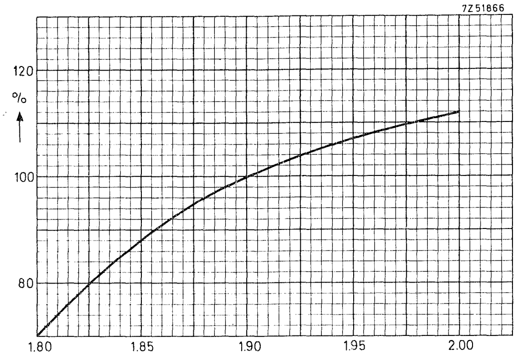


Fig.5

Screen current as a function of the scan-magnification factor (approximately)
Screen current at M_{sc} = 1.9 is 100%, V_{g_1} = const.

For the adjustment of the scan-magnification factor the following procedure is recommended:

a. Set V_{g_8} and V_{g_9} to 0 with respect to g_2.
b. Display a time-base line and adjust V_{g_6} so that the line appears sharply focused.
c. Apply a square wave signal to the vertical deflection system (the vertical parts of the trace will be out of focus but this is immaterial) and adjust the amplitude so that the height of the display has a convenient value, e.g. 30 mm.
d. Set V_{g_8} and V_{g_9} to the appropriate values and readjust V_{g_6} so that the horizontal parts of the trace are again in focus.
e. Check the height of the display (e.g. for M_{sc} = 1.9 this height should now be 57 mm).
f. If necessary, readjust V_{g_9} until the desired value of M_{sc} has been obtained.

Focusing is controlled by means of the electrode voltage V_{g_4} and V_{g_6}. The electrodes g_5 and g_7 can be used to centre the beam with respect to the vertical and horizontal deflection systems.

The voltages of the focusing and correction electrodes can be adjusted as follows:

a. Display a square-wave signal on the screen so that both horizontal and vertical traces are visible.
b. Adjust V_{g_6} so that the horizontal parts of the display are in focus. The vertical parts will, in general, be out of focus.
c. Adjust V_{g_4} so that the vertical traces are brought into focus. Now the horizontal parts of the display will be out of focus again.
d. Repeat b) and c) successively until both vertical and horizontal traces are simultaneously in focus.
e. Adjust V_{g_3} for minimum width of a horizontal line. If necessary, readjust focusing voltages V_{g_4} and V_{g_6}.

f. Adjust V_{g_7} for equal brightness at the left-hand and right-hand edges of the display area. If necessary, readjust the focus by means of V_{g_6}.

g. Adjust V_{g_5} so that the position of a horizontal trace not deflected in the vertical direction is at the centre of the vertical useful scan. If necessary, readjust the focus by means of V_{g_4}.

If the graticule is not fully covered by the scanned area the image should be shifted by adjusting the correction coil current (see page 16) before the adjustment of V_{g_5} is made.

The procedure for the adjustment of the scan-magnification factor and for focusing, as described above, seems to be rather complicated.
However, in practice it will be sufficient to adjust V_{g_9} to its nominal value without determining the scan-magnification factor for each individual tube. As to focusing, the user can, with some experience, achieve the best setting with very few adjustments.

Post-deflection acceleration

The use of a p.d.a. shield (mesh) ensures a high deflection sensitivity. A geometry control electrode, g_{11}, serves for the correction of pin cushion or barrel distortion of the pattern. In order to suppress background illumination due to secondary electrons originating from the p.d.a. shield g_{12}, this shield should be kept 12 V negative with respect to g_{11} whereas the voltage of the interplate shield, g_{10} should be equal to the mean x-plate potential.

HEATING: Indirect by A.C. or D.C.; parallel supply

Heater voltage	V_f	6.3	V
Heater current	I_f	300	mA

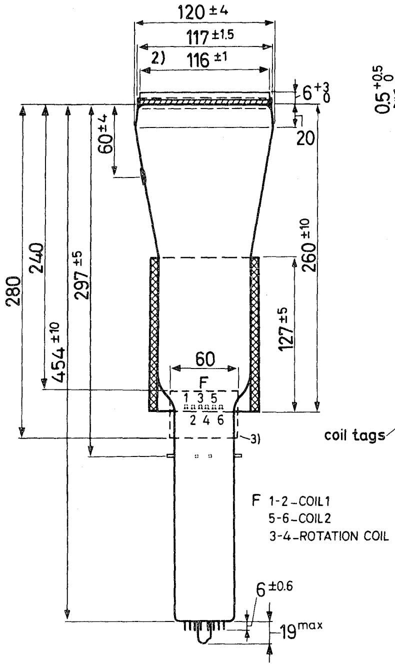
CAPACITANCES

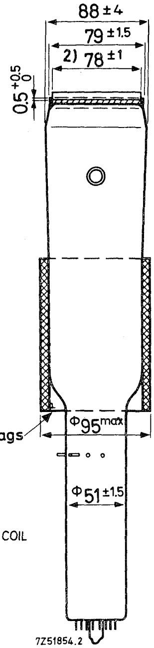
x_1 to all other elements except x_2	$C_{x_1(x_2)}$	4.5	pF
x_2 to all other elements except x_1	$C_{x_2(x_1)}$	4.5	pF
x_1 to x_2	$C_{x_1x_2}$	2.7	pF
Control grid to all other elements	C_{g_1}	6	pF
Cathode to all other elements	C_k	5	pF
External conductive coating to all other elements	C_m	1500	pF

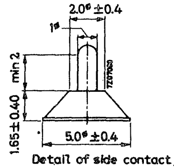
1) Clear area for light conductor.
2) These dimensions apply to the illumination plate which will always be within the limits 117 ± 1.5 x 79 ± 1.5 mm of the tube face.
3) The soldering tags will be situated within a rectangle of 60 mm x 40 mm on the rearside of the tube.

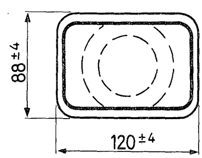
MECHANICAL DATA

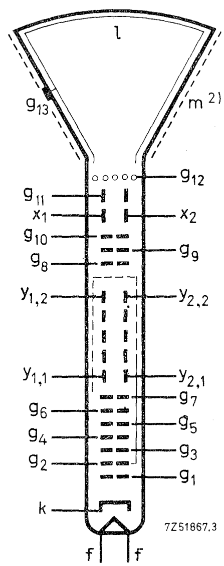
Dimensions in mm

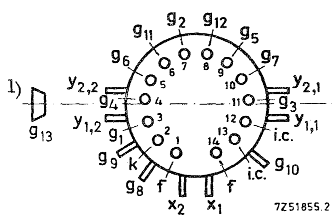










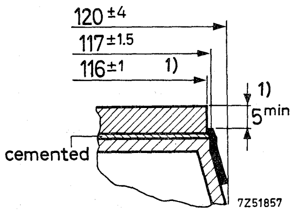


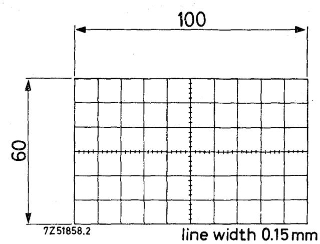
1) The centre of the contact is located within a square of 10 mm x 10 mm around the true geometrical position.

2) The external conductive coating must be earthed.

Notes: see page 7

MECHANICAL DATA (continued)





Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Dimensions and connections

See also outline drawing

Overall length (socket and front glass plate inclusive)	max.	492	mm
Face dimensions	max.	124 x 92	mm^2
Net weight	approx.	1300	g
Base	14-pin all glass		

Accessories

Socket	type 55566
Final accelerator contact connector	type 55563A
Side contact connector	type 55561
Mu-metal screen	type 55582

In order to avoid damage to the side contacts the narrower end of the mu-metal screen should have an internal diameter of not less than 65 mm.

[1]) see page 7

FOCUSING electrostatic [1]

DEFLECTION double electrostatic

x plates symmetrical

The y deflection system consists of a symmetrical delay line system.

Characteristic impedance	2 x 150	Ω
Bandwidth (−3 dB)	800	MHz [2]
Rise time	< 0.45	ns [3]

If use is made of the full deflection capabilities of the tube the deflection plates will intercept part of the electron beam: hence a low impedance deflection plate drive is desirable.

Angle between x and y traces 90° [4] (see page 14 "Correction coils")

[1] Because of the applications of a quadrupole lens for the magnification of the vertical deflection, two more quadrupole lenses are used for focusing. Therefore, controls for two voltages have to be provided.

[2] The band-width is defined as the frequency at which the vertical deflection sensitivity is 3 dB lower than at D.C.

[3] The rise-time is defined as the time interval between 10% and 90% of the final value of deflection when an ideal step-function signal is applied to the vertical deflection system. If the actual signal has an appreciable rise-time τ_2, the rise-time of the tube can be determined from

$$\tau_1 = \sqrt{\tau^2 - \tau_2^2}$$

where τ is the rise-time observed on the display.
This should be measured after the angle between the x-traces and y-traces has been corrected by means of the correction coils, otherwise two measurements have to be taken (using either a different polarity of the vertical deflection signal or different direction of the time-base sweep) and the true value of τ has to be calculated as the arithmetic mean of the two results.

[4] Deviations from the orthogonality of traces can be eliminated by means of correction coils.

LINE WIDTH

Measured with the shrinking raster method in the centre of the screen under typical operating conditions, adjusted for optimum spot size at a beam current I_ℓ = 10 µA and a screen magnification factor M_{sc} = 1.9. See also 3) page 13.

Line width	l.w.		approx. 0,35	mm	

TYPICAL OPERATING CONDITIONS

Final accelerator	$V_{g13(\ell)}$		15	kV	
Post deflection shield voltage (with respect to g_{11})	$V_{g12-g11}$		−9 to −15	V	
Geometry control electrode voltage	V_{g11}		2500 ±100	V	1)
Interplate shield voltage	V_{g10}		2500	V	2)
Scan magnifier electrode voltage (with respect to g_2)	V_{g9-g2}		−250 to −375	V	3)
Correction electrode voltage (with respect to g_2)	V_{g8-g2}		+200	V	4)
Horizontal beam centering electrode voltage	V_{g7}		2500 ±70	V	5)
Vertical beam centering electrode voltage	V_{g5}		2500	V	
Focusing electrode voltages (with respect to g_2)	V_{g6-g2}		-450 to -650	V	7)
	V_{g4-g2}		-650 to -850	V	7)
Spot correction electrode voltage	V_{g3}		2500 ±70	V	8)
First accelerator voltage	V_{g2}		2500	V	
Control grid voltage for visual extinction of a focused spot	V_{g1}		−75 to −150	V	
Deflection coefficient, horizontal	M_x	typ.	13.5	V/cm	
		max.	15.0	V/cm	
vertical	M_y	typ.	1.7	V/cm	9)
		max.	2.0	V/cm	
Deviation of linearity of deflection			2	%	10)
Geometry distortion			see note 11		
Useful scan, horizontal			100	mm	
vertical			60	mm	

Notes see page 13

LIMITING VALUES (absolute max. rating system)

Final accelerator voltage	$V_{g13(\ell)}$	max.	18 000	V
		min.	9 000	V
Post-deflection shield voltage	V_{g12}	max.	3 100	V
Geometry control electrode voltage	V_{g11}	max.	3 100	V
Interplate shield voltage	V_{g10}	max.	3 100	V
Scan-magnifier electrode voltage	V_{g9}	max.	3 000	V
Correction electrode voltage	V_{g8}	max.	3 200	V
Focusing electrode voltages	V_{g6}	max.	3 000	V
	$-V_{g6-g2}$	max.	1 000	V
	V_{g4}	max.	3 000	V
	$-V_{g4-g2}$	max.	1 000	V
Beam centering electrode voltages	V_{g7}	max.	3 100	V
	V_{g5}	max.	3 100	V
Spot correction electrode voltage	V_{g3}	max.	3 100	V
First accelerator voltage	V_{g2}	max.	3 000	V
		min.	2 000	V
Control grid voltage, negative	$-V_{g1}$	max.	200	V
positive	V_{g1}	max.	0	V
Cathode to heater voltage				
cathode positive	V_{kf}	max.	125	V
cathode negative	$-V_{kf}$	max.	125	V
Voltage between first accelerator and any deflection electrode	$V_{g2\,x}$	max.	500	V
	$V_{g2\,y}$	max.	500	V
Screen dissipation	W_{ℓ}	max.	3	mW/cm^2
Average cathode current	I_k	max.	300	μA
Control grid circuit resistance	R_{g1}	max.	1	$M\Omega$

Notes to page 11

1) This voltage should be adjusted for optimum pattern geometry.

2) This voltage should be equal to the mean x-plate potential.

3) The range indicated corresponds to a scan magnification factor, M_{sc}, i.e. the ratio by which the vertical deviation on the screen is increased, in the approximate range $1.8 < M_{sc} < 2.0$, and the tube should not be operated outside this range. Within this range, line width and screen current at a fixed value of the control grid voltage are increasing functions of M_{sc}. The best compromise between brightness and line width is usually found at $M_{sc} \approx 1.9$ which corresponds to $V_{g9-g2} \approx 310$ V.

4) For minimum defocusing of vertical lines near the upper and lower edges of the scanned area this voltage should be adjusted approximately to the value indicated. Since the value V_{g8-g2} has some effect on the scan magnification factor both V_{g8} and V_{g9} should be connected to g_2 when the deviation without scan magnification is to be measured.

5) This voltage should be adjusted for equal brightness in the x-direction with respect to the electrical centre of the tube.

7) These voltages should be stabilized to within 1 V.

8) This voltage should be adjusted for minimum width of a horizontal line.

9) For a scan magnification factor $M_{sc} = 1.9$.
In the above mentioned range of V_{g9-g2} the vertical deflection factor will vary approximately ± 5%.

10) The sensitivity at a deflection of less than 75 % of the useful scan will not differ from the sensitivity at a deflection of 25 % of the useful scan by more than the indicated value.

11) A ractangle of 98 mm x 58.2 mm is concentrically aligned with the internal graticule of the tube. With optimum corrections applied, the edges of a raster will fall between this rectangle and the boundary lines of the internal graticule.

CORRECTIONS COILS

The tube is provided with a coil unit consisting of:

1. A pair of coils (No.1 and 2), with approx. 220 Ω resistance per coil, for
   a) correction of the orthogonality of the x- and y-traces so that the angle between these traces at the centre of the screen can be made exactly 90°.
   b) vertical shift of the scanned area.
2. A single coil (No.3) with approx. 550 Ω resistance, for image rotation (alignment of the x-trace with the x-lines of the graticule).

Orthogonality and shift

The change in the angle between the traces and the shift of the scanned area will be proportional to the algebraic sum and the algebraic difference of the currents in the coils No.1 and 2.
Under typical operating conditions and with the coil unit closely surrounded by a mu-metal shield, the currents required are max. 5 mA per degree of angle correction and max. 2 mA per millimeter shift. The supply circuit for these coils should be so designed that in each coil a maximum current of 20 mA, with either polarity, can be produced.

If a wider mu-metal shield is used the above-mentioned values have to be multiplied by a factor K ($1 < K < 2$) the value of which depends on the dimensions of the shield and approaches 2 for the case no shield is present.

Image rotation

Under typical operating conditions, a current of max. 45 mA will be required for the alignment.

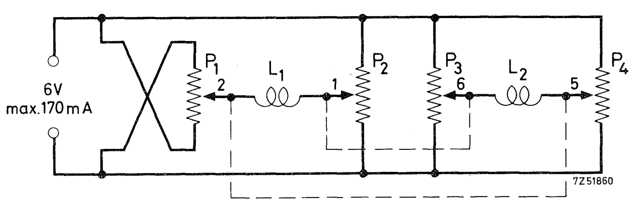


Fig.1

With the above circuit almost independent control for shift and angle correction is achieved. This facilitates the correct adjustment to a great extent.
The dissipation in the potentiometers can be reduced considerably if the requirement of independent controls is dropped.

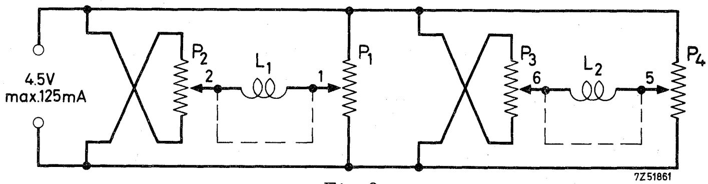


Fig.2

P_1, P_2 potentiometers 220 Ω, 1 watt: ganged
P_3, P_4 potentiometers 220 Ω, 1 watt: ganged

A further reduction of the dissipation can be obtained by providing a commutator for each coil (see circuit fig.3).
The procedure of adjustment will then become more complicated but it should be kept in mind that a readjustment is necessary only when the tube has to be replaced.

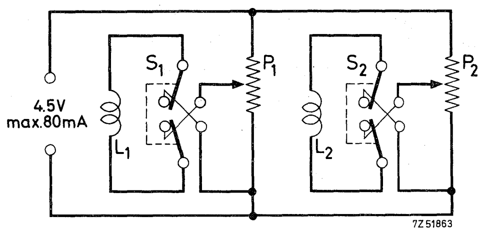


Fig.3

P_1, P_2 potentiometers 220 Ω, 1 watt
S_1, S_2 commutators

A suitable circuit for the image rotating coil is given in fig.4.

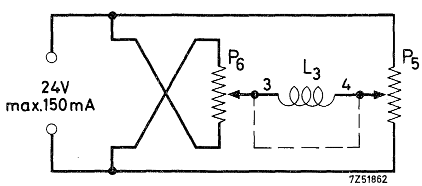


Fig.4

P_5, P_6 potentiometers 500 Ω, 3 watt: ganged

The following procedure of adjustment is recommended

a. Align the x-trace with the graticule by means of the image rotating coil.
b. With the tube fully scanned in the vertical direction, the image has to be shifted so that the graticule is fully covered. With the circuit according to fig.1 this is done by means of the ganged potentiometers P_1 and P_4.
c. Adjustment of orthogonality by means of the ganged potentiometers P_2 and P_3. A slight readjustment of P_1 and P_4 may be necessary afterwards.
d. Readjustment of the image rotation if necessary.

With a circuit according to fig.2 or 3 these corrections have to be performed by means of successive adjustments of the currents in the coils.

The most convenient deflection signal is a square wave form permitting an easy and fairly accurate visual check of orthogonality.

ILLUMINATION OF THE GRATICULE

To illuminate the internal graticule a light conductor (e.g. of perspex) should be used. In order to achieve the most efficient light conductance, the holes for the lamps and the edge adjacent to the tube should be polished, and the distance between the perspex plate and the tube should be as small as possible. It is advisable to apply reflective material to the outer circumference and, if possible, also to the upper and lower faces of the light conductor. The thickness of the conductor should not exceed 3 mm, and its position relative to the frontplate of the tube should be adjusted for optimum illumination of the graticule lines.

INSTRUMENT CATHODE-RAY TUBE

14 cm diagonal, rectangular flat faced oscilloscope tube with mesh and metal backed screen.

QUICK REFERENCE DATA			
Final accelerator voltage	$V_{g7(\ell)}$	10	kV
Display area		100 x 80	mm^2
Deflection coefficient, horizontal	M_x	15,5	V/cm
vertical	M_y	4,2	V/cm

SCREEN: Metal backed phosphor

	Colour	Persistence
D14-120GH	green	medium short

Useful screen area	>	100 x 80	mm^2
Useful scan at $V_{g7(\ell)}/V_{g2,g4} = 6,7$, horizontal	>	100	mm
vertical	>	80	mm
Spot eccentricity in horizontal and vertical directions	<	6	mm

HEATING: Indirect by a.c. or d.c.; parallel supply

Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

MECHANICAL DATA

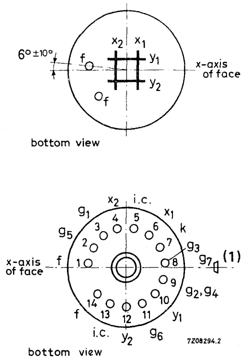
Dimensions and connections

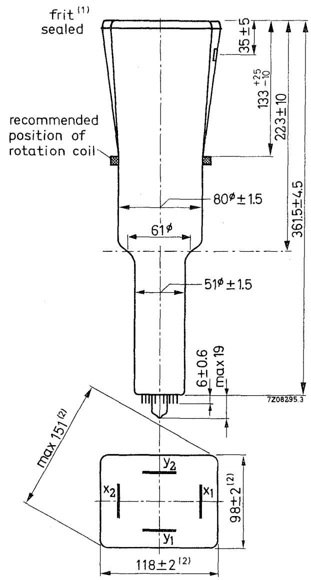
See also outline drawing

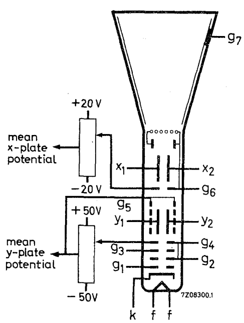
Overall length (socket included)	<	385	mm
Face dimensions	<	100 x 120	mm
Net mass	approx.	900	g

Base 14-pin all-glass

Dimensions in mm







(1) The centre of the contact is located within a square of 10 mm x 10 mm around the true geometrical position.
(2) The bulge at the frit seal may increase the indicated maximum dimensions by not more than 2 mm.

Mounting position any

The tube should not be supported by the base alone; under no circumstances should the socket be allowed to support the tube.

Accessories

Socket (supplied with tube)	type 55566
Final accelerator contact connector	type 55563A
Mu-metal shield	type 55581

FOCUSING	electrostatic
DEFLECTION	double electrostatic
x plates	symmetrical
y plates	symmetrical

If use is made of the full deflection capabilities of the tube the deflection plates will intercept part of the electron beam; hence a low impedance deflection plate drive is desirable.

Angle between x and y traces $90^\circ \pm 1^\circ$

Angle between x trace and the horizontal axis of the face $< 5^\circ$ [1]).

LINE WIDTH

Measured with the shrinking raster method under typical operating conditions, adjusted for optimum spot size at a beam current $I_\ell = 10\ \mu A$.

Line width at the centre of the screen	l.w.		0,40	mm
over the whole screen area	l.w.	av. <	0,45	mm

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	6,5	pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	6,5	pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	5,0	pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	5,0	pF
x_1 to x_2	C_{x1x2}	2,2	pF
y_1 to y_2	C_{y1y2}	1,7	pF
Control grid to all other elements	C_{g1}	5,5	pF
Cathode to all other elements	C_k	4,5	pF

[1]) To align the x trace with the horizontal axis of the screen, the whole picture can be rotated by means of a rotation coil. This coil will have 50 ampere turns for the indicated maximum rotation of 5° and should be positioned as indicated in the drawing.

TYPICAL OPERATING CONDITIONS

Final accelerator voltage	$V_{g7(\ell)}$		10	kV	
Interplate shield voltage	V_{g6}		1500	V	
Geomrty control voltage	ΔV_{g6}		±15	V	1)
Deflection plate shield voltage	V_{g5}		1500	V	2)
Focusing electrode voltage	V_{g3}	250 to	350	V	
First accelerator voltage	$V_{g2,\,g4}$		1500	V	
Astigmatism control voltage	$\Delta V_{g2,\,g4}$		±50	V	3)
Control voltage for visual extinction of focused spot	V_{g1}	-20 to	-60	V	
Grid drive for 10 µA screen current		approx.	12	V	
Deflection coefficient, horizontal	M_x		15,5	V/cm	
		<	16	V/cm	
vertical	M_y		4,2	V/cm	
		<	4,6	V/cm	
Deviation of linearity of deflection		<	2	%	4)
Geometry distortion		See note 5			
Useful scan, horizontal		>	100	mm	
vertical		>	80	mm	

LIMITING VALUES (Absolute max. rating system)

Final accelerator voltage	$V_{g7(\ell)}$	max.	11	kV
		min.	9	kV
Interplate shield voltage and geometry control electrode voltage	V_{g6}	max.	2200	V
Deflection plate shield voltage	V_{g5}	max.	2200	V
Focusing electrode voltage	V_{g3}	max.	2200	V
First accelerator and astigmatism control electrode voltage	$V_{g2,\,g4}$	max.	2200	V
		min.	1350	V
Control grid voltage	$-V_{g1}$	max.	200	V
		min.	0	V
Cathode to heater voltage	V_{kf}	max.	125	V
	$-V_{kf}$	max.	125	V
Voltage between astigmatism control electrode and any deflection plate	$V_{g4/x}$	max.	500	V
	$V_{g4/y}$	max.	500	V
Grid drive, average		max.	20	V
Screen dissipation	W_{ℓ}	max.	8	mW/cm^2
Ratio $V_{g7(\ell)}/V_{g2,\,g4}$	$V_{g7(\ell)}/V_{g4}$	max.	6,7	
Control grid circuit resistance	R_{g1}	max.	1	MΩ

Notes see page 5

Notes

1. This tube is designed for optimum performance when operating at a ratio $V_{g7(\ell)}/V_{g2,\,g4} = 6{,}7$. The geometry electrode voltage should be adjusted within the indicated range (values with respect to the mean x-plate potential). A negative control voltage will cause some pincushion distortion and less background light, a positive control voltage will give some barrel distortion and a slight increase of background light.
2. The deflection plate shield voltage should be equal to the mean y-plate potential. The mean x-plate and y-plate potentials should be equal for optimum spot quality.
3. The astigmatism control electrode voltage should be adjusted for optimum spot shape. For any necessary adjustment its potential will be within the stated range.
4. The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.
5. A graticule, consisting of concentric rectangles of 95 mm x 75 mm and 93 mm x 73,6 mm is aligned with the electrical x-axis of the tube. With optimum correction potentials applied a raster will fall between these rectangles.

INSTRUMENT CATHODE-RAY TUBE

14 cm diagonal, rectangular flat-faced oscilloscope tube with mesh and metal backed screen. The tube has side connections to the x- and y-plates, and is intended for use in transistorized oscilloscopes up to a frequency of 50 MHz.

QUICK REFERENCE DATA			
Final accelerator voltage	$V_{g8(\ell)}$	10	kV
Display area		100 x 80	mm^2
Deflection coefficient, horizontal	M_x	15,5	V/cm
vertical	M_y	4,2	V/cm

SCREEN : Metal backed phosphor

	Colour	Persistence
D14-121GH	green	medium short

Useful screen area	>	100 x 80	mm^2
Useful scan at $V_{g8(\ell)}/V_{g2,g4}$ = 6,7, horizontal	>	100	mm
vertical	>	80	mm
Spot eccentricity in horizontal and vertical directions	<	6	mm

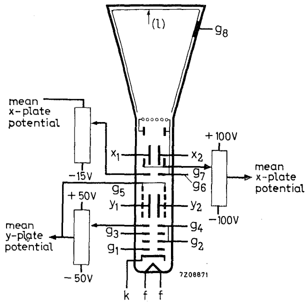
HEATING

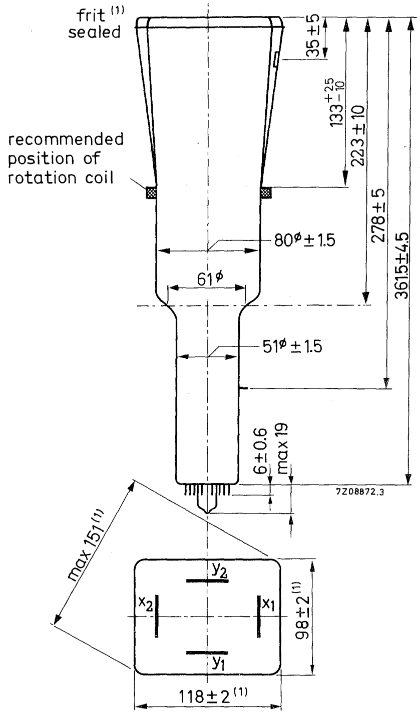
Indirect by a.c. or d.c.; parallel supply

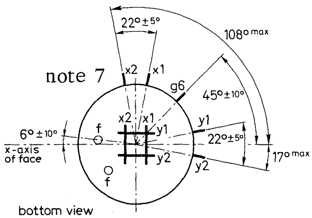
Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

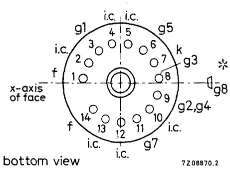
MECHANICAL DATA

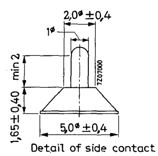
Dimensions in mm











(1) The bulge at the frit seal may increase the indicated maximum dimensions by not more than 2 mm.

* The centre of the contact is located within a square of 10 mm x 10 mm around the true geometrical position.

Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Dimensions and connections

See also outline drawing			
Overall length (socket included)	<	385	mm
Face dimensions	< 100 x	120	mm
Net mass	approx.	900	g
Base	14-pin all glass		

Accessories

Socket (supplied with tube)	type	55566
Final accelerator contact connector	type	55563A
Mu-metal shield	type	55581A

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	5,5	pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	5,5	pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	4	pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	4	pF
x_1 to x_2	C_{x1x2}	2,2	pF
y_1 to y_2	C_{y1y2}	1,7	pF
Control grid to all other elements	C_{g1}	5,5	pF
Cathode to all other elements	C_k	4,5	pF

FOCUSING electrostatic

DEFLECTION double electrostatic

x plates symmetrical

y plates symmetrical

If use is made of the full deflection capabilities of the tube the deflection plates will intercept part of the electron beam; hence a low impedance deflection plate drive is desirable.

Angle between x and y traces $90 \pm 1^{\circ}$

Anglr between x trace and the horizontal axis of the face $< 5^{\circ}$ [1])

LINE WIDTH

Measured with the shrinking raster method under typical operating conditions, adjusted for optimum spot size at a beam current $I_\ell = 10\ \mu A$.

Line width at screen centre	l.w.	0,40	mm
over the whole screen area	l.w. av. <	0,45	mm

Notes see page 5

TYPICAL OPERATING CONDITIONS

Final accelerator voltage	$V_{g8(\ell)}$		10	kV
Geometry-control electrode voltage	V_{g7}		1500 ± 100	V 2)
Post deflection and interplate shield voltage	V_{g6}		1500	V
Background illumination control voltage	ΔV_{g6}		0 to -15	V 2)
Deflection plate shield voltage	V_{g5}		1500	V 3)
Focusing electrode voltage	V_{g3}		250 to 350	V
First accelerator voltage	$V_{g2,g4}$		1500	V
Astigmatism control voltage	$\Delta V_{g2,g4}$		±50	V 4)
Control grid voltage for extinction of focused spot	V_{g1}		−20 to −60	V
Grid drive for 10 μA screen current		approx.	12	V
Deflection coefficient, horizontal	M_x	av.	15,5	V/cm
		<	16	V/cm
vertical	M_y	av.	4,2	V/cm
		<	4,6	V/cm
Deviation of linearity of deflection		<	2	% 5)
Geometry distortion			See note 6	
Useful scan, horizontal		>	100	mm
vertical		>	80	mm

LIMITING VALUES (Absolute max. rating system)

Final accelerator voltage	$V_{g8(\ell)}$	max.	11	kV
		min.	9	kV
Post deflection and interplate shield voltage and geometry control electrode voltage	V_{g7}, V_{g6}	max.	2200	V
Deflection plate shield voltage	V_{g5}	max.	2200	V
Focusing electrode voltage	V_{g3}	max.	2200	V
First accelerator and astigmatism control electrode voltage	$V_{g2,g4}$	max.	2200	V
		min.	1350	V
Control grid voltage	$-V_{g1}$	max.	200	V
		min.	0	V
Cathode to heater voltage	V_{kf}	max.	125	V
	$-V_{kf}$	max.	125	V
Voltage between astigmatism control electrode and any deflection plate	$V_{g4/x}$	max.	500	V
	$V_{g4/y}$	max.	500	V
Grid drive, average		max.	20	V
Screen dissipation	W_ℓ	max.	8	mW/cm^2
Ratio $V_{g8(\ell)}/V_{g2,g4}$	$V_{g8(\ell)}/V_{g2,g4}$	max.	6,7	
Control grid circuit resistance	R_{g1}	max.	1	MΩ

For notes see page 5

NOTES

1) In order to align the x-trace with the horizontal axis of the screen, the whole picture can be rotated by means of a rotation coil. This coil will have 50 amp. turns for the indicated max. rotation of 5^{o} and should be positioned as indicated on the drawing.

2) This tube is designed for optimum performance when operating at a ratio $V_{g8(\ell)}/V_{g2,g4} = 6{,}7$
The geometry control voltage V_{g7} should be adjusted within the indicated range (values with respect to the mean x-plate potential).
A negative control voltage on g_6 (with respect to the mean x-plate potential) will cause some pincushion distortion and less background light.
By the use of the two voltages, V_{g6} and V_{g7}, it is possible to find the best compromise between background light and raster distortion.

3) The deflection plate shield voltage should be equal to the mean y-plate potential. The mean x- and y-plate potentials should be equal for optimum spot quality.

4) The astigmatism control electrode voltage should be adjusted for optimum spot shape. For any necessary adjustment its potential will be within the stated range.

5) The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.

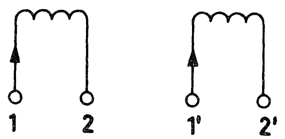
6) A graticule, consisting of concentric rectangles of 95 mm x 75 mm and 93 mm x 73,6 mm is aligned with the electrical x axis of the tube. With optimum correction potentials applied a raster will fall between these rectangles.

7) To avoid damage to the side contacts the narrower end of the Mu-metal shield should have an internal diameter of not less than 64 mm.

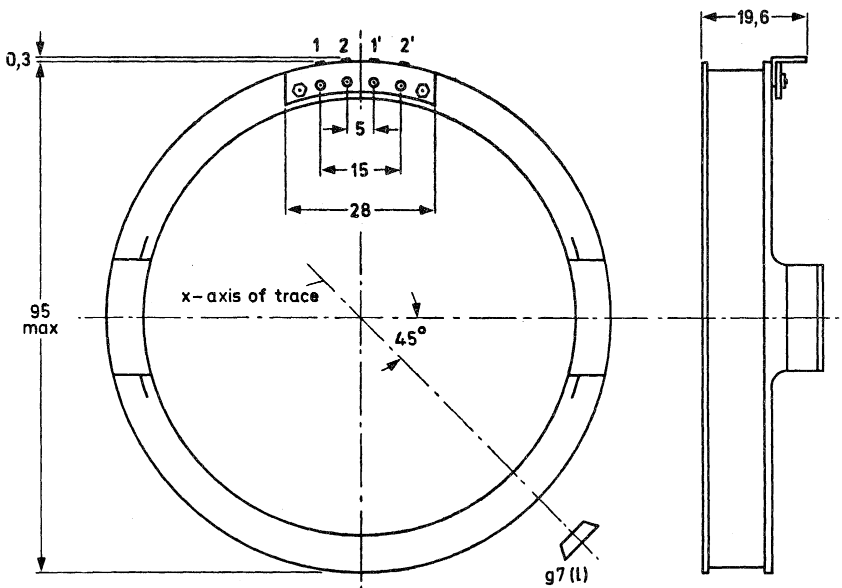
INSTRUMENT CATHODE-RAY TUBE

This type is equivalent with type D14-120GH but provided with a rotation coil as indicated in note 1 of D14-120GH.

COIL



Number of turns	1 - 2	850	turns
	1' - 2'	850	turns
Resistance of coils	1 - 2	360	Ω + 10 %
	1' - 2'	375	Ω 10 %



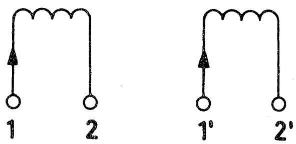
base view

7Z66593.1

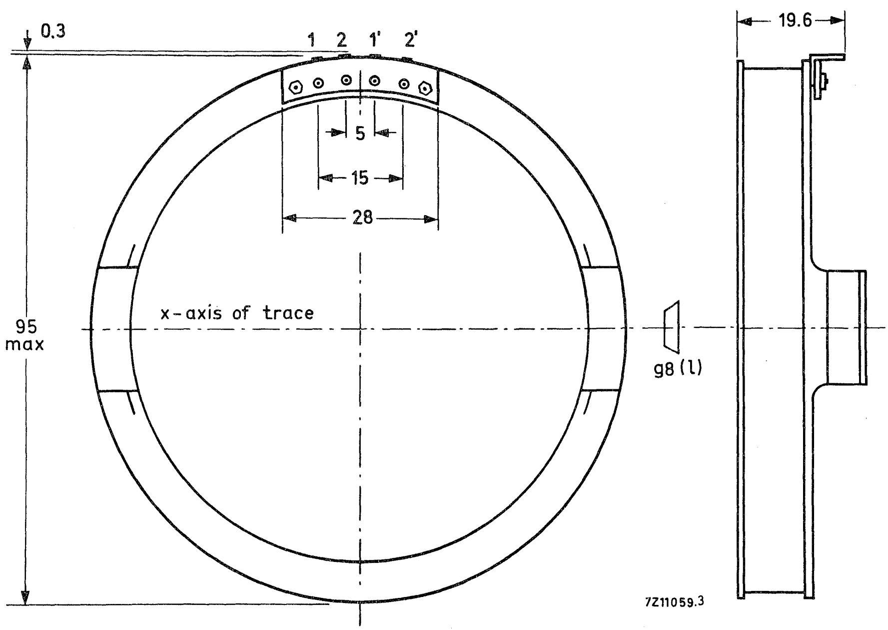
INSTRUMENT CATHODE-RAY TUBE

This type is equivalent with type D14-121GH but provided with a rotation coil as indicated in note 1 of D14-121GH.

COIL



Number of turns	1 -2	850 turns
	1'-2'	850 turns
Resistance of coils	1 -2	360 Ω (±10 %)
	1'-2'	375 Ω (±10 %)



base view

INSTRUMENT CATHODE-RAY TUBE

14 cm diagonal, rectangular flat faced oscilloscope tube with mesh and metal-backed screen. The tube has side connections to the x and y-plates and an internal graticule.

QUICK REFERENCE DATA			
Final accelerator voltage	$V_{g8(\ell)}$	10	kV
Display area		100 x 80	mm^2
Deflection coefficient, horizontal	M_x	15,2	V/cm
vertical	M_y	4,1	V/cm

SCREEN : Metal-backed phosphor

	Colour	Persistence
D14-162GH/09	green	medium-short

Useful screen area	>	100 x 80	mm^2
Useful scan at $V_{g8(\ell)}/V_{g2,g4} = 6,7$, horizontal	>	100	mm
vertical	>	80	mm
Spot eccentricity in horizontal direction	<	6	mm

The x-trace can be aligned with the x-lines of the graticule by means of correction coils fitted around the tube by the manufacturer (see page 5).

HEATING : Indirect by a.c. or d.c.; parallel supply

Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

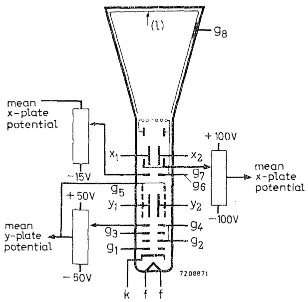
MECHANICAL DATA

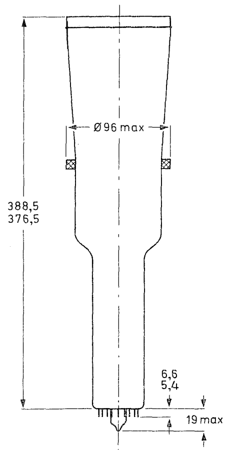
Dimensions and connections

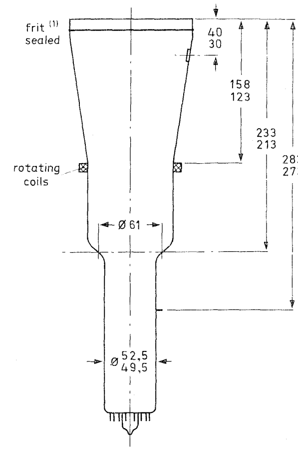
See also outline drawing

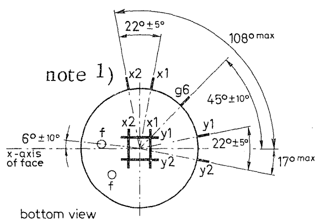
Overall length (socket included)	<	407,5	mm
Face dimensions	<	100 x 120	mm
Net mass	approx.	1200	g

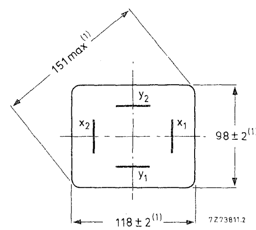
Dimensions in mm

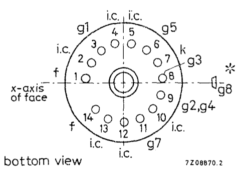


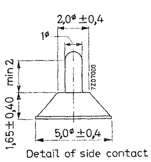


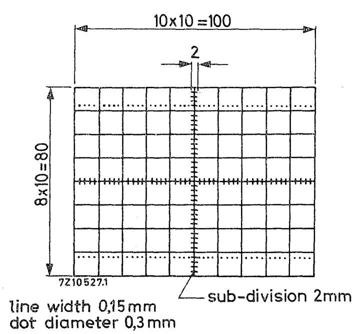












(1) The bulge at the frit seal may increase the indicated maximum dimensions by not more than 2 mm.

* The centre of the contact is situated within a square of 10 mm x 10 mm around the true geometrical position.

Base		14 pin all glass	

Mounting position : any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Accessories

Socket (supplied with tube)	type	55566	
Final accelerator contact connector	type	55563A	
Mu-metal shield	type	55585	[1])

FOCUSING	electrostatic
DEFLECTION	double electrostatic
x-plates	symmetrical
y-plates	symmetrical

If use is made of the full deflection capabilities of the tube the deflection plates will intercept part of the electron beam; hence a low impedance deflection plate drive is desirable.

Angle between x and y-traces $90^{\circ} \pm 1^{\circ}$

Angle between x-trace and the horizontal axis of the face 0° See page 5 "Correction coils"

LINE WIDTH

Measured with the shrinking raster method in the centre of the screen under typical operating conditions, adjusted for optimum spot size at a beam current $I_{\ell} = 10\ \mu A$.

Line width at the centre of the screen	l.w.	0,3	mm

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	5,5	pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	5,5	pF
y_1 to all other elements except y_2	$C_{y1(y1)}$	3,5	pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	3,5	pF
x_1 to x_2	C_{x1x2}	2	pF
y_1 to y_2	C_{y1y2}	1,6	pF
Control grid to all other elements	C_{g1}	5,5	pF
Cathode to all other elements	C_k	4	pF

[1]) See page 5.

TYPICAL OPERATING CONDITIONS

Final accelerator voltage	$V_{g8(\ell)}$	10	kV	
Geometry control electrode voltage	V_{g7}	1500 ± 100	V	2)
Post deflection and interplate shield voltage	V_{g6}	1500	V	
Background illumination control voltage	ΔV_{g6}	0 to -15	V	2)
Deflection plate shield voltage	V_{g5}	1500	V	3)
Focusing electrode voltage	V_{g3}	450 to 550	V	
First accelerator voltage	$V_{g2, g4}$	1500	V	
Astigmatism control voltage	$\Delta V_{g2, g4}$	±50	V	4)
Control grid voltage for visual extinction of focused spot	V_{g1}	-30 to -70	V	
Grid drive for 10 μA screen current		approx. 20	V	
Deflection coefficient, horizontal	M_x	15,2	V/cm	
		< 16	V/cm	
vertical	M_y	4,1	V/cm	
		< 4,4	V/cm	
Deviation of linearity of deflection		< 2	%	5)
Geometry distortion		See note 6		
Useful scan, horizontal		> 100	mm	
vertical		> 80	mm	

LIMITING VALUES (Absolute max. rating system)

Final accelerator voltage	$V_{g8(\ell)}$	max.	12	kV
		min.	9	kV
Post deflection and interplate shield voltage and geometry control electrode voltage	V_{g7}, V_{g6}	max.	2200	V
Deflection plate shield voltage	V_{g5}	max.	2200	V
Focusing electrode voltage	V_{g3}	max.	2200	V
First accelerator and astigmatism control electrode voltage	$V_{g2, g4}$	max.	2200	V
		min.	1350	V
Control grid voltage	$-V_{g1}$	max.	200	V
		min.	0	V
Cathode to heater voltage	V_{kf}	max.	125	V
	$-V_{kf}$	max.	125	V
Voltage between astigmatism control electrode and any deflection plate	$V_{g4/x}$	max.	500	V
	$V_{g4/y}$	max.	500	V
Grid drive, average		max.	30	V
Screen dissipation	W_ℓ	max.	8	mW/cm^2
Ratio $V_{g8(\ell)}/V_{g2, g4}$	$V_{g8(\ell)}/V_{g2, g4}$	max.	6,7	
Control grid circuit resistance	R_{g1}	max.	1	MΩ

Notes see page 5.

NOTES

1) To avoid damage to the side contacts the narrower end of the mu-metal shield should have an internal diameter of not less than 64 mm.

2) This tube is designed for optimum performance when operating at a ratio $V_{g8(\ell)}/V_{g2g4}$ $V_{g8(\ell)}/V_{g2,g4} = 6,7$.
The geometry control voltage V_{g7} should be adjusted within the indicated range (values with respect to the mean x-plate potential).
A negative control voltage on g_6 (with respect to the mean x-plate potential) will cause some pincushion distortion and less background light.
By the use of two voltages, V_{g6} and V_{g7}, it is possible to find the best compromise between background light and raster distortion.
If a fixed voltage on V_{g6} is required this voltage should be 10 V lower than the mean x-plate potential.

3) The deflection plate shield voltage should be equal to the mean y-plate potential.
The mean x and y-plate potentials should be equal for optimum spot quality.

4) The astigmatism control electrode voltage should be adjusted for optimum spot shape. For any necessary adjustment its potential will be within the stated range.

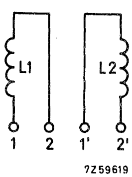
5) The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.

6) A graticule, consisting of concentric rectangles of 95 mm x 75 mm and 93 mm x 73,6 mm is aligned with the electrical x-axis of the tube. With optimum corrections applied a a raster will fall between these rectangles.

CORRECTION COILS

General

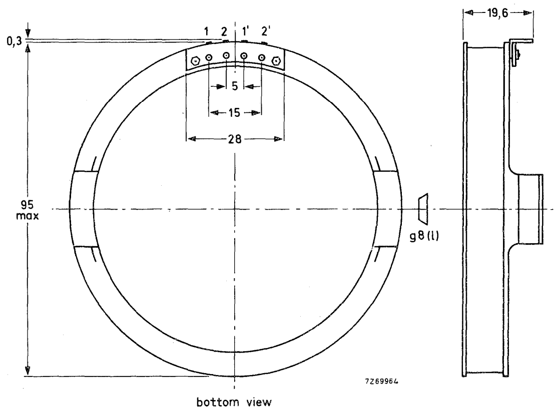
The D14-1626H/09 is provided with a pair of coils L1 and L2 for image rotation which enable the alignment of the x-trace with the x-lines of the graticule.



The image rotation coils are wound concentrically around the tube neck.
Under typical operating conditions 50 ampere-turns are required for the maximum rotation of 5°. Both coils have 850 turns. This means that a current of < 30 mA per coil is required which can be obtained by using a 24 V supply when the coils are connected in series, or a 12 V supply when they are in parallel.

Connecting the coils

The coils have been connected to the 4 soldering tags as follows:



INSTRUMENT CATHODE-RAY TUBE

14 cm diagonal rectangular flat-faced oscilloscope tube with domed post-deflection acceleration mesh, sectioned y-plates, and metal-backed screen with internal graticule.

QUICK REFERENCE DATA			
Final accelerator voltage	$V_{g9(\ell)}$	20	kV
Display area		100 x 80	mm^2
Deflection coefficient, horizontal	M_x	9	V/cm
vertical	M_y	3	V/cm

SCREEN

Metal-backed phosphor

	colour	persistence
D14-240GH/37	green	medium short

Useful screen dimensions	>	100 x 80	mm
Spot eccentricity in horizontal and vertical directions	<	6	mm

HEATING

Indirect by a.c. or d.c.; parallel supply

Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

MECHANICAL DATA

Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Dimensions and connections

See also outline drawing

Overall length (socket included)	<	385	mm
Face dimensions	<	120 x 100	mm

MECHANICAL DATA (continued)

Net mass	≈ 900 g
Base	14 pin, all glass
Accessories	
Socket (supplied with tube)	type 55566
Side contact connector (12 required)	type 55561
Final accelerator contact connector	note [1])
Mu-metal shield	note [2])

FOCUSING	electrostatic
DEFLECTION	double electrostatic
x-plates	symmetrical
y-plates	symmetrical
Angle between x and y traces	90°
Angle between x-trace and x-axis of the internal graticule	0°

See also "Correction coils"

If use is made of the full deflection capabilities of the tube the deflection plates will intercept part of the electron beam; hence a low impedance deflection plate drive is desirable.

CAPACITANCES

x_1 to all other elements except x_2	$C_{x_1(x_2)}$	4,5	pF
x_2 to all other elements except x_1	$C_{x_2(x_1)}$	4,5	pF
$y_{1.1}$ to all other elements except $y_{2.1}$	$C_{y_{1.1}(y_{2.1})}$	1,3	pF
$y_{2.1}$ to all other elements except $y_{1.1}$	$C_{y_{2.1}(y_{1.1})}$	1,3	pF
x_1 to x_2	$C_{x_1x_2}$	3	pF
$y_{1.1}$ to $y_{2.1}$	$C_{y_{1.1}y_{2.1}}$	0,7	pF
Control grid to all other elements	C_{g_1}	5,5	pF
Cathode to all other elements	C_k	4,5	pF

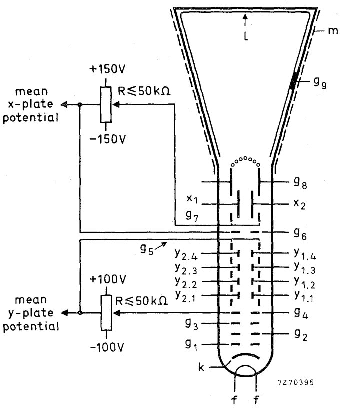
---

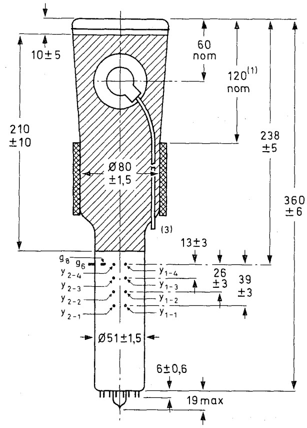
[1]) The connection to the final accelerator electrode is made by means of an EHT cable attached to the tube.

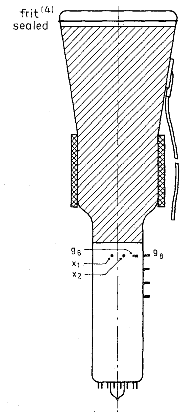
[2]) The diameter of the mu-metal shield should be large enough to avoid damage to the side contacts.

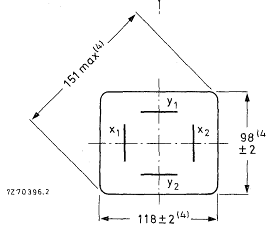
DIMENSIONS AND CONNECTIONS

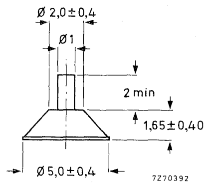
Dimensions in mm



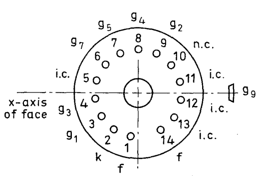




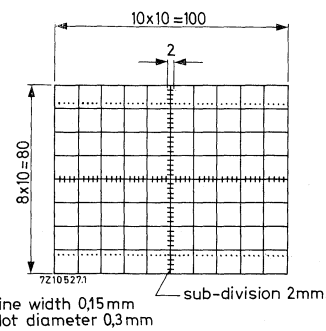


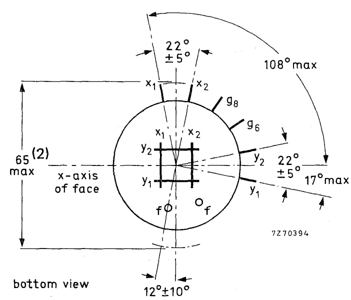


detail of side contact



bottom view





bottom view

(1) Recommended position of correction coils.
(2) See page 2.
(3) Length of cable approx. 460 mm.
(4) The bulge at the frit seal may increase the indicated maximum dimensions by not more than 2 mm.

TYPICAL OPERATION

Conditions

Final accelerator voltage	$V_{g9(\ell)}$	20	kV	
Post deflection accelerator mesh electrode voltage	V_{g8}	2000	V	
Geometry control electrode voltage	V_{g7}	2000 ± 150	V	1)
Interplate shield voltage	V_{g6}	2000	V	2)
Deflection plate shield voltage	V_{g5}	2000	V	3)
Astigmatism control electrode voltage	V_{g4}	2000 ± 100	V	4)
Focusing electrode voltage	V_{g3}	500 to 800	V	
First accelerator voltage	V_{g2}	2000	V	
Control grid voltage for visual extinction of focused spot	V_{g1}	-55 to -110	V	
Voltage on outer conductive coating	V_m	2000	V	

Performance

Useful scan, horizontal		>	100	mm	5)
vertical		>	80	mm	
Deflection coefficient, horizontal	M_x		9	V/cm	
		<	9,9	V/cm	
vertical	M_y		3	V/cm	
		<	3,3	V/cm	
Line width		≈	0,45	mm	6)
Writing speed		>	1,5	cm/ns	7)
Deviation of linearity of deflection			see note 8	%	
Geometry distortion			see note 9		
Grid drive for 10 μA screen current		≈	20	V	

1) The geometry control electrode voltage V_{g7} should be adjusted within the indicated range (values with respect to the mean x-plate potential).

2) The interplate shield voltage should be equal to the mean x-plate potential.

3) The deflection plate shield voltage should be equal to the mean y-plate potential. The mean x-plate and y-plate potentials should be equal for optimum performance.

4) The astigmatism control electrode voltage should be adjusted for optimum spot shape. For any necessary adjustment its potential will be within the stated range.

5) If the tube is operated at a ratio $V_{g9(\ell)}/V_{g5} < 10$, the useful scan may be smaller than 100 mm x 80 mm.
The scanned raster can be shifted and aligned with the internal graticule by means of correction coils fitted around the tube.

LIMITING VALUES (Absolute maximum rating system)

Final accelerator voltage	$V_{g9(\ell)}$	max.	21	kV
		min.	15	kV
Post deflection acceleration mesh electrode voltage	V_{g8}	max.	2200	V
Geometry control electrode voltage	V_{g7}	max.	2400	V
Interplate shield voltage	V_{g6}	max.	2200	V
Deflection plate shield voltage	V_{g5}	max.	2200	V
Astigmatism control electrode voltage	V_{g4}	max.	2300	V
		min.	1800	V
Focusing electrode voltage	V_{g3}	max.	2200	V
First accelerator voltage	V_{g2}	max.	2200	V
		min.	1900	V
Control grid voltage	$-V_{g1}$	max.	200	V
		min.	0	V
Cathode to heater voltage				
positive	V_{kf}	max.	125	V
negative	$-V_{kf}$	max.	125	V
Voltage between astigmatism control electrode and any deflection plate	$V_{g4/x}$	max.	500	V
	$V_{g4/y}$	max.	500	V
Grid drive, average		max.	30	V
Screen dissipation	W_ℓ	max.	8	mW/cm^2
Ratio V_{g9}/V_{g5}	V_{g9}/V_{g5}	max.	10	
		min.	8	
Control grid circuit resistance	R_{g1}	max.	1	MΩ

6. Measured with the shrinking raster method in the centre of the screen, with corrections adjusted for optimum spot size, at a beam current of 10 μA.
7. Writing speed measuring conditions:

Film	Polaroid 410 (10 000 ASA)
Lens	F 1/1,2
Object to image ratio	1/0,5
Modulation	$\Delta V_{g1} = 55$ V

8. The deflection coefficient over each division will not differ more than 5% from that over any other division; all these deflection coefficients being measured per division along the axes.
9. A graticule consisting of concentric rectangles of 95 mm x 75 mm and 93 mm x 73,6 mm is aligned with the electrical x-axis of the tube. With optimum corrections applied, the edges of a raster will fall between these rectangles.

CORRECTION COILS

On request a correction coil unit can be made available consisting of:

1. a pair of coils L1 and L2 which enable the angle between the x and y traces at the centre of the sceen to be made exactly 90^{o} (orthogonality correction).
2. a pair of coils L3 and L4 which enable the scanned area to be shifted up and down (vertical shift).
3. a coil L5 for image rotation which enables the alignment of the x trace with the x lines of the graticule.

Orthogonality (coils L1 and L2)

The current required under typical operating conditions with mu-metal shield being used is < 8 mA for complete correction of orthogonality.
The resistance of each coil is ≈ 160 Ω.

Shift (coils L3 and L4)

The current required under typical operating conditions with mu-metal shield being used is < 12 mA for a maximum shift of 5 mm.
The resistance of each coil is ≈ 160 Ω.

Image rotation (coil L5)

The image rotation coil is wound concentrically around the tube neck. Under typical operating conditions 27 ampere-turns are required for the maximum rotation of 5^{o}.
The coil has 1560 turns. This means that a current of < 18 mA is required.
The resistance of the coil is ≈ 185 Ω.

INSTRUMENT CATHODE-RAY TUBE

14 cm diagonal rectangular flat-faced monoaccelerator oscilloscope tube primarily for use in inexpensive oscilloscopes and read-out devices. This tube features a low heater power consumption.

QUICK REFERENCE DATA

Accelerator voltage	$V_{g2,\,g4,\,g5\,(\ell)}$	2000 V
Display area		100 mm x 80 mm
Deflection coefficient		
horizontal	M_x	23 V/cm
vertical	M_y	13,5 V/cm

The D14—251GH is equivalent to the type D14—252GH except for the following.

HEATING

Indirect by a.c. or d.c. *

Heater voltage	V_f	6,3 V
Heater current	I_f	95 mA

LIMITING VALUES (Absolute maximum rating system)

Cathode to heater voltage			
positive	V_{kf}	max.	100 V
negative	$-V_{kf}$	max.	15 V

CAPACITANCES

Cathode to all other elements	C_k	2,5 pF

* Not to be connected in series with other tubes.

INSTRUMENT CATHODE-RAY TUBE

14 cm diagonal rectangular flat-faced monoaccelerator oscilloscope tube primarily for use in inexpensive oscilloscopes and read-out devices. This tube features a 1,5 W cathode with short warm-up time (quick-heating cathode).

QUICK REFERENCE DATA

Accelerator voltage	$V_{g2, g4, g5 (\ell)}$	2000 V
Display area		100 mm x 80 mm
Deflection coefficient		
horizontal	M_x	23 V/cm
vertical	M_y	13,5 V/cm

OPTICAL DATA

Screen		
phosphor type		GH, colour green
persistence		medium short
Useful screen dimensions		⩾ 100 mm x 80 mm
Useful scan		
horizontal	⩾	100 mm
vertical	⩾	80 mm
Spot eccentricity in horizontal and vertical directions	<	7 mm

HEATING

Indirect by a.c. or d.c. *

Heater voltage	V_f	6,3 V
Heater current	I_f	240 mA

MECHANICAL DATA

Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Net mass approx. 1 kg

Base 14-pin all glass

* Not to be connected in series with other tubes.

Dimensions and connections

See also outline drawing

Overall length (socket included)	$\leqslant$	333 mm
Face dimensions	$\leqslant$	121 x 100 mm

Accessories

Socket (supplied with tube)	type 55566
Mu-metal shield	type 55590

FOCUSING	electrostatic

DEFLECTION	double electrostatic
x-plates	symmetrical
y-plates	symmetrical

If use is made of the full deflection capabilities of the tube the deflection plates will block part of the electron beam; hence a low impedance deflection plate drive is desirable.

Angle between x and y-traces	$90^{\circ} \pm 1^{\circ}$
Angle between x-trace and horizontal axis of the face	see footnote

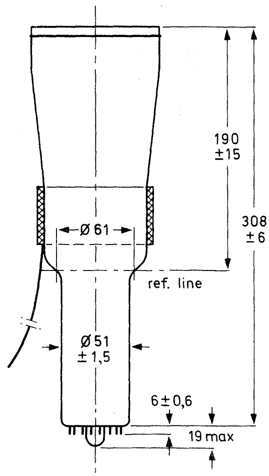
CAPACITANCES

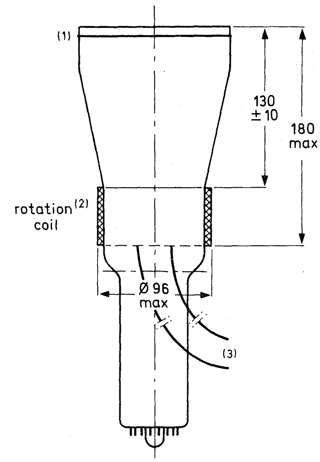
x_1 to all other elements except x_2	$C_{x1(x2)}$	4,5 pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	4,5 pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	3,5 pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	3 pF
x_1 to x_2	C_{x1x2}	2 pF
y_1 to y_2	C_{y1y2}	1,1 pF
Control grid to all other elements	C_{g1}	6 pF
Cathode to all other elements	C_k	2,7 pF

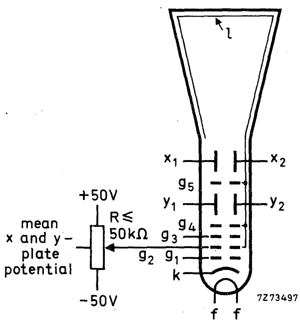
Note
The tube is provided with a rotation coil, concentrically wound around the tube neck, enabling the alignment of the x-trace with the mechanical x-axis of the screen. The coil has 1000 turns and a resistance of max. 400 Ω. Under typical operating conditions, max. 30 ampere-turns are required for the max. rotation of 5°. This means the required current is max. 30 mA at a required voltage of max. 12 V.

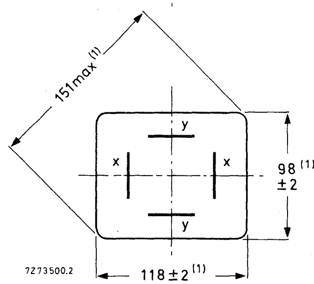
DIMENSIONS AND CONNECTIONS

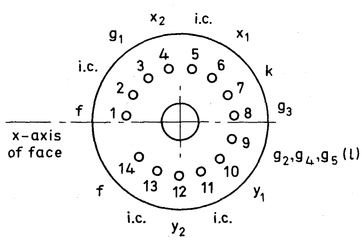
Dimensions in mm

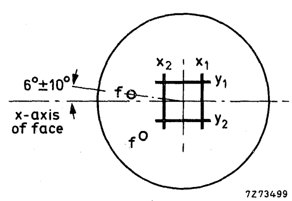












(1) The bulge at the frit seal may increase the indicated maximum dimensions by not more than 2 mm.
(2) The coil is fixed to the envelope by means of adhesive tape.
(3) The length of the connecting leads of the rotation coil is min. 350 mm.

TYPICAL OPERATION

Conditions (note 1)

Accelerator voltage	$V_{g2, g4, g5(\ell)}$		2000 V	
Astigmatism control voltage	$\Delta V_{g2, g4, g5(\ell)}$		± 50 V	(note 2)
Focusing electrode voltage	V_{g3}		220 to 370 V	
Control grid voltage for visual extinction of focused spot	V_{g1}	⩽	−65 V	

Performance

Useful scan				
horizontal		⩾	100 mm	
vertical		⩾	80 mm	
Deflection coefficient				
horizontal	M_x		23 V/cm	
		<	25 V/cm	
vertical	M_y		13,5 V/cm	
		<	15 V/cm	
Line width	l.w.	≈	0,35 mm	(note 3)
Deviation of linearity of deflection		⩽	2 %	(note 4)
Geometry distortion		see note 5		
Grid drive for 10 μA screen current		≈	10 V	

NOTES

1. The mean x-plate potential and the mean y-plate potential should be equal to $V_{g2,g4,g5(\ell)}$ (with astigmatism control voltage set to zero).
2. When putting the tube into operation the astigmatism control voltage should be adjusted only once for optimum spot size in the centre of the screen. The control voltage will be within the stated range, provided the conditions of note 1 are adhered to.
3. Measured with the shrinking raster method in the centre of the screen under typical operating conditions, adjusted for optimum spot size at a beam current $I_\ell = 10\ \mu$A.

   As the construction of the tube does not permit a direct measurement of the beam current, this current should be determined as follows:
   a) under typical operating conditions, apply a small raster display (no overscan), adjust V_{g1} for a beam current of approx. 10 μA and adjust V_{g3} and $V_{g2,g4,g5(\ell)}$ for optimum spot quality at the centre of the screen.
   b) under these conditions, but without raster, the deflection plate voltages should be changed to: $V_{y1} = V_{y2} = 2000$ V; $V_{x1} = 1300$ V; $V_{x2} = 1700$ V, thus directing the total beam current to x_2. Measure the current on x_2 and adjust V_{g1} for $I_{x2} = 10\ \mu$A.
   c) set again for the conditions under a), without touching the V_{g1} control. The screen current of the resulting raster display is now 10 μA.
   d) focus optimally in the centre of the screen (do not adjust the astigmatism control) and measure the line width.
4. The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.
5. A graticule consisting of concentric rectangles of 95 mm x 75 mm and 93 mm x 73 mm is aligned with the electrical x-axis of the tube. With optimum correction potentials applied a raster will fall between these rectangles.

LIMITING VALUES (Absolute maximum rating system)

Accelerator voltage	$V_{g2, g4, g5(\ell)}$	max.	2200	V
		min.	1500	V
Focusing electrode voltage	V_{g3}	max.	2200	V
Control grid voltage	$-V_{g1}$	max.	200	V
		min.	0	V
Cathode to heater voltage				
positive	V_{kf}	max.	125	V
negative	$-V_{kf}$	max.	125	V
Grid drive, average		max.	20	V
Screen dissipation	W_{ℓ}	max.	3	mW/cm^2
Control grid circuit resistance	R_{g1}	max.	1	MΩ

INSTRUMENT CATHODE-RAY TUBE

14 cm diagonal, rectangular flat faced oscilloscope tube with post-deflection acceleration mesh, primarily for use in compact oscilloscopes with 15 to 20 MHz bandwidth. This tube features a low heater consumption.

QUICK REFERENCE DATA

Final accelerator voltage	$V_{g7(\ell)}$	4	kV
Display area		100 mm x 80	mm
Deflection coefficient			
horizontal	M_x	19,5	V/cm
vertical	M_y	10,5	V/cm

The D14-261GH is equivalent to the type D14-262GH except for the following.

HEATING

Indirect by a.c. or d.c. *

Heater voltage	V_f	6,3	V
Heater current	I_f	95	mA

LIMITING VALUES (Absolute maximum rating system)

Cathode to heater voltage				
positive	V_{kf}	max.	100	V
negative	$-V_{kf}$	max.	15	V

CAPACITANCES

Cathode to all other elements	C_k	2,5	pF

* Not to be connected in series with other tubes.

INSTRUMENT CATHODE-RAY TUBE

14 cm diagonal, rectangular flat-faced oscilloscope tube with post-deflection acceleration mesh, primarily for use in compact oscilloscopes with 15 to 20 MHz bandwidth. This tube features a 1,5 W cathode with short warm-up time (quick-heating cathode).

QUICK REFERENCE DATA

Final accelerator voltage	$V_{g7(\ell)}$	4	kV
Display area		100 mm x 80	mm
Deflection coefficient			
horizontal	M_x	19,5	V/cm
vertical	M_y	10,5	V/cm

OPTICAL DATA

Screen			
phosphor type	GH, colour green		
persistence	medium short		
Useful screen dimensions	⩾	100 mm x 80	mm
Useful scan			
horizontal	⩾	100	mm
vertical	⩾	80	mm
Spot eccentricity in horizontal and vertical directions	⩽	6,5	mm

HEATING

Indirect by a.c. or d.c.*

Heater voltage	V_f	6,3	V
Heater current	I_f	240	mA

MECHANICAL DATA

Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Net mass	approx. 1 kg
Base	14-pin, all glass
Final accelerator contact	small ball

* Not to be connected in series with other tubes.

Dimensions and connections

See also outline drawing

Overall length	⩽	333 mm
Face dimensions	⩽	100 x 120 mm^2

Accessories

Socket, supplied with tube	type 55566
Mu-metal shield	type 55591
Final accelerator contact connector	type 55569

FOCUSING		electrostatic
DEFLECTION		double electrostatic
x-plates		symmetrical
y-plates		symmetrical
Angle between x and y-traces		$90 \pm 1^\circ$
Angle between x-trace and horizontal axis of the face	⩽	5° *

If use is made of the full deflection capabilities of the tube the deflection plates will block part of the electron beam, hence a low impedance deflection plate drive is desirable.

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	7 pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	6,5 pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	4 pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	3,5 pF
x_1 to x_2	C_{x1x2}	2,2 pF
y_1 to y_2	C_{y1y2}	1,1 pF
Control grid to all other elements	C_{g1}	6,1 pF
Cathode to all other elements	C_k	2,7 pF

* The tube is provided with a rotation coil, concentrically wound around the tube neck, enabling the alignment of the x-trace with the mechanical x-axis of the screen. The coil has 1000 turns and a resistance of max. 400 Ω. Under typical operating conditions, max. 30 ampere-turns are required for the max. rotation of 5°. This means the required current is max. 30 mA at a required voltage of max. 12 V.

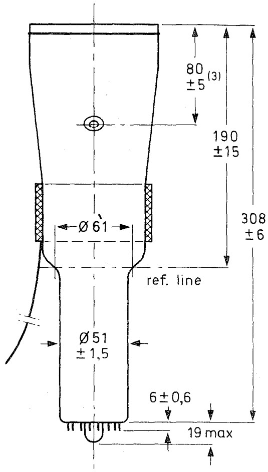
Notes to the drawings on opposite page.

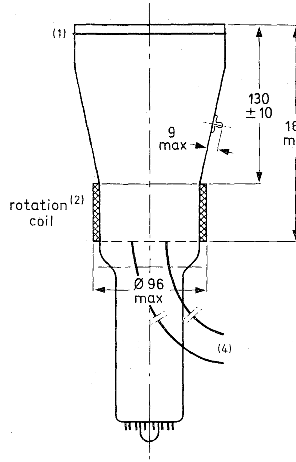
1. The bulge at the frit seal may increase the indicated maximum dimensions by not more than 2 mm.
2. The coil is fixed to the envelope by means of adhesive tape.
3. The centre of the contact is situated within a square of 10 mm x 10 mm around the true geometrical position.
4. The length of the connecting leads of the rotation coil is min. 350 mm.

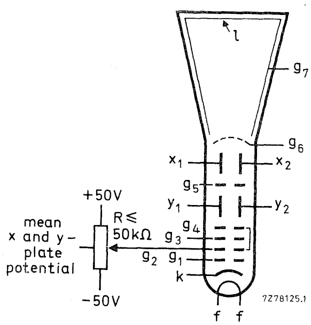
DIMENSIONS AND CONNECTIONS

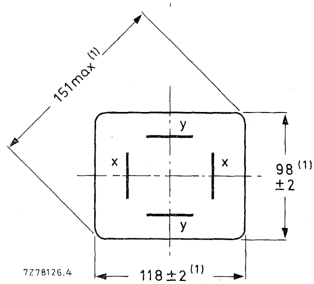
Dimensions in mm

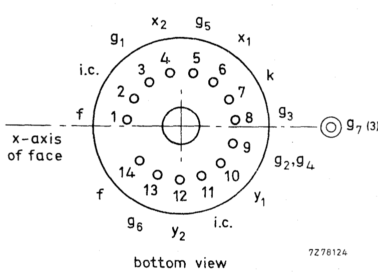
For notes to the drawings see bottom of opposite page.

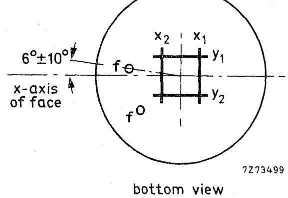












TYPICAL OPERATION

Conditions

Final accelerator voltage	$V_{g7(\ell)}$	4 kV	
Post deflection accelerator mesh electrode voltage	V_{g6}	2000 V	
Interplate shield voltage	V_{g5}	2000 V	(note 1)
First accelerator voltage	$V_{g2, g4}$	2000 V	
Astigmatism control electrode voltage	$\Delta V_{g2, g4}$	± 50 V	(note 2)
Focusing electrode voltage	V_{g3}	300 to 480 V	
Cut-off voltage for visual extinction of focused spot	$-V_{g1}$	30 to 70 V	

Performance

Useful scan				
horizontal		⩾	100 mm	(note 3)
vertical		⩾	80 mm	(note 3)
Deflection coefficient				
horizontal	M_x		19,5 V/cm	
		⩽	21,5 V/cm	
vertical	M_y		10,5 V/cm	
		⩽	11,6 V/cm	
Line width	l.w.	≈	0,35 mm	(note 4)
Deviation of deflection linearity		⩽	2 %	(note 5)
Grid drive for 10 μA screen current	V_d	≈	20 V	
Geometry distortion	see note 6			

NOTES

1. The interplate shield voltage should be equal to the mean x-plate potential. The mean x-plate and y-plate potentials should be equal for optimum spot quality.
2. The astigmatism control electrode voltage should be adjusted for optimum spot shape. For any necessary adjustment its potential will be within the stated range.
3. The tube is designed for optimum performance when operating at a ratio $V_{g7(\ell)}/V_{g2, g4} = 2$. If this ratio is smaller than 2, the useful scan may be smaller than 100 mm x 80 mm.
4. Measured with the shrinking raster method in the centre of the screen with corrections adjusted for optimum spot size, at a beam current of 10 μA.
5. The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.
6. A graticule consisting of concentric rectangles of 95 mm x 75 mm and 93 mm x 73 mm is aligned with the electrical x-axis of the tube. With optimum corrections applied, the edges of a raster will fall between these rectangles.

LIMITING VALUES (Absolute maximum rating system)

Final accelerator voltage	$V_{g7(\ell)}$	max.	4,4	kV
Post deflection accelerator mesh electrode voltage	V_{g6}	max.	2200	V
Interplate shield voltage	V_{g5}	max.	2200	V
First accelerator and astigmatism control electrode voltage	$V_{g2,\,g4}$	max.	2200	V
		min.	1500	V
Focusing electrode voltage	V_{g3}	max.	2200	V
Control grid voltage	$-V_{g1}$	max.	200	V
		min.	0	V
Cathode to heater voltage				
positive	V_{kf}	max.	125	V
negative	$-V_{kf}$	max.	125	V
Grid drive, averaged over 1 ms	V_d	max.	20	V
Screen dissipation	W_{ℓ}	max.	3	mW/cm^2
Control grid circuit resistance	R_{g1}	max.	1	MΩ

INSTRUMENT CATHODE-RAY TUBE

14 cm diagonal rectangular flat-faced oscilloscope tube with domed post-deflection acceleration mesh and metal-backed screen, primarily for use in compact oscilloscopes with 25 to 50 MHz bandwidth. This tube features a 1,5 W cathode with short warm-up time (quick-heating cathode).

QUICK REFERENCE DATA

Final accelerator voltage	$V_{g8(\ell)}$	10	kV
Display area		100 mm x 80	mm
Deflection coefficient			
horizontal	M_x	12,8	V/cm
vertical	M_y	6,3	V/cm

OPTICAL DATA

Screen	metal-backed phosphor	
phosphor type	GH, colour green	
persistence	medium short	
Useful screen dimensions	⩾100 mm x 80 mm	
Useful scan		
horizontal	⩾	100 mm
vertical	⩾	80 mm
Spot eccentricity in horizontal and vertical directions	⩽	6,5 mm

HEATING

Indirect by a.c. or d.c.*

Heater voltage	V_f	6,3	V
Heater current	I_f	240	mA

MECHANICAL DATA

Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Net mass	approx. 1 kg
Base	14 pin, all glass
Final accelerator contact	small ball

* Not to be connected in series with other tubes.

Dimensions and connections

See also outline drawing		
Overall length	⩽	343 mm
Face dimensions	⩽	100 x 120 mm^2 (note 1)

Accessories

Socket, supplied with tube	type 55566
Mu-metal shield	type 55592
Final accelerator contact connector	type 55569

FOCUSING	electrostatic	
DEFLECTION	double electrostatic	
x-plates	symmetrical	
y-plates	symmetrical	
Angle between x and y-traces		$90 \pm 1^{\circ}$
Angle between x-trace and horizontal axis of the face	⩽	5° *

If use is made of the full deflection capabilities of the tube the deflection plates will block part of the electron beam, hence a low impedance deflection plate drive is desirable.

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	7 pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	7 pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	4 pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	4 pF
x_1 to x_2	C_{x1x2}	2,2 pF
y_1 to y_2	C_{y1y2}	1,3 pF
Control grid to all other elements	C_{g1}	6 pF
Cathode to all other elements	C_k	2,7 pF

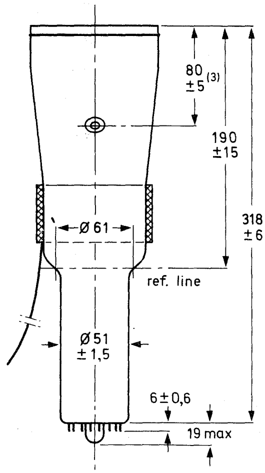
* The tube is provided with a rotation coil, concentrically wound around the tube neck, enabling the alignment of the x-trace with the mechanical x-axis of the screen. The coil has 1000 turns and a resistance of max. 350 Ω. Under typical operating conditions, max. 35 ampere-turns are required for the max. rotation of 5°. This means the required current is max. 35 mA at a required voltage of max. 12 V.

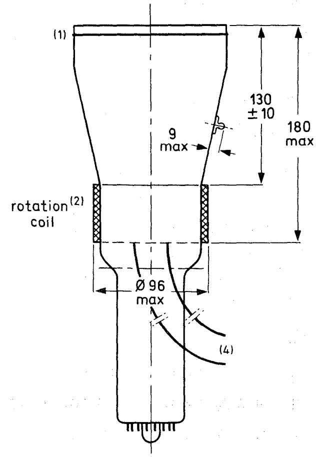
Notes to the drawings on opposite page.

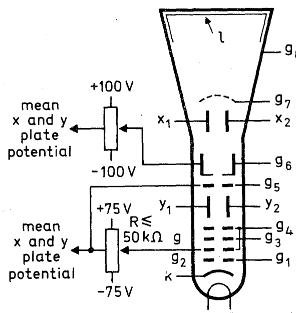
1. The bulge at the frit seal may increase the indicated maximum dimensions by not more than 2 mm.
2. The coil is fixed to the envelope by means of adhesive tape.
3. The centre of the contact is situated within a square of 10 mm x 10 mm around the true geometrical position.
4. The length of the connecting leads of the rotation coil is min. 350 mm.

DIMENSIONS AND CONNECTIONS

For notes to the drawings see bottom of opposite page.







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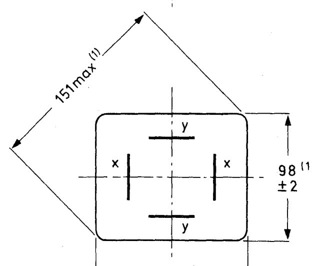

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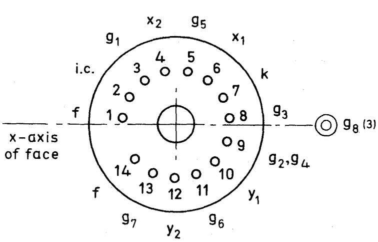

bottom view

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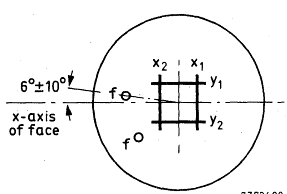

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bottom view

TYPICAL OPERATION

Conditions

Final accelerator voltage	$V_{g8(\ell)}$	10	kV	
Post deflection accelerator mesh electrode voltage	V_{g7}	2000	V	
Geometry control electrode voltage	V_{g6}	2000 ± 100	V	(note 1)
Interplate shield voltage	V_{g5}	2000	V	(note 2)
First accelerator voltage	$V_{g2, g4}$	2000	V	
Astigmatism control electrode voltage	$\Delta V_{g2, g4}$	± 75	V	(note 3)
Focusing electrode voltage	V_{g3}	400 to 560	V	
Cut-off voltage for visual extinction of focused spot	$-V_{g1}$	25 to 70	V	

Performance

Useful scan					
horizontal		⩾	100	mm	(note 4)
vertical		⩾	80	mm	(note 4)
Deflection coefficient					
horizontal	M_x		12,8	V/cm	
		⩽	14	V/cm	
vertical	M_y		6,3	V/cm	
		⩽	7	V/cm	
Line width	l.w.	≈	0,38	mm	(note 5)
Deviation of deflection linearity		⩽	2	%	(note 6)
Grid drive for 10 μA screen current	V_d	≈	20	V	
Geometry distortion	see note 7				

NOTES

1. The geometry control electrode voltage V_{g6} should be adjusted within the indicated range (values with respect to the mean x-plate potential).
2. The interplate shield voltage should be equal to the mean x-plate potential. The mean x-plate and y-plate potentials should be equal for optimum spot quality.
3. The astigmatism control electrode voltage should be adjusted for optimum spot shape. For any necessary adjustment its potential will be within the stated range.
4. The tube is designed for optimum performance when operating at a ratio $V_{g8(\ell)}/V_{g2, g4} = 5$. If this ratio is smaller than 5, the useful scan may be smaller than 100 mm x 80 mm.
5. Measured with the shrinking raster method in the centre of the screen with corrections adjusted for optimum spot size, at a beam current of 10 μA.
6. The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.
7. A graticule consisting of concentric rectangles of 95 mm x 75 mm and 93 mm x 73 mm is aligned with the electrical x-axis of the tube. With optimum corrections applied, the edges of a raster will fall between these rectangles.

LIMITING VALUES (Absolute maximum rating system)

Final accelerator voltage	$V_{g8(\ell)}$	max.	12	kV
Post deflection accelerator mesh electrode voltage	V_{g7}	max.	2200	V
Geometry control electrode voltage	V_{g6}	max.	2200	V
Interplate shield voltage	V_{g5}	max.	2200	V
Accelerator voltage	$V_{g2,\,g4}$	max.	2200	V
		min.	1800	V
Focusing electrode voltage	V_{g3}	max.	2200	V
Control grid voltage	$-V_{g1}$	max.	200	V
		min.	0	V
Cathode to heater voltage				
positive	V_{kf}	max.	125	V
negative	$-V_{kf}$	max.	125	V
Grid drive, averaged over 1 ms	V_d	max.	20	V
Screen dissipation	W_ℓ	max.	8	mW/cm^2
Voltage between astigmatism control electrode and any deflection plate	$V_{g4/x}$	max.	500	V
	$V_{g4/y}$	max.	500	V
Control grid circuit resistance	R_{g1}	max.	1	MΩ

INSTRUMENT CATHODE-RAY TUBE

14 cm diagonal rectangular flat-faced oscilloscope tube with domed mesh and metal-backed screen with internal graticule. The tube has side connections to the x and y-plates, and is intended for use in compact oscilloscopes with up to 150 MHz bandwidth. This tube features a 1,5 W cathode with short warm-up time (quick-heating cathode).

QUICK REFERENCE DATA

Final accelerator voltage	$V_{g8(\ell)}$	16,5 kV
Display area		100 x 80 mm^2
Deflection coefficient		
horizontal	M_x	8,7 V/cm
vertical	M_y	4,7 V/cm

OPTICAL DATA

Screen	metal-backed phosphor	
type	GH, colour green	
persistence	medium short	
Useful screen dimensions	$\geqslant$	100 x 80 mm^2
Useful scan		
horizontal	$\geqslant$	100 mm
vertical	$\geqslant$	80 mm
Spot eccentricity in horizontal and vertical directions	$\leqslant$	6,5 mm

HEATING

Indirect by a.c. or d.c.; parallel supply

Heater voltage	V_f	6,3 V
Heater current	I_f	240 mA

MECHANICAL DATA

Dimensions and connections

See outline drawings	
Overall length (socket included)	$\leqslant$ 397 mm
Face dimensions	$\leqslant 100 \times 120$ mm^2
Net mass	approx. 1 kg
Base	14 pin, all glass

Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Accessories

Socket, supplied with tube	type 55572
Side contact connector (7 required)	type 55561
Final accelerator contact connector	connection to final accelerator electrode is made via an EHT cable attached to the tube

FOCUSING	electrostatic
DEFLECTION	double electrostatic
x-plates	symmetrical
y-plates	symmetrical
Angle between x and y-traces	$90 \pm 1^{\circ}$
Angle between y-trace and y-axis of the internal graticule	$\leqslant 5^{\circ}$ *

If use is made of the full deflection capabilities of the tube the deflection plates will block part of the electron beam, hence a low impedance deflection plate drive is desirable.

* The tube is provided with a rotation coil, concentrically wound around the tube neck, enabling the alignment of the y-trace with the mechanical y-axis of the screen. The coil has 2000 turns and a maximum resistance of 650 Ω. Under typical operating conditions, a maximum of 40 ampere-turns are required for the maximum rotation of 5°. This means the required current is 20 mA maximum at a required voltage of 13 V.

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	5 pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	5 pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	1,7 pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	2 pF
x_1 to x_2	C_{x1x2}	3 pF
y_1 to y_2	C_{y1y2}	1,6 pF
Control grid to all other elements	C_{g1}	6 pF
Cathode to all other elements	C_k	2,7 pF
Focusing electrode to all other electrodes	C_{g3}	5 pF

DIMENSIONS AND CONNECTIONS

Dimensions in mm

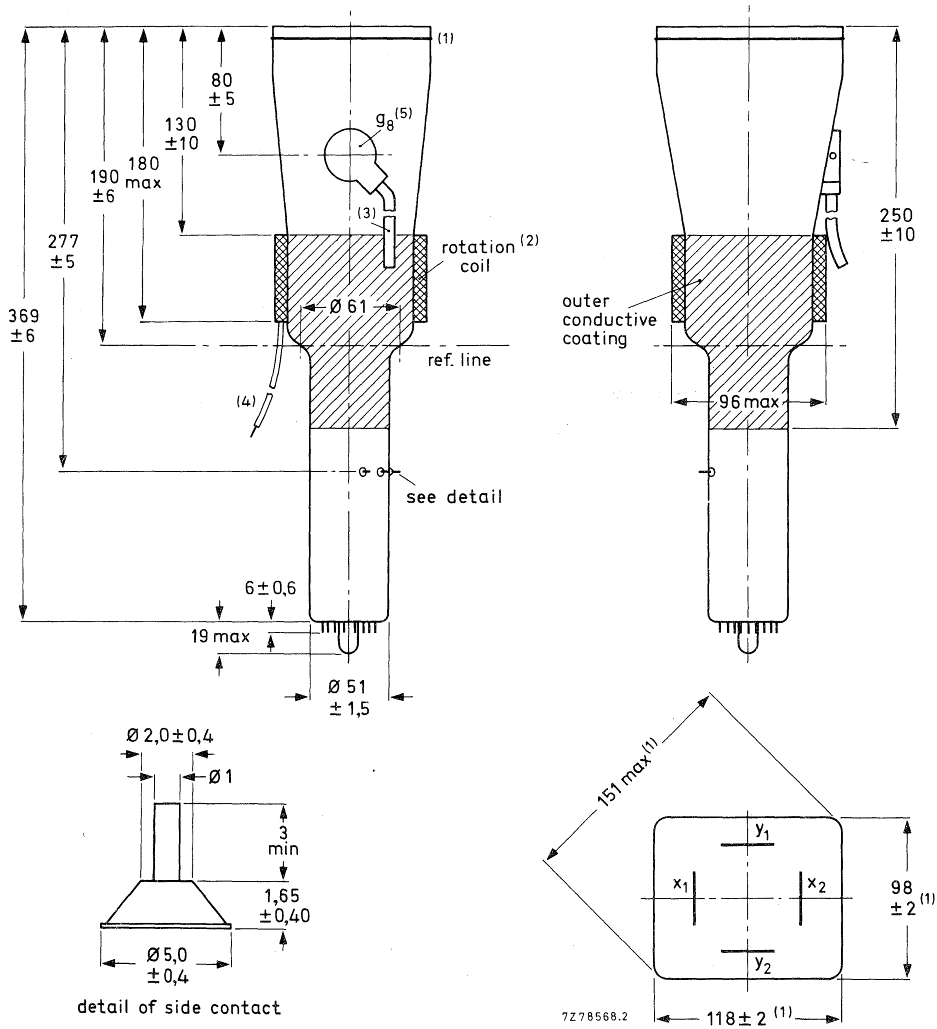


Fig. 1 Outlines; for notes see bottom of opposite page.

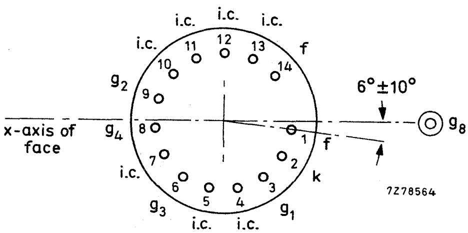


Fig. 2 Pin arrangement; bottom view.

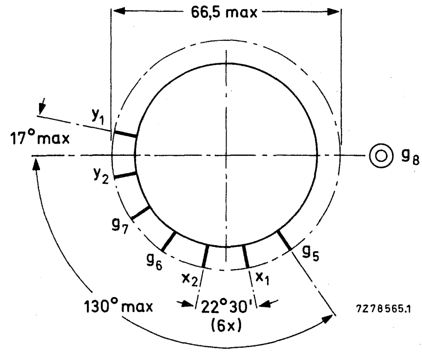


Fig. 3 Side-contact arrangement; bottom view.

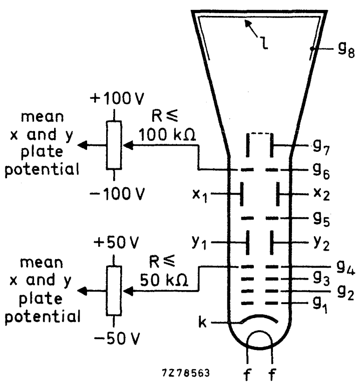


Fig. 4 Electrode configuration.

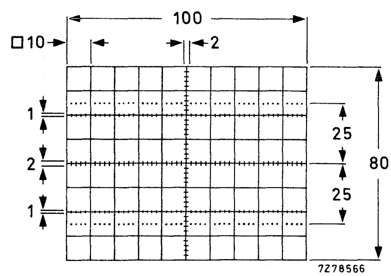


Fig. 5 Internal graticule.
Line thickness = 0,2 mm;
dot diameter = 0,4 mm.

Notes to the drawing on opposite page.

1. The bulge at the frit seal may increase the indicated maximum dimensions by not more than 2 mm.
2. The coil is fixed to the envelope by means of adhesive tape.
3. EHT cable; minimum length is 530 mm.
4. Connection cable, comprising two wires for connection of the rotation coil, and one green wire for earthing the outer conductive coating. Minimum cable length is 400 mm.
5. The centre of the final accelerator contact is situated within a square of 10 mm x 10 mm around the true geometrical position.

TYPICAL OPERATION

Conditions

Final accelerator voltage	$V_{g8(\ell)}$	16,5 kV	
Post deflection accelerator mesh electrode voltage	V_{g7}	2200 V	
Geometry control electrode voltage	V_{g6}	2200 ± 100 V	(note 1)
Interplate shield voltage	V_{g5}	2200 V	(note 2)
First accelerator voltage	V_{g2}	2200 V	
Astigmatism control electrode voltage	V_{g4}	2200 ± 50 V	(note 3)
Focusing electrode voltage	V_{g3}	620 to 800 V	
Cut-off voltage for visual extinction of focused spot	$-V_{g1}$	60 to 110 V	

Performance

Useful scan				
horizontal		≥	100 mm	(note 4)
vertical		≥	80 mm	(note 4)
Deflection coefficient				
horizontal	M_x		8,7 V/cm	
		≤	9,8 V/cm	
vertical	M_y		4,7 V/cm	
		≤	5,3 V/cm	
Line width	l.w.	typ.	0,37 mm	(note 5)
Grid drive for 10 μA screen current	V_d	approx.	30 V	
Geometry distortion		see note 6		
Deviation of deflection linearity		3%; see note 7		

NOTES

1. The geometry control electrode voltage V_{g6} should be adjusted within the indicated range (values with respect to the mean x-plate potential).
2. The interplate shield voltage should be equal to the mean x-plate and y-plate potentials for optimum spot quality.
3. The astigmatism control electrode voltage should be adjusted for optimum spot shape. For any necessary adjustment its potential will be within the stated range.
4. The tube is designed for optimum performance when operating at a ratio $V_{g8(\ell)}/V_{g2} = 7{,}5$. If this ratio is smaller, the useful scan may be smaller than 100 mm x 80 mm.
5. Measured with the shrinking raster method in the centre of the screen with corrections adjusted for optimum spot size, at a beam current of 10 μA.
6. A graticule consisting of horizontal and vertical line pairs according to Fig. 6, is aligned with the electrical x-axis of the tube. With optimum corrections applied (including orthogonality correction), any horizontal or vertical trace will fall between these line pairs.
7. Deviation of linearity is defined as the proportional deviation of the deflection coefficient over any division on the x-axis and y-axis from the average values over the central eight (horizontal) and central six (vertical) divisions respectively.

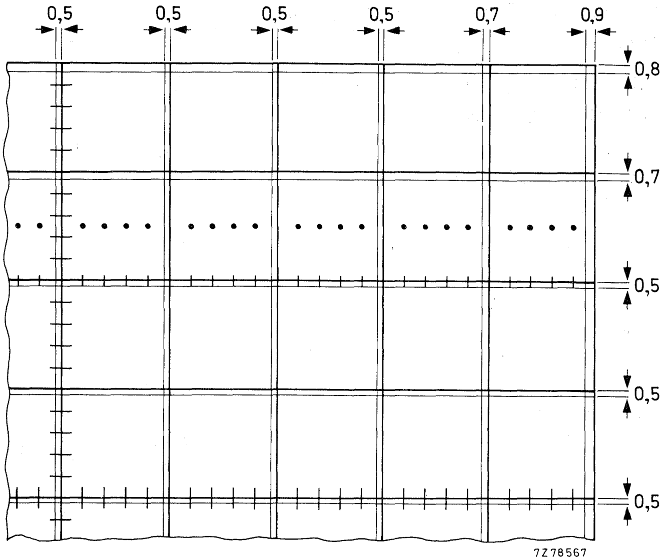


Fig. 6 Quarter of graticule with horizontal and vertical line pairs, see note 6 on opposite page.

LIMITING VALUES (Absolute maximum rating system)

Final accelerator voltage	$V_{g8(\ell)}$	max.	18	kV
Post deflection accelerator mesh electrode voltage	V_{g7}	max.	2500	V
Geometry control electrode voltage	V_{g6}	max.	2500	V
Interplate shield voltage	V_{g5}	max.	2500	V
Astigmatism control electrode voltage	V_{g4}	max.	2500	V
Focusing electrode voltage	V_{g3}	max.	2500	V
First accelerator voltage	V_{g2}	max.	2500	V
Control grid voltage	$-V_{g1}$	max.	200	V
		min.	0	V
Cathode to heater voltage				
positive	V_{kf}	max.	125	V
negative	$-V_{kf}$	max.	125	V
Voltage between astigmatism control electrode and any deflection plate	$V_{g4/x}$	max.	500	V
	$V_{g4/y}$	max.	500	V
→ Grid drive, averaged over 1 ms	V_d	max.	20	V
Screen dissipation	W_{ℓ}	max.	8	mW/cm^2
Control grid circuit resistance	R_{g1}	max.	1	MΩ

INSTRUMENT CATHODE-RAY TUBES

- mono accelerator
- 14 cm diagonal rectangular flat face
- internal magnetic lens system for vertical scan magnification (1,2 x), orthogonality, astigmatism and eccentricity correction
- quick-heating cathode
- with or without internal graticule
- for inexpensive oscilloscopes and read-out devices

QUICK REFERENCE DATA

Accelerator voltage	$V_{g2,(\ell)}$	2000 V
Minimum useful scan area		100 mm x 80 mm
Deflection coefficient		
horizontal	M_x	22 V/cm
vertical	M_y	11,5 V/cm

OPTICAL DATA

Screen

type	colour	persistence
GH	green	medium short
GY	yellowish-green	medium short
GM	yellowish-green	long

Useful screen area	⩾ 102 mm x 82 mm note 1; (page 7)
Useful scan area	⩾ 100 mm x 80 mm
Internal graticule	type 93; see Fig. 4

HEATING

Indirect by a.c. or d.c.*

Heater voltage	V_f	6,3 V
Heater current	I_f	240 mA
Heating time to attain 10% of the cathode current at equilibrium conditions	approx.	5 s

* Not to be connected in series with other tubes.

MECHANICAL DATA

Dimensions and connections (see also outline drawing)

Overall length (socket included)	$\leqslant$ 333 mm
Faceplate dimensions	118 ± 1 mm x 98 ± 1 mm
Net mass	approx. 1 kg
Base	12 pin, all glass, JEDEC B12-246

→ **Mounting**

The tube can be mounted in any position. It must not be supported by the socket and not by the base region alone. The reference points on adjoining edges of the faceplate (see Fig. 5) enable the tube to be mounted accurately in the front panel, thus providing optimum alignment of the internal graticule.

Accessories

Pin protector (required for shipping)	supplied with tube
→ Socket with solder tags	type 55589/55594
→ Socket with printed-wiring pins	type 55595
Mu-metal shield	to be established

FOCUSING

electrostatic

DEFLECTION*

DEFLECTION*	double electrostatic	
x-plates	symmetrical	
y-plates	symmetrical	

If use is made of the full deflection capabilities of the tube the deflection plates will block part of the electron beam, hence a low impedance deflection plate drive is desirable.

Angle between x and y-traces	90^{o}	note 2
→ Angle between x-trace and x- axis of the internal graticule	$\leqslant 5^{o}$	note 3
Eccentricity of undeflected spot with respect to internal graticule		
horizontal	$\leqslant$ 4 mm	
vertical	$\leqslant$ 2 mm	note 2

* Notes are on page 8.

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	4,5 pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	4,5 pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	3,5 pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	3,5 pF
x_1 to x_2	C_{x1x2}	2 pF
y_1 to y_2	C_{y1y2}	1 pF
Control grid to all other elements	C_{g1}	6 pF
Cathode to all other elements	C_k	3 pF

DIMENSIONS AND CONNECTIONS Dimensions in mm

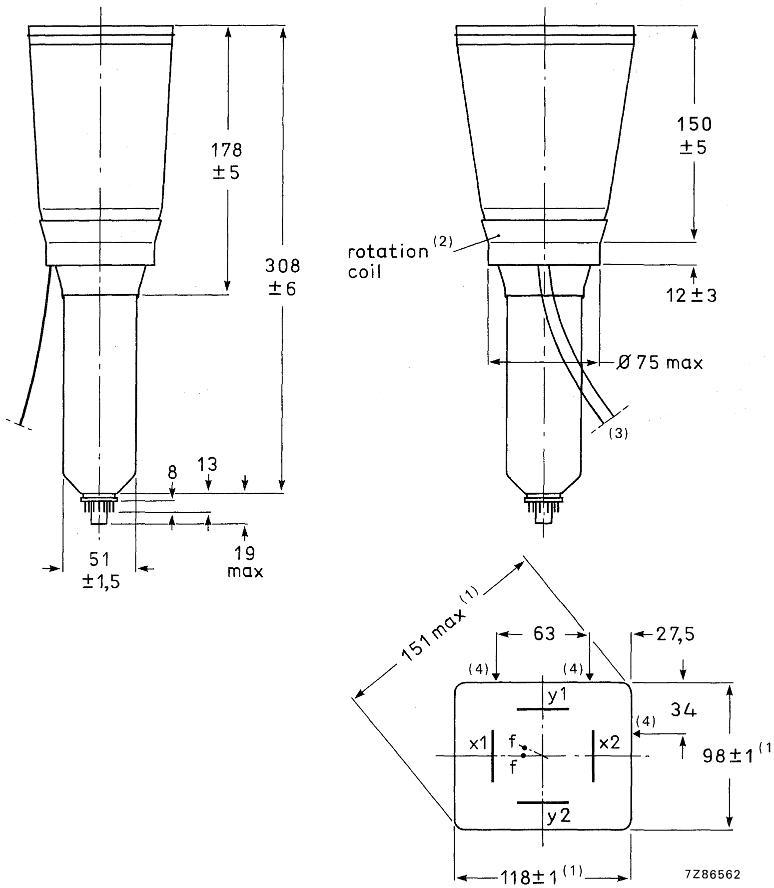


Fig. 1 Outlines.

(1) Dimensions of faceplate only. The complete assembly of faceplate and cone (frit seal included) will pass through an opening of 122 mm x 102 mm (diagonal 153 mm).
(2) The coil is fixed to the envelope with resin and adhesive tape.
(3) The length of the connecting leads of the rotation coil is min. 350 mm.
(4) Reference points on faceplate for graticule alignment (see Fig. 4).

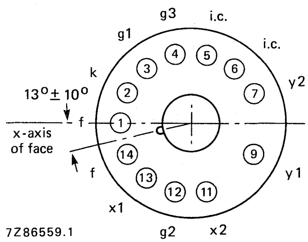


Fig. 2 Pin arrangement; bottom view.

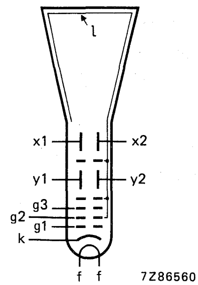


Fig. 3 Electrode configuration.

Internal graticule

The internal graticule is aligned with the faceplate by using the faceplate reference points A1, A2 and A3, see Fig. 4. See also note 1, page 7.

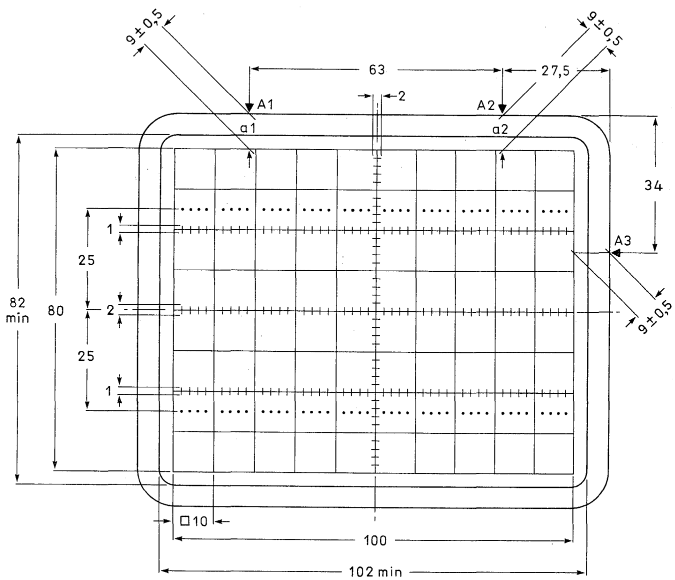


Fig. 4 Front view of tube with internal graticule, type 93.
$|a1 - a2| \leqslant 0{,}3$ mm.

Line thickness = 0,2 mm;
dot diameter = 0,4 mm;
colour: red.

TYPICAL OPERATION (voltages with respect to cathode)*

Conditions (note 4)

Accelerator voltage	$V_{g2,(\ell)}$		2000 V	
Astigmatism control voltage	$\Delta V_{g2(\ell)}$		0 V	notes 2, 5
Focusing voltage	V_{g3}		220 to 370 V	
Cut-off voltage for visual extinction of focused spot	$-V_{g1}$		22 to 65 V	

Performance

Useful scan				
horizontal		$\geqslant$	100 mm	
vertical		$\geqslant$	80 mm	
Deflection coefficient				
horizontal	M_x		22 V/cm	
		$<$	24 V/cm	
vertical	M_y		11,5 V/cm	
		$<$	12 V/cm	
Line width	l.w.	$\approx$	0,35 mm	note 6
Deviation of deflection linearity		$\leqslant$	2 %	note 7
Geometry distortion		see note 8		
Grid drive for 10 μA screen current	V_d	$\approx$	10 V	

LIMITING VALUES (Absolute maximum rating system)

Accelerator voltage	$V_{g2,(\ell)}$	max.	2200 V
Focusing electrode voltage	V_{g3}	max.	2200 V
Control grid voltage	$-V_{g1}$	max.	200 V
		min.	0 V
Cathode to heater voltage			
positive	V_{kf}	max.	125 V
negative	$-V_{kf}$	max.	125 V
Heater voltage	V_f	max.	6,6 V
		min.	6,0 V
Grid drive, averaged over 1 ms	V_d	max.	20 V
Screen dissipation	W_ℓ	max.	3 mW/cm^2
Control grid circuit resistance	R_{g1}	max.	1 MΩ

* Notes are on page 7.

NOTES

1. As the frit seal is visible through the faceplate, and not necessarily aligned with the internal graticule, application of an external passe-partout with open area of max. 102 mm x 82 mm is recommended. The internal graticule is aligned with the faceplate by using the faceplate reference points (see Fig. 4).
2. The tube features internal magnetic correction for orthogonality between x- and y-traces, spot shaping (astigmatism) and vertical eccentricity calibration. Correction is obtained at V_{g2} = 1800 to 2200 V; optimum at V_{g2} = 2000 V.
3. The tube has a trace rotation coil, fixed onto the lower cone part. The coil has 1000 turns and a typical resistance of 180 Ω at 20 °C (max. 270 Ω at 80 °C). Approx. 5 mA causes 1° trace rotation. Thus maximum required voltage is approx. 11 V for tube tolerances (± 5°) and earth magnetic field with reasonable shielding (± 2°).
4. The mean x-plate potential should be equal to V_{g2}. A deviation may lead to raster distortion beyond the indicated range (see note 8).
5. Deviation of mean y-plate potential with respect to V_{g2} will introduce astigmatism (as without internal magnetic correction). The grid 2 impedance should be less than 10 kΩ.
6. Measured with the shrinking raster method in the centre of the screen under typical operating conditions, adjusted for optimum spot size at a beam current I_ℓ = 10 μA.
7. The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.
8. A graticule consisting of concentric rectangles of 95 mm x 75 mm and 93 mm x 73 mm is aligned with the internal graticule. With optimum trace rotation correction the edges of a raster will fall between these rectangles.

INSTRUMENT CATHODE-RAY TUBE

- 14 cm diagonal rectangular flat face
- domed mesh post-deflection acceleration
- internal magnetic lens system for correction of orthogonality, astigmatism and eccentricity
- quick-heating cathode
- internal graticule
- high sensitivity and high brightness
- short overall length
- for compact oscilloscopes with up to 75 MHz bandwidth

QUICK REFERENCE DATA

Final accelerator voltage	$V_{g7(\ell)}$	10	16,5	kV
First accelerator voltage	$V_{g2,g4}$	2	2,2	kV
Minimum useful scan area		100 mm x 80		mm
Deflection coefficient				
horizontal	M_x	7,5	7,8	V/cm
vertical	M_y	4	4	V/cm

OPTICAL DATA

Screen	metal-backed phosphor
type	GH
colour	green
persistance	medium short
Useful screen area	⩾ 102 mm x 82 mm; note 1 (page 8)
Useful scan area	⩾ 100 mm x 80 mm
Internal graticule	type 93; see Fig. 4

HEATING

Indirect by a.c. or d.c.*		
Heater voltage	V_f	6,3 V
Heater current	I_f	240 mA
Heater time to attain 10% of the cathode current at equilibrium conditions	approx.	5 s

* Not to be connected in series with other tubes.

MECHANICAL DATA

Dimensions and connections (see also outline drawings)

Overall length (socket included)	⩽ 338 mm
Faceplate dimensions	118 ± 1 mm x 98 ± 1 mm
Net mass	approx. 1 kg
Base	12 pin, all glass, JEDEC B12-246

Mounting

The tube can be mounted in any position. It must not be supported by the socket and not by the base region alone. The reference points on adjoining edges of the faceplate (see Fig. 5) enable the tube to be mounted accurately in the front panel, thus providing optimum alignment of the internal graticule.

Accessories

Pin protector (required for shipping)	supplied with tube
Socket with solder tags	type 55589/55594
Socket with printed-wiring pins	type 55595
Final accelerator contact connector	type 55569
Mu-metal shield	to be established

FOCUSING	electrostatic
DEFLECTION	double electrostatic
x-plates	symmetrical
y-plates	symmetrical

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	4,2 pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	4,2 pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	3,1 pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	3,1 pF
x_1 to x_2	C_{x1x2}	2 pF
y_1 to y_2	C_{y1y2}	1,6 pF
Control grid to all other elements	C_{g1}	6 pF
Cathode to all other elements	C_k	3,2 pF
Focusing electrode to all other elements	C_{g3}	5 pF

DEVELOPMENT SAMPLE DATA

DIMENSIONS AND CONNECTIONS

Dimensions in mm

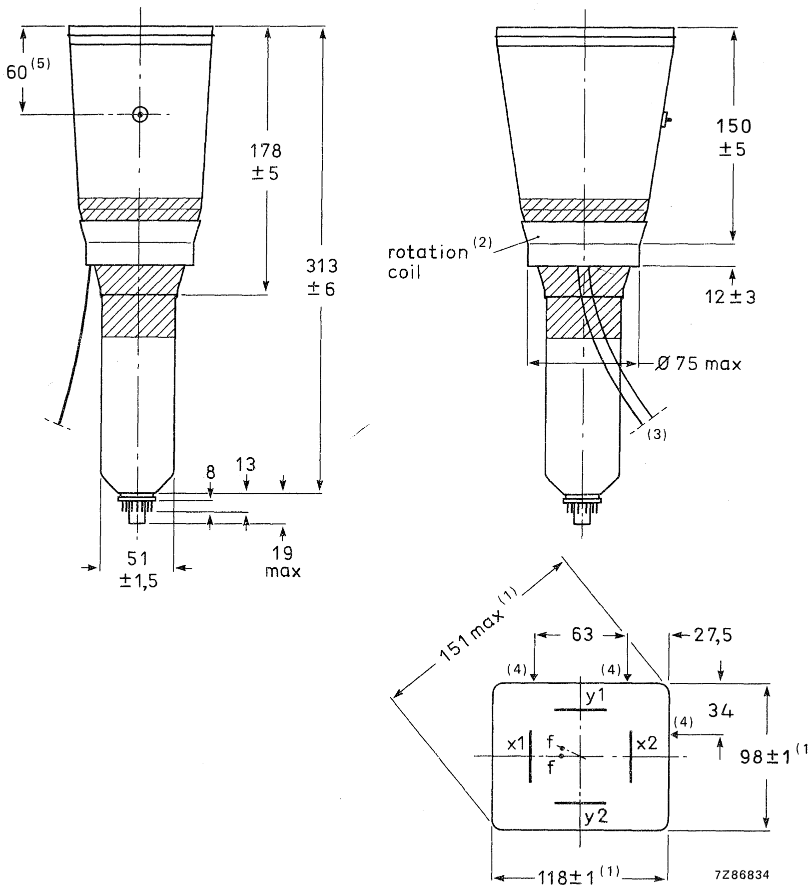


Fig. 1 Outlines.

1. Dimensions of faceplate only. The complete assembly of faceplate and cone (frit seal included) will pass through an opening of 122 mm x 102 mm (diagonal 153 mm).
2. The coil is fixed to the envelope with resin and adhesive tape.
3. The length of the connecting leads of the rotation coil is min. 350 mm.
4. Reference points on faceplate for graticule alignment (see Fig. 4).
5. The centre of the final accelerator contact is situated within a square of 10 mm x 10 mm around the indicated position.

DIMENSIONS AND CONNECTIONS (continued)

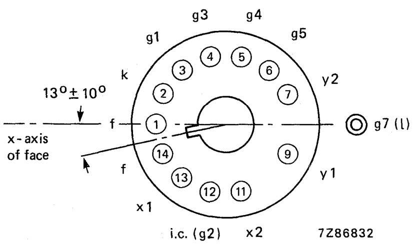


Fig. 2 Pin arrangement; bottom view.

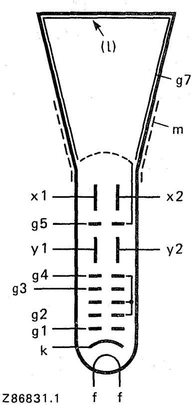


Fig. 3 Electrode configuration.

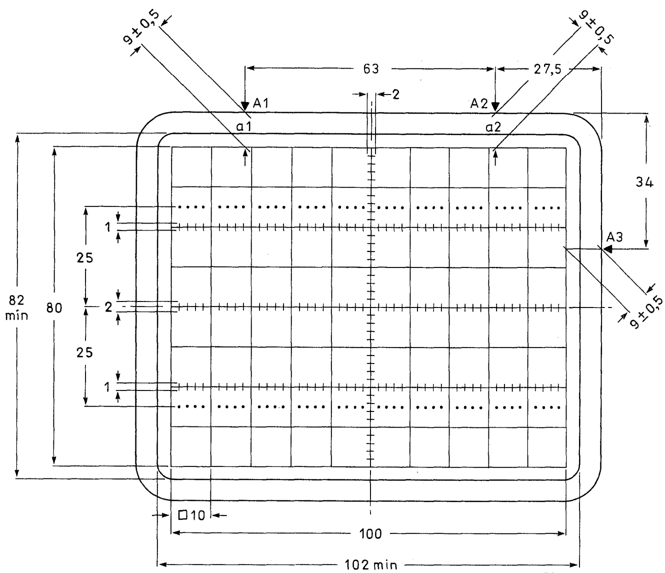


Fig. 4 Front view of tube with internal graticule, type 93. The faceplate reference points A1, A2 and A3 are used for aligning the graticule with the faceplate. $|a1 - a2| \leqslant 0{,}3$ mm.

Line thickness = 0,2 mm; dot diameter = 0,4 mm; colour: red.

TYPICAL OPERATION (voltages with respect to cathode) *

Conditions

Final accelerator voltage	$V_{g7(\ell)}$	10	16,5	kV
Mean deflection plate potential		2	2,2	kV note 2
Shield voltage for optimum geometry	V_{g5}	2	2,2	kV note 3
First accelerator and astigmatism control voltage	$V_{g2,g4}$	2	2,2	kV note 3
Focusing voltage	V_{g3}	400 to 800		V
Cut-off voltage for visual extinction of focused spot	$-V_{g1}$	45 to 90	50 to 100	V

Outer conductive coating (m) and mu-metal shield to be earthed.

Performance

Horizontal deflection coefficient	M_x	7,5	7,8	V/cm ± 10%
Vertical deflection coefficient	M_y	4,0	4,0	V/cm ± 5%
Deviation of deflection linearity		≤ 2%		note 4
Geometry distortion				note 5
Eccentricity of undeflected spot				
in horizontal direction		≤ 4 mm		
in vertical direction		≤ 2 mm		
Angle between x- and y-traces		90°		note 2
Angle between x-trace and x-axis of internal graticule		≤ 5°		note 6
Luminance reduction with respect to screen centre				
x-axis, outer graticule line		≤ 30%		
y-axis, outer graticule line		≤ 30%		
any corner		≤ 50%		
Grid drive for 10 μA screen current	V_d	approx.	20	V
Line width	l.w.	approx.	0,35	mm note 7

* Notes are on page 8.

LIMITING VALUES (Absolute maximum rating system)

Final accelerator voltage	$V_{g7(\ell)}$	max.	18 kV
Shield voltage	V_{gs}	max.	2,5 kV
First accelerator and astigmatism control voltage	$V_{g2,g4}$	max.	2,5 kV
Focusing electrode voltage	V_{g3}	max.	2,5 kV
Control grid voltage	$-V_{g1}$	max.	200 V
		min.	0 V
Cathode to heater voltage			
positive	V_{kf}	max.	125 V
negative	$-V_{kf}$	max.	125 V
Heater voltage	V_f	max.	6,6 V
		min.	6,0 V
Voltage between g4,g5 and any deflection plate	$\Delta V_{g4,g5,x,y}$	max.	500 V
Grid drive, averaged over 1 ms	V_d	max.	25 V
Screen dissipation	W_{ℓ}	max.	8 mW/cm^2
Control grid circuit resistance	R_{g1}	max.	1 MΩ

DEVELOPMENT SAMPLE DATA

NOTES

1. As the frit seal is visible through the faceplate, and not necessarily aligned with the internal graticule, application of an external passe-partout with open area of max. 102 mm x 82 mm is recommended. The internal graticule is aligned with the faceplate by using the faceplate reference points (see Fig. 4).
2. The deflection plates must be operated symmetrically; floating mean x- or y-potentials will result into non-uniform line width and geometry distortion. The mean x- and y-potentials should be equal; under this condition the tube will be within the specification without corrections for astigmatism and geometry.

   The tube features internal magnetic correction for orthogonality between x- and y-traces, spot shaping (astigmatism) and eccentricity calibration. Correction is obtained at $V_{g2,g4}$ = 1800 to 2500 V; optimum at $V_{g2,g4}$ = 2200 V.
3. For some applications a mean x-potential up to 50 V positive with respect to mean y-potential is inevitable. In this case V_{g5} must be made equal to mean x-potential, and a range of 0 to −25 V with respect to mean y-potential will be required on g2,g4 for astigmatism correction. The circuit resistance for $V_{g2,g4}$ should be $\leq$ 10 kΩ.
4. The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.
5. A graticule consisting of concentric rectangles of 100 mm x 80 mm and 98 mm x 78 mm is aligned with the internal graticule. With optimum trace rotation correction the edges of a raster will fall between these rectangles.
6. The tube has a trace rotation coil, fixed onto the lower cone part. The coil has 1000 turns and a typical resistance of 185 Ω at 20 °C (max. 270 Ω at 80 °C). Approx. 6,5 mA causes 1° trace rotation. Thus maximum required voltage is approx. 13 V for tube tolerances (± 5°) and earth magnetic field with reasonable shielding (± 2°).
7. Measured with the shrinking raster method in the centre of the screen under typical operating conditions, adjusted for optimum spot size at a beam current I_ℓ = 10 μA.

INSTRUMENT CATHODE-RAY TUBE

- 14 cm diagonal rectangular flat face
- domed mesh post-deflection acceleration
- internal magnetic lens system for correction of orthogonality, astigmatism and eccentricity
- quick-heating cathode
- side contacts to deflection plates
- internal graticule
- high sensitivity and high brightness
- short overall length
- for compact oscilloscopes with up to 150 MHz bandwidth

QUICK REFERENCE DATA

Final accelerator voltage	$V_{g7(\ell)}$	16,5 kV
First accelerator voltage	$V_{g2,g4}$	2,2 kV
Minimum useful scan area		100 mm x 80 mm
Deflection coefficient		
horizontal	M_x	7,8 V/cm
vertical	M_y	4 V/cm (max. 4,2 V/cm)
Photographic writing speed	p.w.s.	2,0 cm/ns

OPTICAL DATA

Screen	metal-backed phosphor
type	GH
colour	green
persistance	medium short
Useful screen area	⩾ 102 mm x 82 mm; note 1 (page 8)
Useful scan area	⩾ 100 mm x 80 mm
Internal graticule	type 93; see Fig. 5

HEATING

Indirect by a.c. or d.c.*

Heater voltage	V_f	6,3 V
Heater current	I_f	240 mA
Heating time to attain 10% of the cathode current at equilibrium conditions		approx. 5 s

* Not to be connected in series with other tubes.

MECHANICAL DATA

Dimensions and connections (see also outline drawings)

Overall length (socket included)	⩽ 338 mm
Faceplate dimensions	118 ± 1 mm x 98 ± 1 mm
Net mass	approx. 1 kg
Base	12 pin, all glass, JEDEC B12-246

Mounting

The tube can be mounted in any position. It must not be supported by the socket and not by the base region alone. The reference points on adjoining edges of the faceplate (see Fig. 6) enable the tube to be mounted accurately in the front panel, thus providing optimum alignment of the internal graticule.

Accessories

Pin protector (required for shipping)	supplied with tube
Socket with solder tags	type 55589/55594
Socket with printed-wiring pins	type 55595
Side contact connector for ϕ 0,6 mm pin (4 required)	type 2422 034 11976 (AMP87313)
Final accelerator contact connector	type 55569
Mu-metal shield	to be established

FOCUSING	electrostatic
DEFLECTION	double electrostatic
x-plates	symmetrical
y-plates	symmetrical

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	2,4 pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	2,4 pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	1,9 pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	1,9 pF
x_1 to x_2	C_{x1x2}	1,8 pF
y_1 to y_2	C_{y1y2}	1,5 pF
Control grid to all other elements	C_{g1}	6 pF
Cathode to all other elements	C_k	3,2 pF
Focusing electrode to all other elements	C_{g3}	5 pF

DEVELOPMENT SAMPLE DATA

DIMENSIONS AND CONNECTIONS

Dimensions in mm

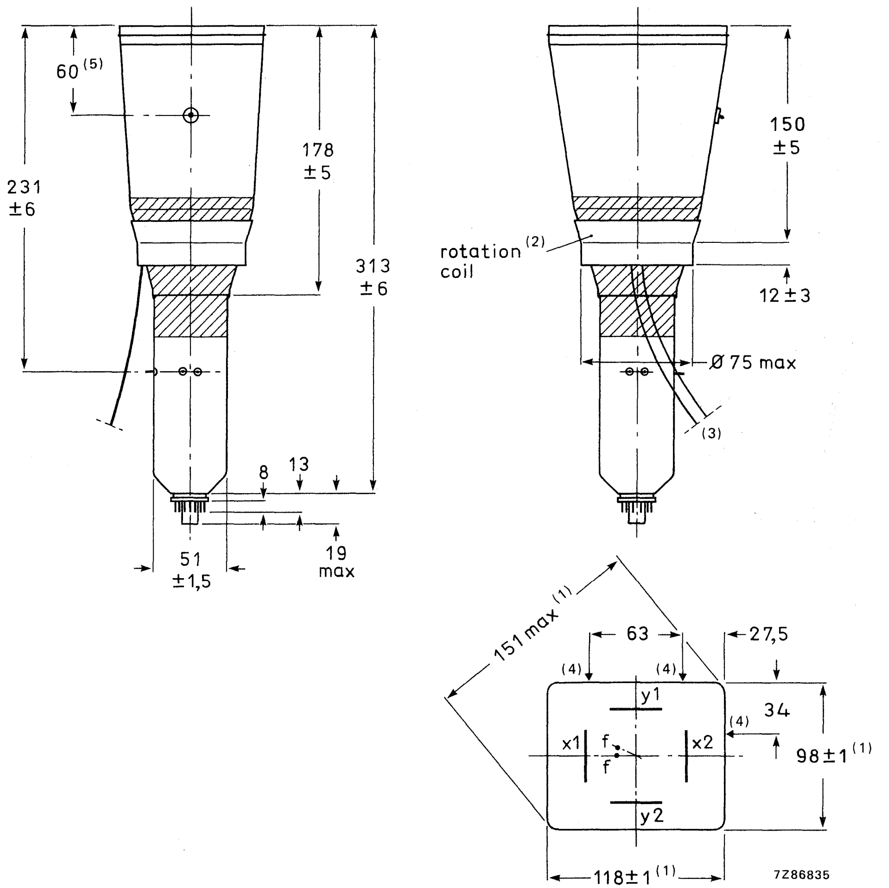


Fig. 1 Outlines.

1. Dimensions of faceplate only. The complete assembly of faceplate and cone (frit seal included) will pass through an opening of 122 x 102 mm (diagonal 153 mm).
2. The coil is fixed to the envelope with resin and adhesive tape.
3. The length of the connecting leads of the rotation coil is min. 350 mm.
4. Reference points on faceplate for graticule alignment (see Fig. 5).
5. The centre of the final accelerator contact is situated within a square of 10 mm x 10 mm around the indicated position.

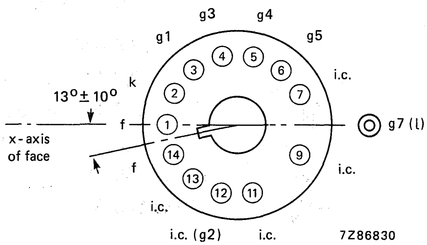


Fig. 2 Pin arrangement; bottom view.

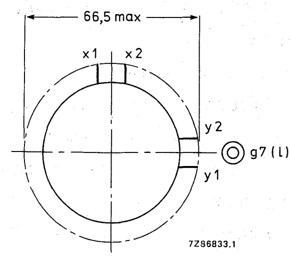


Fig. 3 Side-contact arrangement bottom view.

DEVELOPMENT SAMPLE DATA

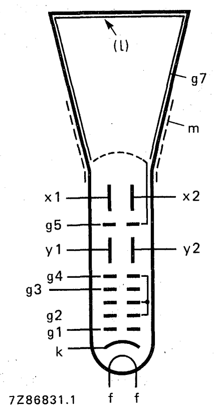


Fig. 4 Electrode configuration.

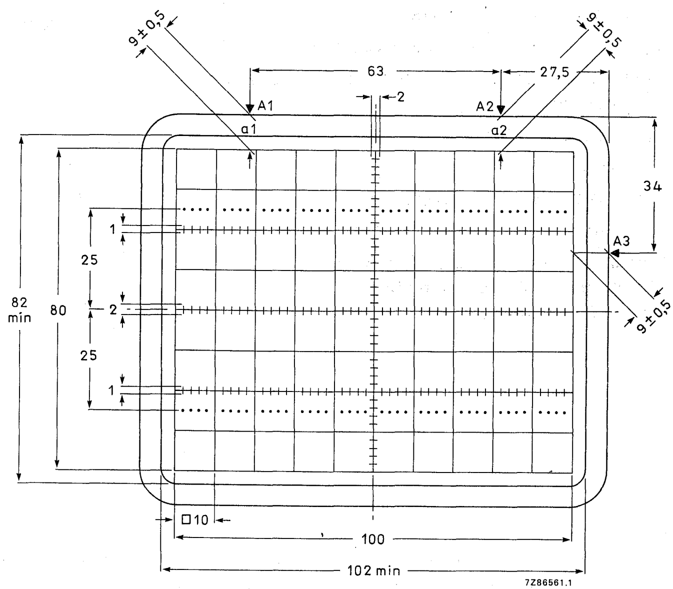


Fig. 5 Front view of tube with internal graticule, type 93. The faceplate reference points A1, A2 and A3 are used for aligning the graticule with the faceplate. $|a1 - a2| \leq 0,3$ mm.

Line thickness = 0,2 mm; dot diameter = 0,4 mm; colour: red.

TYPICAL OPERATION (voltages with respect to cathode)*

Conditions

Final accelerator voltage	$V_{g7(\ell)}$	16,5 kV	
Mean deflection plate potential		2,2 kV	note 2
Shield voltage for optimum geometry	V_{g5}	2,2 kV	note 3
First accelerator and astigmatism control voltage	$V_{g2,g4}$	2,2 kV	note 3
Focusing voltage	V_{g3}	400 to 800 V	
Cut-off voltage for visual extinction of focused spot	$-V_{g1}$	50 to 100 V	

Outer conductive coating (m) and mu-metal shield to be earthed.

Performance

Horizontal deflection coefficient	M_x	7,8 V/cm ± 10%	
Vertical deflection coefficient	M_y	4,0 V/cm ± 5%	
Deviation of deflection linearity		≤ 2 %	note 4
Geometry distortion			note 5
Eccentricity of undeflected spot			
in horizontal direction		≤ 4 mm	
in vertical direction		≤ 2 mm	
Angle between x- and y-traces		90°	note 2
Angle between x-trace and x-axis of internal graticule		≤ 5°	note 6
Luminance reduction with respect to screen centre			
x-axis, outer graticule line		≤ 30 %	
y-axis, outer graticule line		≤ 30 %	
any corner		≤ 50 %	
Grid drive for 10 μA screen current	V_d	approx. 20 V	
Line width	l.w.	approx. 0,35 mm	note 7
Photographic writing speed (V_d = 50 V; Polaroid 612 film; GH phosphor; F = 1,2; magnification 0,5)	p.w.s.	2,0 cm/ns	

* Notes are on page 8.

LIMITING VALUES (Absolute maximum rating system)

Final accelerator voltage	$V_{g7(\ell)}$	max.	18 kV
Shield voltage	V_{g5}	max.	2,5 kV
First accelerator and astigmatism control voltage	$V_{g2,g4}$	max.	2,5 kV
Focusing electrode voltage	V_{g3}	max.	2,5 kV
Control grid voltage	$-V_{g1}$	max.	200 V
		min.	0 V
Cathode to heater voltage			
positive	V_{kf}	max.	125 V
negative	$-V_{kf}$	max.	125 V
Heater voltage	V_f	max.	6,6 V
		min.	6,0 V
Voltage between g4,g5 and any deflection plate	$\Delta V_{g4,g5,x,y}$	max.	500 V
Grid drive, averaged over 1 ms	V_d	max.	25 V
Screen dissipation	W_ℓ	max.	8 mW/cm²
Control grid circuit resistance	R_{g1}	max.	1 MΩ

DEVELOPMENT SAMPLE DATA

NOTES

1. As the frit seal is visible through the faceplate, and not necessarily aligned with the internal graticule, application of an external passe-partout with open area of max. 102 mm x 82 mm is recommended. The internal graticule is aligned with the faceplate by using the faceplate reference points (see Fig. 5).
2. The deflection plates must be operated symmetrically; floating mean x- or y-potentials will result into non-uniform line width and geometry distortion. The mean x- and y-potentials should be equal; under this condition the tube will be within the specification without corrections for astigmatism and geometry.

   The tube features internal magnetic correction for orthogonality between x- and y-traces, spot shaping (astigmatism) and eccentricity calibration. Correction is obtained at $V_{g2,g4}$ = 1800 V to 2500 V; optimum at $V_{g2,g4}$ = 2200 V.
3. For some applications a mean x-potential up to 50 V positive with respect to mean y-potential is inevitable. In this case V_{g5} must be made equal to mean x-potential, and a range of 0 to −25 V with respect to mean y-potential will be required on g2,g4 for astigmatism correction. The circuit resistance for $V_{g2,g4}$ should be $\leqslant$ 10 kΩ.
4. The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.
5. A graticule consisting of concentric rectangles of 100 mm x 80 mm and 98 mm x 78 mm is aligned with the internal graticule. With optimum trace rotation correction the edges of a raster will fall between these rectangles.
6. The tube has a trace rotation coil, fixed onto the lower cone part. The coil has 1000 turns and a typical resistance of 185 Ω at 20 °C (max. 270 Ω at 80 °C). Approx. 6,5 mA causes 1° trace rotation. Thus maximum required voltage is approx. 13 V for tube tolerances (± 5°) and earth magnetic field with reasonable shielding (± 2°).
7. Measured with the shrinking raster method in the centre of the screen under typical operating conditions, adjusted for optimum spot size at a beam current I_{ℓ} = 10 μA.

INSTRUMENT CATHODE-RAY TUBE

18 cm diagonal, rectangular flat faced oscilloscope tube with mesh and metal backed screen.

QUICK REFERENCE DATA			
Final accelerator voltage	$V_{g7(\ell)}$	10	kV
Display area		120 x 100	mm^2
Deflection factor, horizontal	M_x	15,5	V/cm
vertical	M_y	4,5	V/cm

SCREEN : Metal backed phosphor

	colour	persistence
D18-120GH	green	medium short

Useful screen area	min.	120 x 100	mm^2
Useful scan at $V_{g7(\ell)}/V_{g2',g4} = 5$			
horizontal	min.	120	mm
vertical	min.	100	mm
Spot eccentricity in horizontal direction		± 8	mm
in vertical direction		± 6	mm

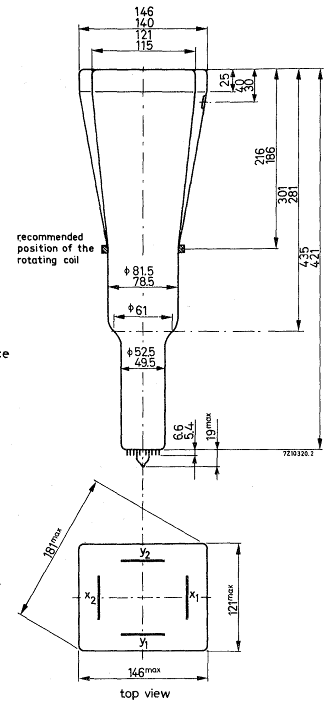
HEATING : Indirect by a.c. or d.c.; parallel supply

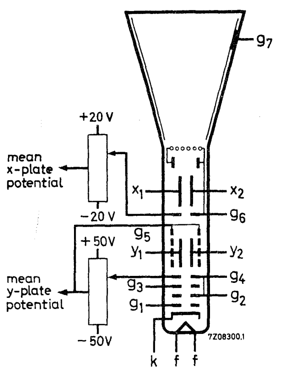
Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

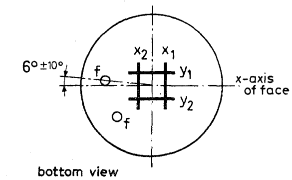
MECHANICAL DATA

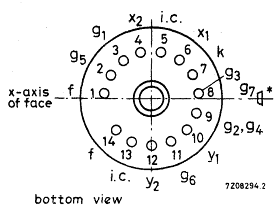
Dimensions in mm

* The centre of the contact is located within a square of 10 mm x 10 mm around the true geometrical position.









Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Dimensions and connections

See also outline drawing

Overall length (socket included)	max.	454	mm
Face dimensions	max.	146 x 121	mm^2
Net weight	approx.	1300	g
Base	14 pin all glass		

Accessories

Socket (supplied with tube)	type 55566
Final accelerator contact connector	type 55563A
Mu-metal shield	type 55584

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	6,5	pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	6,5	pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	5	pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	5	pF
x_1 to x_2	C_{x1x2}	2,2	pF
y_1 to y_2	C_{y1y2}	1,7	pF
Control grid to all other elements	C_{g1}	5,5	pF
Cathode to all other elements	C_k	4,5	pF

FOCUSING electrostatic

DEFLECTION double electrostatic

x plates symmetrical

y plates symmetrical

If use is made of the full deflection capabilities of the tube the deflection plates will intercept part of the electron beam; hence a low impedance deflection plate drive is desirable.

Angle between x and y traces $90 \pm 1^\circ$

Angle between x trace and the horizontal axis of the face max. 5° 1)

LINE WIDTH

Measured with the shrinking raster method in the centre of the screen under typical operating conditions, adjusted for optimum spot size at a beam current $I_\ell = 10\ \mu A$.

Line width, at screen centre	l.w.		0,50	mm
in corner area	l.w.	approx.	0,60	mm

1) See page 5

TYPICAL OPERATING CONDITIONS

Final accelerator voltage	$V_{g7(\ell)}$		10000	V
Interplate shield voltage	V_{g6}		2000	V
Geometry control voltage	ΔV_{g6}		±20	V 2)
Deflection plate shield voltage	V_{g5}		2000	V 3)
Focusing electrode voltage	V_{g3}		350 to 500	V
First accelerator voltage	$V_{g2,g4}$		2000	V
Astigmatism control voltage	$\Delta V_{g2,g4}$		±50	V 4)
Control grid voltage for visual extinction of focused spot	V_{g1}		-25 to -80	V
Grid drive for 10 μA screen current		approx.	12	V
Deflection factor, horizontal	M_x	av.	15,5	V/cm
		max.	17	V/cm
vertical	M_y	av.	4,5	V/cm
		max.	5	V/cm
Deviation of linearity of deflection		max.	2	% 5)
Geometry distortion		See note 6		
Useful scan, horizontal		min.	120	mm
vertical		min.	100	mm

LIMITING VALUES (Absolute max. rating system)

Final accelerator voltage	$V_{g7(\ell)}$	max.	11000	V
		min.	9000	V
Interplate shield voltage and geometry control electrode voltage	V_{g6}	max.	2200	V
Deflection plate shield voltage	V_{g5}	max.	2200	V
Focusing electrode voltage	V_{g3}	max.	2200	V
First accelerator and astigmatism control electrode voltage	$V_{g2,g4}$	max.	2200	V
		min.	1350	V
Control grid voltage	$-V_{g1}$	max.	200	V
		min.	0	V
Cathode to heater voltage	V_{kf}	max.	125	V
	$-V_{kf}$	min.	125	V
Voltage between astigmatism control electrode and any deflection plate	$V_{g4/x}$	max.	500	V
	$V_{g4/y}$	max.	500	V
Grid drive, average		max.	20	V
Screen dissipation	W_ℓ	max.	8	mW/cm^2
Ratio $V_{g7(\ell)}/V_{g2,g4}$	$V_{g7(\ell)}/V_{g2,g4}$	max.	6,7	
Control grid circuit resistance	R_{g1}	max.	1	MΩ

Notes see page 5.

NOTES

1) In order to align the x-trace with the horizontal axis of the screen, the whole picture can be rotated by means of a rotation coil. This coil will have 50 amp. turns for the indicated max. rotation of 5^o and should be positioned as indicated in the drawing.
2) This tube is designed for optimum performance when operating at a ratio $V_{g7}/V_{g2,g4} = 5$.
   The geometry electrode voltage should be adjusted within the indicated range (values with respect to the mean x-plate potential).
   A negative control voltage will cause some pincushion distortion and less background light, a positive control voltage will give some barrel distortion and a slight increase of background light.
3) The deflection plate shield voltage should be equal to the mean y-plate potential. The mean x- and y-plate potentials should be equal for optimum spot quality.
4) The astigmatism control electrode voltage should be adjusted for optimum spot shape. For any necessary adjustment its potential will be within the stated range.
5) The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.
6) A graticule, consisting of concentric rectangles of 115 mm x 95 mm and 112,2 mm x 93,0 mm is aligned with the electrical x-axis of the tube, with optimum correction potentials applied, a raster will fall between these rectangles.

INSTRUMENT CATHODE-RAY TUBE

Cathode-ray tube for monitoring purposes.

QUICK REFERENCE DATA			
Accelerator voltage	$V_{g3}(\ell)$	800	V
Display area	Both directions full scan		
Deflection coefficient, horizontal	M_x	62,5	V/cm
vertical	M_y	40	V/cm

SCREEN

	colour	persistence
DG7-5	yellowish green	medium short

Useful screen diameter > 65 mm

Useful scan

horizontal full scan

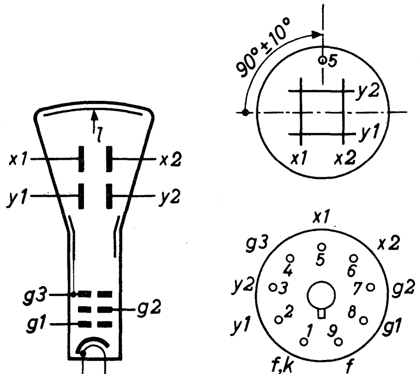
vertical full scan

HEATING

Indirect by a.c. or d.c.; parallel supply

Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

MECHANICAL DATA Dimensions in mm



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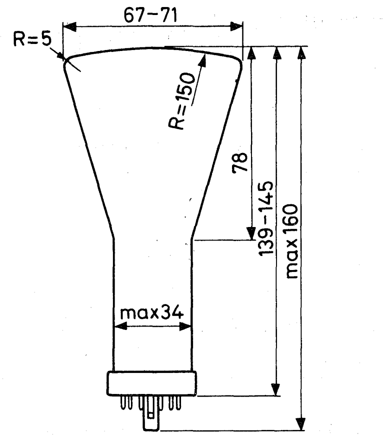

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Mounting position:

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Base English Loctal 9-pin

Dimensions and connections

See also outline drawing

Overall length	<	160	mm
Face diameter	<	71	mm
Net mass:	approx.	140	g

Accessories

Mu-metal shield type 55530

CAPACITANCES

x_1 to all other elements except x_2	$C_{x_1(x_2)}$	2,8	pF
x_2 to all other elements except x_1	$C_{x_2(x_1)}$	2,8	pF
y_1 to all other elements except y_2	$C_{y_1(y_2)}$	3,0	pF
y_2 to all other elements except y_1	$C_{y_2(y_1)}$	3,3	pF
x_1 to x_2	$C_{x_1x_2}$	0,8	pF
y_1 to y_2	$C_{y_1y_2}$	0,6	pF
Control grid to all other elements	C_{g_1}	7,0	pF
Cathode to all other elements	C_k	3,2	pF

FOCUSING electrostatic

DEFLECTION double electrostatic

x plates symmetrical

y plates symmetrical

Angle between x and y traces $90^o \pm 1,5^o$

LINE WIDTH

Measured on a circle of 50 mm diameter

Accelerator voltage	$V_{g_3(\ell)}$	800	V
Beam current	$I_{(\ell)}$	0,5	μA
Line width	l.w.	0,4	mm

TYPICAL OPERATING CONDITIONS

Accelerator voltage	$V_{g_3(\ell)}$	800	V
Focusing electrode voltage	V_{g_2}	200 to 300	V
Control grid voltage for visual extinction of focused spot	$-V_{g_1}$	max. 50	V
Deflection coefficient, horizontal	M_x	53 to 72	V/cm
vertical	M_y	33 to 45	V/cm
Geometry distortion		See note 1 page 4	
Useful scan, horizontal		full scan	
vertical		full scan	

LIMITING VALUES (Absolute max. rating system)

Accelerator voltage	$V_{g_3(\ell)}$	max.	1000	V
		min.	800	V
Focusing electrode voltage	V_{g_2}	max.	400	V
Control grid voltage				
negative	$-V_{g_1}$	max.	200	V
positive	V_{g_1}	max.	0	V
positive peak	$V_{g_{1p}}$	max.	2	V
Cathode to heater voltage				
cathode positive	$V_{+k/f-}$	max.	200	V
cathode negative	$V_{-k/f+}$	max.	125	V
Voltage between accelerator electrode and any deflection plate	$V_{g_3/x}$	max.	500	V
	$V_{g_3/y}$	max.	500	V
Screen dissipation	W_ℓ	max.	3	mW/cm^2

CIRCUIT DESIGN VALUES

Focusing voltage	V_{g_2}	250 to 375	V per kV of V_{g_3}
Control grid voltage for visual extinction of focused spot	$-V_{g_1}$	0 to 62,5	V per kV of V_{g_3}
Deflection coefficient			
horizontal	M_x	66 to 90	V/cm per kV of V_{g_3}
vertical	M_y	41 to 56	V/cm per kV of V_{g_3}
Control grid circuit resistance	R_{g_1}	max. 0,5	MΩ
Deflection plate circuit resistance	R_x, R_y	max. 5	MΩ

[1]) A graticule, consisting of concentric rectangles of 43.2 mm x 43.2 mm and 40 mm x 40 mm is aligned with the electrical x axis of the tube. The edges of a raster will fall between these rectangles with optimum correction potentials applied.

INSTRUMENT CATHODE-RAY TUBE

Cathode-ray tube for monitoring purposes.

QUICK REFERENCE DATA

Accelerator voltage	$V_{g3(\ell)}$	800 V
Display area	Both directions full scan	
Deflection coefficient		
horizontal	M_x	62,5 V/cm
vertical	M_y	40 V/cm

SCREEN

	Colour	Persistence
DG7-6	yellowish green	medium short

Useful screen diameter	>	65 mm
Useful scan		
horizontal	full scan	
vertical	full scan	

HEATING: Indirect by a.c. or d.c.; parallel supply

Heater voltage	V_f	6,3 V
Heater current	I_f	300 mA

MECHANICAL DATA

Dimensions and connections

See also outline drawing

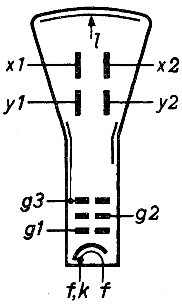
Overall length	<	160 mm
Faceplate diameter	<	71 mm

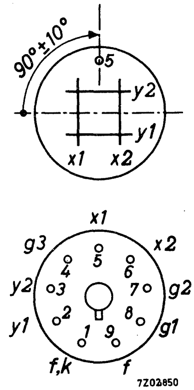
Net mass	approx.	140 g

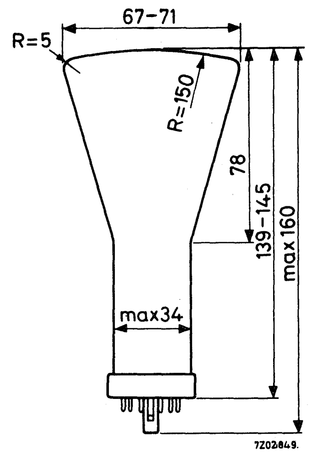
Accessories

Mu-metal shield	type	55530

Dimensions in mm







Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Base English loctal 9-pin

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	2,8	pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	2,8	pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	3,0	pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	3,3	pF
x_1 to x_2	C_{x1x2}	0,8	pF
y_1 to y_2	C_{y1y2}	0,6	pF
Control grid to all other elements	C_{g1}	7,0	pF
Cathode to all other elements	C_k	3,2	pF

FOCUSING electrostatic

DEFLECTION double electrostatic

x plates	asymmetrical x_1 has to be connected to the accelerator electrode. Earthing of the accelerator electrode is recommended.
y plates	symmetrical
Angle between x and y traces	$90^o \pm 1,5^o$

LINE WIDTH

Measured on a circle of 50 mm diameter

Accelerator voltage	$V_{g3(\ell)}$	800	V
Beam current	I_ℓ	0,5	μA
Line width	l.w.	0,4	mm

TYPICAL OPERATING CONDITIONS

Accelerator voltage	$V_{g3(\ell)}$	800	V
Focusing electrode voltage	V_{g2}	200 to 300	V
Control grid voltage for visual extinction of focused spot	V_{g1}	< -50	V
Deflection coefficient, horizontal	M_x	53 to 72	V/cm
vertical	M_y	33 to 45	V/cm
Geometry distortion	see note 1		
Useful scan, horizontal	full scan		
vertical	full scan		

[1]) A graticule consisting of concentric rectangles of 43, 2 mm x 43, 2 mm and 40 mm x 40 mm is aligned with the electrical x axis of the tube. The edges of a raster will fall between these rectangles with optimum correction potentials applied.

LIMITING VALUES (Absolute max. rating system)

Accelerator voltage	$V_{g3(\ell)}$	max.	1000	V
		min.	800	V
Focusing electrode voltage	V_{g2}	max.	400	V
Control grid voltage, negative	$-V_{g1}$	max.	200	V
positive	V_{g1}	max.	0	V
positive peak	V_{g1_p}	max.	2	V
Cathode to heater voltage, positive	V_{kf}	max.	200	V
negative	$-V_{kf}$	max.	125	V
Voltage between accelerator electrode and any deflection plate	$V_{g3/x}$	max.	500	V
	$V_{g3/y}$	max.	500	V
Screen dissipation	W_ℓ	max.	3	mW/cm^2

CIRCUIT DESIGN VALUES

Focusing voltage	V_{g2}	250 to 375	V per kV of V_{g3}
Control grid voltage for visual extinction of focused spot	V_{g1}	0 to -62,5	V per kV of V_{g3}
Deflection coefficient, horizontal	M_x	66 to 90	V/cm per kV of V_{g3}
vertical	M_y	41 to 56	V/cm per kV of V_{g3}
Control grid circuit resistance	R_{g1}	max. 0,5	MΩ
Deflection plate circuit resistance	R_x, R_y	max. 5	MΩ

INSTRUMENT CATHODE-RAY TUBE

Low accelerator voltage cathode-ray tube with asymmetrical deflection, intended for monitoring purposes.

QUICK REFERENCE DATA

Final accelerator voltage	$V_{g4,g2,(\ell)}$	500 V
Display area	Both directions full scan	
Deflection coefficient, horizontal	M_x	37 V/cm
vertical	M_y	21 V/cm

SCREEN

	Colour	Persistence
DG7—31	yellowish green	medium short

Useful diameter	>	65 mm
Useful scan, horizontal	full scan	
vertical	full scan	

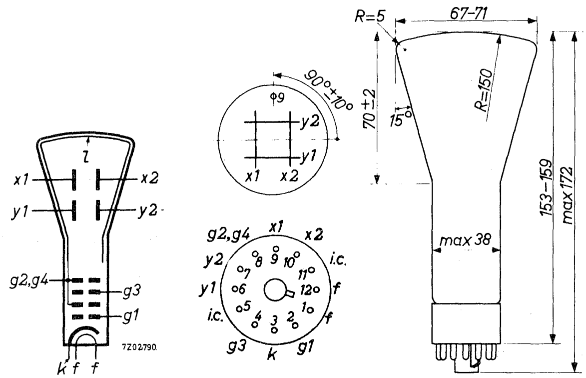
HEATING

Indirect by a.c. or d.c.; parallel supply

Heater voltage	V_f	6,3 V
Heater current	I_f	300 mA

MECHANICAL DATA

Dimensions in mm



Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Base   Duodecal 12 pin

Dimensions and connections

See also outline drawing

Overall length	<	172	mm
Face diameter	<	71	mm

Net mass   approx. 120 g

Accessories

Mu-metal shield   type   55530

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	3,7	pF
x2 to all other elements except x_1	$C_{x2(x1)}$	3,0	pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	2,5	pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	2,5	pF
x_1 to x_2	C_{x1x2}	1,7	pF
y_1 to y_2	C_{y1y2}	1,0	pF
Control grid to all other elements	C_{g1}	7,6	pF
Cathode to all other elements	C_k	3,2	pF

FOCUSING electrostatic

DEFLECTION double electrostatic

x plates asymmetrical

y plates symmetrical

Angle between x and y traces $90^o \pm 1,5^o$

LINE WIDTH

Measured on a circle of 50 mm diameter

Accelerator voltage	$V_{g4g2(\ell)}$	500	V
Beam current	I_ℓ	0,5	µA
Line width	l.w.	0,4	mm

TYPICAL OPERATING CONDITIONS

Accelerator voltage	$V_{g4g2(\ell)}$	500	V
Focusing electrode voltage	V_{g3}	0 to 120	V
Control grid voltage for visual extinction of focused spot	V_{g1}	-50 to -100	V
Deflection coefficient, horizontal	M_x	33,3 to 41,5	V/cm
vertical	M_y	18,8 to 23,2	V/cm
Geometry distortion		see note 1, page 4	
Useful scan, horizontal		full scan	
vertical		full scan	

LIMITING VALUES (Absolute max. rating system)

Accelerator voltage	$V_{g4g2(\ell)}$	max.	800	V
		min.	400	V
Focusing electrode voltage	V_{g3}	max.	200	V
Control grid voltage, negative	$-V_{g1}$	max.	200	V
positive	V_{g1}	max.	0	V
positive peak	V_{g1_p}	max.	2	V
Cathode to heater voltage, positive	V_{kf}	max.	200	V
negative	$-V_{kf}$	max.	125	V
Voltage between accelerator electrode and any deflection plate	$V_{g4/x}$	max.	500	V
	$V_{g4/y}$	max.	500	V
Screen dissipation	W_{ℓ}	max.	3	mW/cm^2

CIRCUIT DESIGN VALUES

Control grid circuit resistance	R_{g1}	max.	0,5	MΩ
Deflection plate circuit resistance	R_x, R_y	max.	5	MΩ
Focusing electrode current	I_{g3}	-15 to	+10	μA [2]

[1]) A graticule, consisting of concentric rectangles of 43, 2 mm x 43, 2 mm and 40 mm x 40 mm is aligned with the electrical x-axis of the tube. The edges of a raster will fall between these rectangles with optimum correction potentials applied.

[2]) Values to be taken into account for the calculation of the focus potentiometer.

Remark: A contrast improving transparent conductive coating connected to $g_4g_2(\ell)$ is present between glass and fluorescent layer. This enables the application of a high potential to $g_4g_2(\ell)$ with respect to earth, without the risk of picture distortion by touching the face (electrostatic body-effect).

INSTRUMENT CATHODE-RAY TUBE

Low accelerator voltage cathode-ray tube with symmetrical deflection, intended for monitoring purposes.

QUICK REFERENCE DATA

Final accelerator voltage	$V_{g4,g2,(\ell)}$	500 V
Display area	Both directions full scan	
Deflection coefficient, horizontal	M_x	37 V/cm
vertical	M_y	21 V/cm

SCREEN

	Colour	Persistence
DG7–32	yellowish green	medium short

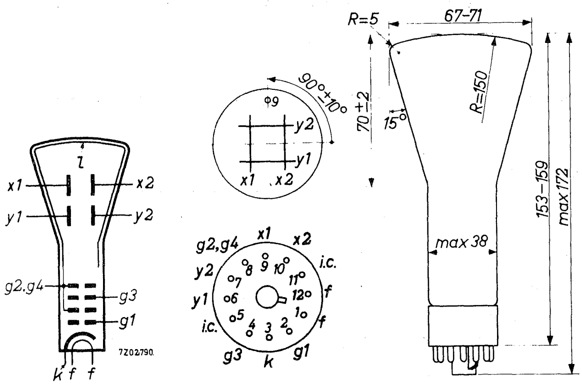
Useful diameter	>	65 mm
Useful scan, horizontal		full scan
vertical		full scan

HEATING

Indirect by a.c. or d.c.; parallel supply

Heater voltage	V_f	6,3 V
Heater current	I_f	300 mA

MECHANICAL DATA Dimensions in mm



Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Base Duodecal 12 pin

Dimensions and connections

See also outline drawing

Overall length	<	172	mm
Face diameter	<	71	mm
Net mass	approx.	120	g

Accessories

Mu-metal shield type 55530

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	3,7	pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	3,0	pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	2,5	pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	2,5	pF
x_1 to x_2	C_{x1x2}	1,7	pF
y_1 to y_2	C_{y1y2}	1,0	pF
Control grid to all other elements	C_{g1}	7,6	pF
Cathode to all other elements	C_k	3,2	pF

FOCUSING electrostatic

DEFLECTION double electrostatic

x plates symmetrical

y plates symmetrical

Angle between x and y traces $90^o \pm 1,5^o$

LINE WIDTH

Measured on a circle of 50 mm diameter

Accelerator voltage	$V_{g4g2(\ell)}$	500	V
Beam current	I_ℓ	0,5	µA
Line width	l.w.	0,4	mm

TYPICAL OPERATING CONDITIONS

Accelerator voltage	$V_{g4g2(\ell)}$	500	V
Focusing electrode voltage	V_{g3}	0 to 120	V
Control grid voltage for visual extinction of focused spot	V_{g1}	-50 to -100	V
Deflection coefficient, horizontal	M_x	33,3 to 41,5	V/cm
vertical	M_y	18,8 to 23,2	V/cm
Geometry distortion		see note 1, page 4	
Useful scan, horizontal		full scan	
vertical		full scan	

LIMITING VALUES (Absolute max. rating system)

Accelerator voltage	$V_{g4g2(\ell)}$	max. min.	800 400	V V
Focusing electrode voltage	V_{g3}	max.	200	V
Control grid voltage, negative	$-V_{g1}$	max.	200	V
positive	V_{g1}	max.	0	V
positive peak	V_{g1_p}	max.	2	V
Cathode to heater voltage, positive	V_{kf}	max.	200	V
negative	$-V_{kf}$	max.	125	V
Voltage between accelerator electrode and any deflection plate	$V_{g4/x}$	max.	500	V
	$V_{g4/y}$	max.	500	V
Screen dissipation	W_{ℓ}	max.	3	mW/cm^2

CIRCUIT DESIGN VALUES

Control grid circuit resistance	R_{g1}	max.	0,5	MΩ
Deflection plate circuit resistance	R_x, R_y	max.	5	MΩ
Focusing electrode current	I_{g3}	-15 to +10		μA [2]

---

1) A graticule, consisting of concentric rectangles of 43,2 mm x 43,2 mm and 40 mm x 40 mm is aligned with the electrical x- axis of the tube. The edges of a raster will fall between these ractangles with optimum correction potentials applied.

2) Values to be taken into account for the calculation of the focus potentiometer.

Remark: A contrast improving transparent conductive coating connected to $g_4g_2(\ell)$ is present between glass and fluorescent layer. This enables the application of a high potential to $g_4g_2(\ell)$ with respect to earth, without the risk of picture distortion by touching the face (electrostatic body-effect).

INSTRUMENT CATHODE-RAY TUBE

Low accelerator voltage cathode-ray tube for monitoring purpose.

QUICK REFERENCE DATA

Accelerator voltage	$V_{g4,g2,y2,(\ell)}$	500	V
Display area	Both directions full scan		
Deflection coefficient, horizontal	M_x	56,5	V/cm
vertical	M_y	49	V/cm

SCREEN

	Colour	Persistence
DH3–91	green	medium short

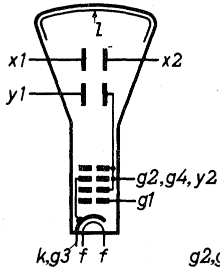
Useful screen diameter	min.	28	mm
Useful scan, horizontal	full scan		
vertical	full scan		

HEATING

Indirect by a.c. or d.c.; parallel supply

Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

MECHANICAL DATA Dimensions in mm



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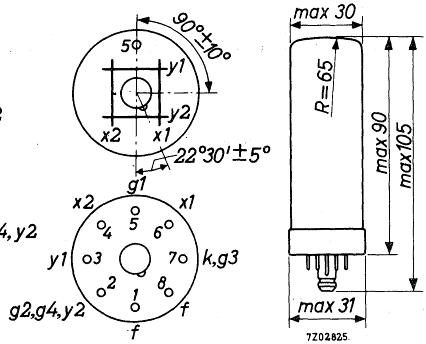


7Z02825.

Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Base:	English Loctal 8-pin	

Dimensions and connections

See also outline drawing

Overall length	<	105 mm
Face diameter	<	30 mm
Net mass:	approx.	39 g

Accessories

Mu-metal shield	type	55525

CAPACITANCES

x_1 to all other elements except x_2	$C_{x_1(x_2)}$	4,5	pF
x_2 to all other elements except x_1	$C_{x_2(x_1)}$	4,5	pF
y_1 to all other elements except y_2	$C_{y_1(y_2)}$	3,5	pF
x_1 to x_2	$C_{x_1 x_2}$	1,0	pF
Control grid to all other elements	C_{g_1}	5,6	pF

FOCUSING electrostatic self focusing

DEFLECTION	double electrostatic
x plates	symmetrical
y plates	asymmetrical

LINE WIDTH

Measured on a circle of 25 mm diameter

Accelerator voltage	$V_{g_4, g_2, y_2(\ell)}$	500	V
Beam current	$I(\ell)$	0,5	μA
Line width	l.w.	0,6	mm

TYPICAL OPERATING CONDITIONS

Accelerator voltage	$V_{g_4, g_2, y_2(\ell)}$	500	V
Control grid voltage for visual extinction of focused spot	$-V_{g_1}$	8 to 27	V
Deflection coefficient			
horizontal	M_x	41 to 72	V/cm
vertical	M_y	35 to 63	V/cm
Useful scan			
horizontal		full scan	
vertical		full scan	

LIMITING VALUES (Absolute max. rating system)

Accelerator voltage	$V_{g_4, g_2, y_2(\ell)}$	max.	1000	V
		min.	350	V
Control grid voltage				
negative	$-V_{g_1}$	max.	200	V
positive	V_{g_1}	max.	0	V
positive peak	$V_{g_{1p}}$	max.	2	V
Cathode to heater voltage				
cathode positive	$V_{+k/f-}$	max.	200	V
cathode negative	$V_{-k/f+}$	max.	125	V
Screen dissipation	W_ℓ	max.	3	mW/cm^2

CIRCUIT DESIGN VALUES

Control grid voltage for visual extinction of focused spot	$-V_{g_1}$	16 to 54	V per kV of V_{g_4, g_2, y_2}
Deflection coefficient			
horizontal	M_x	90 to 120	V/cm per kV of V_{g_4, g_2, y_2}
vertical	M_y	38,5 to 52,5	V/cm per kV of V_{g_4, g_2, y_2}
Control grid circuit resistance	R_{g_1}	max. 1	MΩ
Deflection plate circuit resistance	R_x, R_y	max. 5	MΩ

REMARK

A contrast improving transparent conductive coating connected to the accelerator electrode is present between glass and fluorescent layer. This enables the application of a high potential with respect to earth to the accelerator electrode, without the risk of picture distortion by touching the face (electrostatic body-effect).

INSTRUMENT CATHODE-RAY TUBE

Oscilloscope tube with 7 cm diameter flat face and post deflection acceleration by means of a helical electrode. The low heater consumption together with the high sensitivity render this tube suitable for transistorized equipment.

QUICK REFERENCE DATA			
Final accelerator voltage	$V_{g6(\ell)}$	1200	V
Display area		4,5 x 6	cm^2
Deflection coefficient, horizontal	M_x	10,7	V/cm
vertical	M_y	3,65	V/cm

SCREEN

	Colour	Persistence
DH7-11	green	medium short
DN7-11	bluish green	medium short
DP7-11	yellowish green	long

Useful diameter	>	68	mm
Useful scan at $V_{g6(\ell)}/V_{g4} = 4$, horizontal	>	60	mm
vertical	>	45	mm

HEATING : Indirect by a.c. or d.c.; parallel supply

Heater voltage	V_f	6,3	V
Heater current	I_f	95	mA

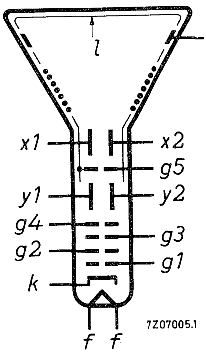
MECHANICAL DATA

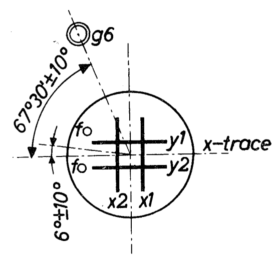
Dimensions and connections

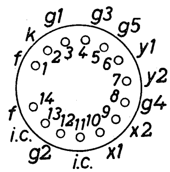
See also outline drawing

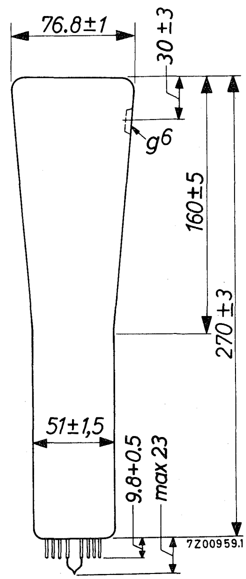
Overall length	<	296	mm
Face diameter	<	77,8	mm
Net mass	approx.	370	g

Dimensions in mm









Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Base 14 pin all glass

Accessories

Socket (supplied with tube)	type	40467
Final accelerator contact connector	type	55563A
Mu-metal shield	type	55532

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	4,0	pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	4,0	pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	3,5	pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	3,5	pF
x_1 to x_2	C_{x1x2}	1,9	pF
y_1 to y_2	C_{y1y2}	1,7	pF
Control grid to all other elements	C_{g1}	5,7	pF
Cathode to all other elements	C_k	3,0	pF

FOCUSING electrostatic

DEFLECTION double electrostatic

x plates symmetrical

y plates symmetrical

If use is made of the full deflection capabilities of the tube the deflection plates will intercept part of the electron beam; hence a low impedance deflection plate drive is desirable.

Angle between x and y traces $90^{\circ} \pm 1^{\circ}$

LINE WIDTH

Measured with the shrinking raster method in the centre of the screen.

Final accelerator voltage	$V_{g6(\ell)}$	1200	V	
Astigmatism control electrode voltage	V_{g4}	300	V	2)
First accelerator voltage	V_{g2}	1200	V	
Beam current	I_{ℓ}	10	μA	
Line width	l.w.	0,65	mm	

HELIX

Post deflection accelerator helix resistance		> 40	MΩ	

TYPICAL OPERATING CONDITIONS

Final accelerator voltage	$V_{g6(\ell)}$	1200	V	
Geometry control electrode voltage	V_{g5}	300 ± 30	V	1)
Astigmatism control electrode voltage	V_{g4}	$300\ ^{+40}_{-15}$	V	2)
Focusing electrode voltage	V_{g3}	20 to 150	V	
First accelerator voltage	V_{g2}	1200	V	
Control grid voltage for visual extinction of focused spot	V_{g1}	-30 to -80	V	
Deflection coefficient, horizontal	M_x	9,4 to 12	V/cm	
vertical	M_y	3,2 to 4,1	V/cm	
Deviation of linearity of deflection		< 2	%	3)
Geometry distortion		see note 4		
Useful scan, horizontal		> 60	mm	
vertical		> 40	mm	

Notes see page 5.

CIRCUIT DESIGN VALUES

Focusing voltage	V_{g3}	35 to 165	V per kV of V_{g4}
Control grid voltage for visual extinction of focused spot	V_{g1}	-30 to -60	V per kV of V_{g2}
Deflection coefficient at $V_{g6(\ell)}/V_{g4} = 4$			
horizontal	M_x	31,3 to 40,0	V/cm per kV of V_{g4}
vertical	M_y	10,7 to 13,7	V/cm per kV of V_{g4}
Control grid circuit resistance	R_{g1}	max. 1,5	MΩ
Deflection plate circuit resistance	R_x, R_y	max. 50	kΩ
Focusing electrode current	I_{g3}	-15 to +10	μA [5]

LIMITING VALUES (Absolute max. rating system)

Final accelerator voltage	$V_{g6(\ell)}$	max.	5000	V
		min.	1200	V
Geometry control electrode voltage	V_{g5}	max.	2200	V
Astigmatism control electrode voltage	V_{g4}	max.	2100	V
		min.	300	V
Focusing electrode voltage	V_{g3}	max.	1000	V
First accelerator voltage	V_{g2}	max.	1600	V
		min.	800	V
Control grid voltage, negative	$-V_{g1}$	max.	200	V
positive	V_{g1}	max.	0	V
positive peak	V_{g1_p}	max.	2	V
Cathode to heater voltage, positive	V_{kf}	max.	100	V
negative	$-V_{kf}$	max.	15	V
Voltage between astigmatism control electrode and any deflection plate	$V_{g4/x}$	max.	500	V
	$V_{g4/y}$	max.	500	V
Screen dissipation	W_ℓ	max.	3	W/cm^2
Ratio $V_{g6(\ell)}/V_{g4}$	$V_{g6(\ell)}/V_{g4}$	max.	4	

Notes see page 5

NOTES

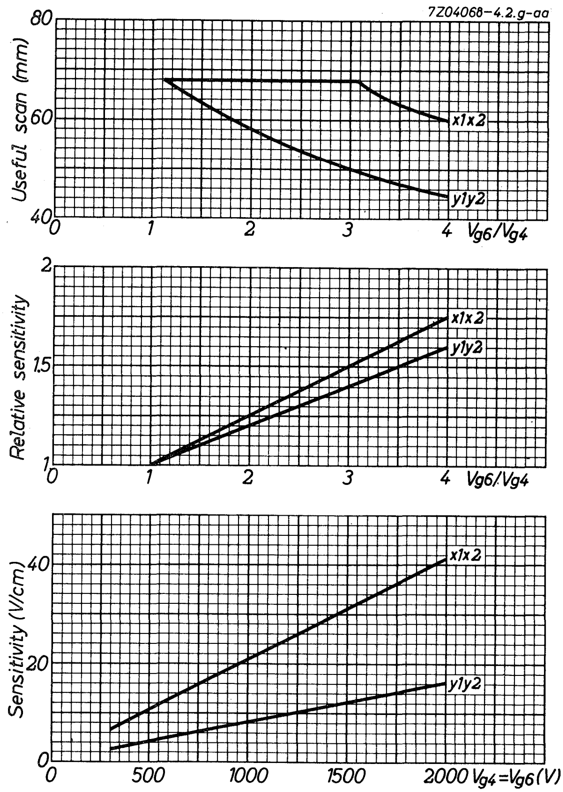
[1]) This tube is designed for optimum performance when operating at the ratio $V_{g6(\ell)}/V_{g4} = 4$. Operation at other ratio may result in changes in deflection uniformity and geometry distortion. The geometry control electrode voltage should be adjusted for optimum performance. For any necessary adjustment its potential will be within the stated range.

[2]) The astigmatism control electrode voltage should be adjusted for optimum spot shape. For any necessary adjustment its potential will be within the stated range.

[3]) The sensitivity at a defelction of less than 75% of the useful scan will not differ from the sensitivity of 25% of the useful scan by more than the indicated value.

[4]) A graticule consisting of concentric rectangles of 40, 8 mm x 40, 8 mm and 39, 2 mm x 39, 2 mm is aligned with the electrical x axis of the tube. The edges of a raster will fall between these rectangles with optimum correction potentials applied.

[5]) Values to be taken into account for the calculation of the focus potentiometer.


7Z04068-4.2.g-aa
Useful scan (mm)
80
60
40
0
1
2
3
4
Vg6/Vg4
x1x2
y1y2
Relative sensitivity
2
1.5
1
0
1
2
3
4
Vg6/Vg4
x1x2
y1y2
Sensitivity (V/cm)
40
20
0
0
500
1000
1500
2000
Vg4=Vg6(V)
x1x2
y1y2

INSTRUMENT CATHODE-RAY TUBE

10 cm diameter flat faced double gun oscilloscope tube, post-deflection acceleration by means of a helical electrode and low interaction between traces. The tube features beam-blanking.

QUICK REFERENCE DATA			
Final accelerator voltage	$V_{g_8}(\ell)$	3000	V
Display area	horizontal full scan		
	vertical	7	cm
Deflection coefficient, horizontal	M_x	15	V/cm
vertical	M_y	7	V/cm

SCREEN

	colour	persistence
E10-12GH	green	medium short
E10-12GM	yellowish green	long
E10-12GP	bluish green	medium short

Useful screen diameter min. 85 mm

Useful scan (each gun) at $V_{g_8}(\ell)/V_{g_5} = 3$

horizontal	full scan	
vertical	min. 70	mm

The useful scan may vertically be shifted to a max. of 5 mm with respect to the geometric centre of the face plate.

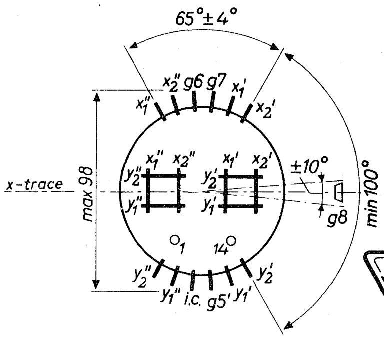
HEATING

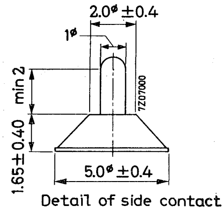
Indirect by A.C. or D.C.; parallel supply

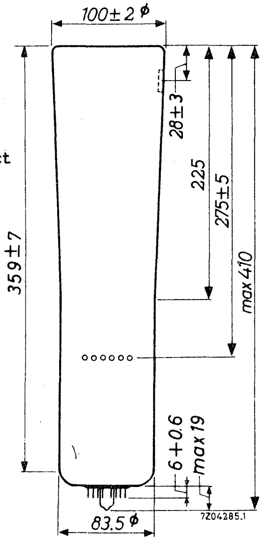
Heater voltage	each gun	V_f	6.3	V
Heater current	each gun	I_f	300	mA

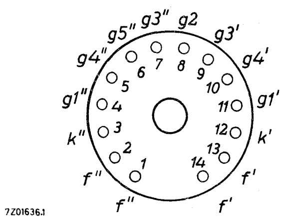
MECHANICAL DATA

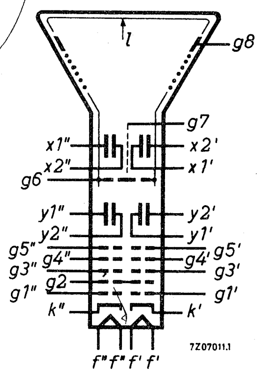
Dimensions in mm











Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Base	14 pin all glass		
Dimensions and connections			
Overall length	max.	410	mm
Face diameter	max.	102	mm
Net weight	approx.	800	g

Accessories

Socket, supplied with tube	type	55566
Final accelerator contact connector	type	55563A
Side contact connector	type	55561
Mu-metal shield	type	55545

CAPACITANCES (each gun)

x_1' to all elements except x_2'	$C_{x_1'(x_2')}$	4.5	pF
x_2' to all elements except x_1'	$C_{x_2'(x_1')}$	3	pF
x_1'' to all other elements except x_2''	$C_{x_1''(x_2'')}$	3	pF
x_2'' to all other elements except x_1''	$C_{x_2''(x_1'')}$	4.5	pF
y_1 to all other elements except y_2	$C_{y_1(y_2)}$	2	pF
y_2 to all other elements except y_1	$C_{y_2(y_1)}$	2	pF
x_1 to x_2	$C_{x_1x_2}$	2	pF
y_1 to y_2	$C_{y_1y_2}$	1.5	pF
Grid No.1 to all other elements	C_{g_1}	5.2	pF
Cathode to all other elements	C_k	5	pF

FOCUSING electrostatic

DEFLECTION double electrostatic

x plates symmetrical

y plates symmetrical

Angle between x and y traces 90 ± 1^o
Angle between x-traces $\pm 0.8^o$ max. in the centre of the screen.
Angle between y-traces $\pm 1^o$ max. in the centre of the screen.

If use is made of the full deflection capabilities of the tube the deflection plates will intercept part of the electron beam; hence a low impedance deflection plate drive is desirable.

LINE WIDTH

Measured with the shrinking raster method in the centre of the screen.

Final accelerator voltage	$V_{g_8(\ell)}$	3000	V
Astigmatism control electrode voltage	V_{g_5}	1000	V [3]
First accelerator voltage	V_{g_2}	1000	V
Beam current	$I_{g_8(\ell)}$	10	μA
Line width	l.w.	0.50	mm

HELIX

Post deflection accelerator helix resistance: min. 100 MΩ

[3]) See page 6.

TYPICAL OPERATING CONDITIONS(each gun)

Final accelerator voltage	$V_{g_8}(\ell)$	3000	V
Intergun shield voltage	V_{g_7}	1000±100	V [1]
Geometry control electrode voltage	V_{g_6}	1000±100	V [1] [2]
Astigmatism control electrode voltage	V_{g_5}	1000±100	V [3]
Focusing electrode voltage	V_{g_4}	180 to 380	V
Deflection blanking electrode voltage	V_{g_3}	1000	V
Deflection blanking control voltage for beam blanking of a current $I_{g_9}(\ell)$ = 10 μA	ΔV_{g_3}	max. 40	V
First accelerator voltage	V_{g_2}	1000	V
Control grid voltage for visual extinction of focused spot	V_{g_1}	-25 to -90	V
Deflection coefficient, horizontal	M_x	12 to 18	V/cm
vertical	M_y	6 to 8	V/cm
Deviation of linearity of deflection		max. 2.5	% [4]
Geometry distortion		See note 5	
Interaction factor		2.10^{-3}	mm/Vdc [6]
Tracking error		1.5	mm [7]

[1] [2] [3] [4] [5] [6] [7] See page 6

LIMITING VALUES (each gun, if applicable) (Absolute max. rating system)

Final accelerator voltage	$V_{g_8}(\ell)$	max.	3300	V
		min.	2700	V
Intergun shield voltage	V_{g_7}	max.	1200	V
Geometry control electrode voltage	V_{g_6}	max.	1200	V
Astigmatism control electrode voltage	V_{g_5}	max.	1200	V
		min.	800	V
Focusing electrode voltage	V_{g_4}	max.	1200	V
Beam blanking electrode voltage	V_{g_3}	max.	1200	V
First accelerator voltage	V_{g_2}	max.	1200	V
		min.	200	V
Control grid voltage,				
negative	$-V_{g_1}$	max.	200	V
positive	V_{g_1}	max.	0	V
positive peak	$V_{g_{1p}}$	max.	2	V
Cathode to heater voltage,				
cathode positive	V_{kf}	max.	200	V
cathode negative	$-V_{kf}$	max.	125	V
Average cathode current	I_k	max.	300	μA
Screen dissipation	W_ℓ	max.	3	mW/cm^2
Ratio $V_{g_8}(\ell)/V_{g_5}$	$V_{g_8}(\ell)/V_{g_5}$	max.	3	

CIRCUIT DESIGN VALUES (each gun, if applicable)

Focusing voltage	V_{g4}	180 to 380	V/kV of V_{g2}
Control grid voltage for visual cut-off focused spot	V_{g1}	25 to -90	V/kV of V_{g2}
Deflection coefficient $V_{g8}(\ell)/V_{g5}$ = 3			
horizontal	M_x	10 to 20	V/cm per kV of V_{g5}
vertical	M_y	6 to 8	V/cm per kV of V_{g5}
Focusing electrode current	I_{g4}	-15 to +10	μA
Control grid circuit resistance	R_{g1}	max. 1.5	MΩ

---

1) This tube is designed for optimum performance when operating at the ratio $V_{g8}(\ell)/V_{g5}$ = 3. Operation at other ratio may result in changes in deflection uniformity and geometry distortion. The geometry control electrode voltage and the intergunshield voltage should be adjusted for optimum performance. For any necessary adjustment its potential will be within the stated range.

2) This voltage should be equal to the mean x- and y plates potential.

3) The astigmatism control electrode voltage should be adjusted for optimum spot shape. For any necessary adjustment its potential will be within the stated range.

4) The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.

5) A graticule consisting of concentric rectangles of 60 mm x 60 mm and 57 mm x 57 mm is aligned with electrical x axis of the tube. The edges of a raster will fall between these rectangles with optimum potentials applied.

6) The deflection of one beam when balanced dc voltage are applied to the deflection plates of the other beam, will not be greater than the indicated value.

7) With 50 mm vertical traces superimposed at the tube face centre and deflected horizontally ± 4 cm by voltages proportional to the relative deflection factors, horizontal separation of the corresponding points of the traces shall not be greater than the indicated value.

INSTRUMENT CATHODE-RAY TUBE

10 cm diameter metal-backed flat-faced double gun oscilloscope tube with post-deflection acceleration by means of a helical electrode and low interaction between beams.

QUICK REFERENCE DATA			
Final accelerator voltage	$V_{g8}(\ell)$	4000	V
Display area	horizontal		full scan
	vertical	7	cm
Deflection coefficient, horizontal	M_x	17	V/cm
vertical	M_y	7.4	V/cm

SCREEN

	Colour	Persistence
E10-130GH	green	medium short
E10-130GM	yellowish green	long
E10-130GP	bluish green	medium short

Useful screen diameter		min. 85	mm
Useful scan (each gun) at $V_{g8}(\ell)/V_{g5} = 4$	horizontal		full scan
	vertical	min. 70	mm

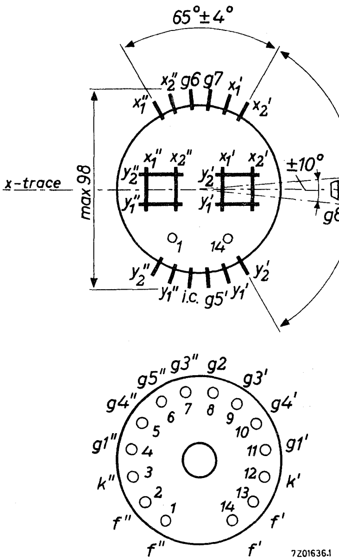
The useful scan may be shifted vertically to a maximum of 5 mm with respect to the geometric centre of the face plate.

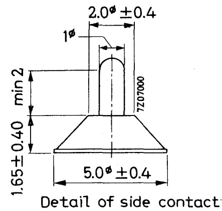
HEATING

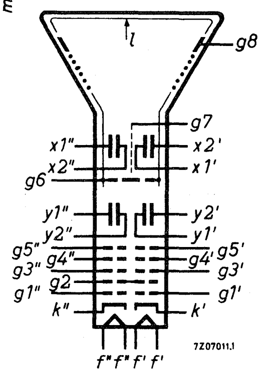
Indirect by A.C. or D.C.; parallel supply

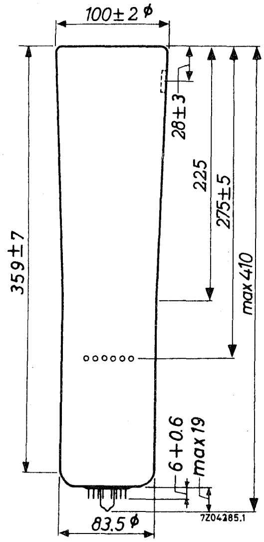
Heater voltage	V_f	6.3	V
Heater current	I_f	300	mA

MECHANICAL DATA









Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Base	14 pin, all glass		
Dimensions and connections			
Overall length	max.	410	mm
Face diameter	max.	102	mm
Net weight	approx.	800	g
Accessories			
Socket, supplied with tube	type	55566	
Final-accelerator contact connector	type	55563A	
Side contact connector	type	55561	
Mu-metal shield	type	55545	

CAPACITANCES

x_1' to all other elements except x_2'	$C_{x_1'(x_2')}$	4.5	pF
x_2' to all other elements except x_1'	$C_{x_2'(x_1')}$	3	pF
x_1'' to all other elements except x_2''	$C_{x_1''(x_2'')}$	3	pF
x_2'' to all other elements except x_1''	$C_{x_2''(x_1'')}$	4.5	pF
y_1 to all other elements except y_2	$C_{y_1(y_2)}$	2	pF
y_2 to all other elements except y_1	$C_{y_2(y_1)}$	2	pF
x_1 to x_2	$C_{x_1x_2}$	2	pF
y_1 to y_2	$C_{y_1y_2}$	1.5	pF
Grid No. 1 to all other elements	C_{g_1}	5.2	pF
Cathode to all other elements	C_k	5	pF

FOCUSING Electrostatic

DEFLECTION Double electrostatic

x plates	symmetrical	
y plates	symmetrical	
Angle between x and y traces (each gun)	90 ± 1	$^\circ$
Angle between corresponding x traces at the centre of the screen	max. 0.6	$^\circ$
Angle between corresponding y traces at the centre of the screen	max. 1	$^\circ$

If use is made of the full deflection capabilities of the tube the deflection plates will intercept part of the electron beam; hence a low impedance deflection plate drive is desirable.

LINE WIDTH

Measured with the shrinking-raster method in the centre of the screen.

Final accelerator voltage	$V_{g_8(\ell)}$	4000	V
Astigmatism-control electrode voltage	V_{g_5}	1000	V 2)
First accelerator voltage	V_{g_2}	1000	V
Beam current	$I_{g_8(\ell)}$	10	μA
Line width	l.w.	0.4	mm

HELIX

Post-deflection accelerator helix resistance	min.	100	MΩ

2) See page 5

TYPICAL OPERATING CONDITIONS (each gun, if applicable)

Final accelerator voltage	$V_{g_8(\ell)}$		4000	V	
Intergun shield voltage	V_{g_7}		1000±100	V	1)
Geometry-control electrode voltage	V_{g_6}		1000±100	V	1)
Astigmatism-control electrode voltage	V_{g_5}		1000±100	V	2)
Focusing electrode voltage	V_{g_4}		200 to 320	V	
Deflection-blanking electrode voltage	V_{g_3}		1000	V	
Deflection-blanking control voltage for blanking a beam current $I_{g_8(\ell)} = 10\ \mu A$	ΔV_{g_3}	max.	40	V	
First accelerator voltage	V_{g_2}		1000	V	
Control grid voltage for extinction of focused spot	V_{g_1}		−25 to −90	V	
Deflection coefficient, horizontal	M_x		14 to 20	V/cm	
vertical	M_y		6.4 to 8.4	V/cm	
Deviation of linearity of deflection		max.	2	%	3)
Geometry distortion			see note 4		
Interaction factor		max.	2.10^{-3}	mm/V_{DC}	5)
Tracking error			1.2	mm	6)

LIMITING VALUES (each gun, if applicable) (Absolute max. rating system)

Final accelerator voltage	$V_{g_8(\ell)}$	max.	5000	V
		min.	2700	V
Intergun shield voltage	V_{g_7}	max.	1200	V
Geometry control electrode voltage	V_{g_6}	max.	1200	V
Astigmatism control electrode voltage	V_{g_5}	max.	1200	V
		min.	800	V
Focusing electrode voltage	V_{g_4}	max.	1200	V
Beam blanking electrode voltage	V_{g_3}	max.	1200	V
First accelerator voltage	V_{g_2}	max.	1200	V
		min.	200	V
Control grid voltage, negative	$-V_{g_1}$	max.	200	V
positive	V_{g_1}	max.	0	V
Cathode to heater voltage,				
cathode positive	V_{kf}	max.	125	V
cathode negative	$-V_{kf}$	max.	125	V
Average cathode current	I_k	max.	300	μA
Screen dissipation	W_ℓ	max.	3	mW/cm^2
Ratio $V_{g_8(\ell)}/V_{g_5}$	$V_{g_8(\ell)}/V_{g_5}$	max.	4	

1) 2) 3) 4) 5) 6) See page 5

CIRCUIT DESIGN VALUES (each gun, if applicable)

Focusing voltage	V_{g_4}	200 to 320 V	per kV of V_{g_2}
Control grid voltage for extinction of focused spot	V_{g_1}	-25 to -90 V	per kV of V_{g_2}
Deflection coefficient at $V_{g_8}(\ell)/V_{g_5} = 4$			
horizontal	M_x	14 to 20 V/cm	per kV of V_{g_5}
vertical	M_y	6.4 to 8.4 V/cm	per kV of V_{g_5}
Focusing electrode current	I_{g_4}	-15 to +10 μA	
Control grid circuit resistance	R_{g_1}	max. 1.5 MΩ	

1) This tube is designed for optimum performance when operating at the ratio $V_{g_8}(\ell)/V_{g_5} = 4$. Operation at higher ratio may result in changes in deflection uniformity and geometry distortion. The geometry control electrode voltage and the intergun shield voltage should be adjusted for optimum performance. For any necessary adjustment its potential will be within the stated range.

2) The astigmatism control electrode voltage should be adjusted for optimum spot shape. For any necessary adjustment its potential will be within the stated range.

3) The sensitivity at a deflection of $\leq 75\%$ of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.

4) A graticule consisting of concentric rectangles of 60 mm x 60 mm and 57.5 mm x 57.5 mm is aligned with the electrical x axis of the tube. The edges of a raster will fall between these rectangles with optimum potentials applied.

5) The deflection of one beam when balanced DC voltages are applied to the deflection plates of the other beam, will not be greater than the indicated value.

6) With 50 mm vertical traces superimposed at the tube face centre and deflected horizontally $\pm$ 4 cm by voltages proportional to the relative deflection factors, horizontal separation of the corresponding points of the traces will not be greater than the indicated value.

INSTRUMENT CATHODE-RAY TUBE

14 cm diagonal, rectangular flat faced, split-beam oscilloscope tube with mesh and metal-backed screen.

QUICK REFERENCE DATA			
Final accelerator voltage	$V_{g7(\ell)}$	10	kV
Display area		100 x 80	mm^2
Deflection coefficient, horizontal	M_x	13,5	V/cm
vertical	M_y'	9	V/cm
	M_y''	9	V/cm
Overlap of the systems		100	%

SCREEN : Metal-backed phosphor

	Colour	Persistence
E14-100GH	green	medium short

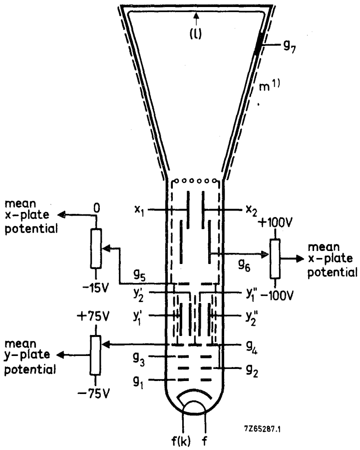
Useful screen dimensions	min.	100 x 80	mm^2
Useful scan at $V_{g7(\ell)}/V_{g2,g4} = 6,7$			
horizontal	min.	100	mm
vertical (each system)	min.	80	mm
overlap		100	%
Spot eccentricity in horizontal direction	max.	7	mm
in vertical direction	max.	10	mm

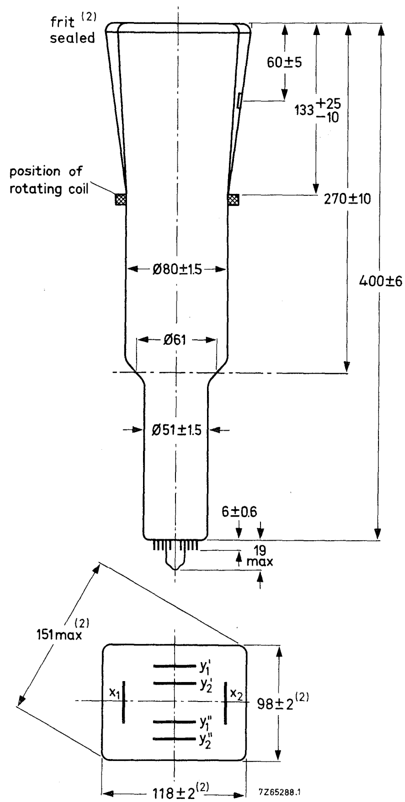
HEATING : indirect by A.C. or D.C. ; parallel supply

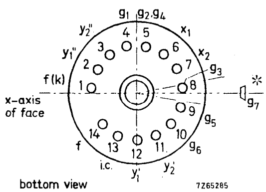
Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

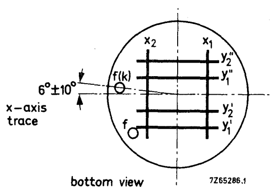
MECHANICAL DATA

Dimensions in mm









(1) The external conductive coating should be earthed.
(2) The bulge at the frit seal may increase the indicated maximum dimensions by not more than 2 mm.
* The centre of the contact is located within a square of 10 mm x 10 mm around the true geometrical position.

Mounting position: any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

MECHANICAL DATA (continued)

Dimensions and connections

See also outline drawing.

Overall length (socket included)	max.	425 mm
Face dimensions	max.	120 x 100 mm^2
Net weight	approx.	900 g
Base		14-pin all glass

Accessories

Socket (supplied with tube)	type	55566
Final accelerator contact connector	type	55563A

FOCUSING Electrostatic

DEFLECTION Double electrostatic
x-plates symmetrical
y-plates symmetrical

If the full deflection capacity of the tube is used, part of the beam is intercepted by the deflection plates; hence a low-impedance deflection plate drive is desirable.

Angle between x and y traces (each beam)		90 ± 1 °
Angle between corresponding y traces at screen centre	max.	45 '
Angle between x trace and horizontal axis of the face	max.	0 °

See page 6

LINE WIDTH

Measured with the shrinking raster method under typical operating conditions, and adjusted for optimum spot size at a beam current of 5 μA per system.

Line width at screen centre	l.w	approx.	0,35 mm

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	8 pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	8 pF
y_1' to all other elements except y_2'	$C_{y1'(y2')}$	4 pF
y_2' to all other elements except y_1'	$C_{y2'(y1')}$	5,5 pF
y_1'' to all other elements except y_2''	$C_{y1''(y2'')}$	5 pF
y_2'' to all other elements except y_1''	$C_{y2''(y1'')}$	4 pF
External conductive coating to all other elements	C_m	800 pF

CAPACITANCES (continued)

x_1 to x_2	$C_{x_1x_2}$	3 pF
y_1' to y_2'	$C_{y_1'y_2'}$	1 pF
y_1'' to y_2''	$C_{y_1''y_2''}$	1 pF
y_1' to y_1''	$C_{y_1'y_1''}$	0,005 pF
y_2' to y_2''	$C_{y_2'y_2''}$	0,005 pF
y_1' to y_2''	$C_{y_1'y_2''}$	0,001 pF
y_2' to y_1''	$C_{y_2'y_1''}$	0,015 pF
Control grid to all other elements	C_{g_1}	6 pF
Cathode and heater to all other elements	$C_{kf/R}$	3 pF

NOTES

1) This tube is designed for optimum performance when operating at a ratio $V_{g7(\ell)}/V_{g2,g4} = 6,7$.
The geometry control voltage V_{g6} should be adjusted within the indicated range (values with respect to the mean x-plate potential).

2) A negative control voltage on g_5 (with respect to the mean x-plate potential) will cause some pincushion distortion and less background light. By varying the two voltages V_{g5} and V_{g6} it is possible to find the best compromise between background light and raster distortion.

3) The astigmatism control electrode voltage should be adjusted for optimum spot shape. For any necessary adjustment its potential will be within the stated range.

4) The sensitivity at a deflection less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.

5) A graticule, consisting of concentric rectangles of 100 mm x 80 mm and 96 mm x 77 mm is aligned with the electrical x-axis of the tube. With optimum correction potentials applied a raster of each system will fall between these rectangles.

TYPICAL OPERATING CONDITIONS

Final accelerator voltage	$V_{g7}(\ell)$	10	kV	
Geometry control electrode voltage	V_{g6}	1500 ± 100	V	1)
Interplate shield voltage	V_{g5}	1500	V	
Background illumination control voltage	ΔV_{g5}	0 to −15	V	2)
Focusing electrode voltage	V_{g3}	350 to 650	V	
First accelerator voltage	$V_{g2}, g4$	1500	V	
Astigmatism control voltage	$\Delta V_{g2}, g4$	±75	V	3)
Control grid voltage for extinction of focused spot	V_{g1}	−20 to −70	V	
Deflection coefficient, horizontal	M_x	12,5	V/cm	
		< 14	V/cm	
vertical	M_y'	9	V/cm	
		< 10	V/cm	
	M_y''	9	V/cm	
		< 10	V/cm	
Deviation of deflection linearity		< 2	%	4)
Geometry distortion		see note 5)		
Useful scan, horizontal		> 100	mm	
vertical		> 80	mm	
Overlap of the two systems, horizontal		100	%	
vertical		100	%	

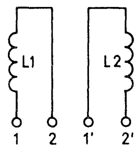
LIMITING VALUES (Absolute max. rating system)

Final accelerator voltage	$V_{g7}(\ell)$	max.	12	kV
		min.	9	kV
Geometry control electrode voltage	V_{g6}	max.	2200	V
Interplate shield voltage	V_{g5}	max.	2200	V
Focusing electrode voltage	V_{g3}	max.	2200	V
First accelerator and astigmatism control electrode voltage	$V_{g2}, g4$	max.	2200	V
		min.	1350	V
Control grid voltage	$-V_{g1}$	max.	200	V
		min.	0	V
Voltage between astigmatism control electrode and any deflection plate	V_{g4}/x	max.	500	V
	V_{g4}/y	max.	500	V
Grid drive average		max.	30	V
Screen dissipation	W_ℓ	max.	8	mW/cm^2
Ratio $V_{g7(\ell)}/V_{g2}, g4$	$V_{g7(\ell)}/V_{g2}, g4$	max.	6,7	
Control grid circuit resistance	R_{g1}	max.	1	MΩ

CORRECTION COILS

General

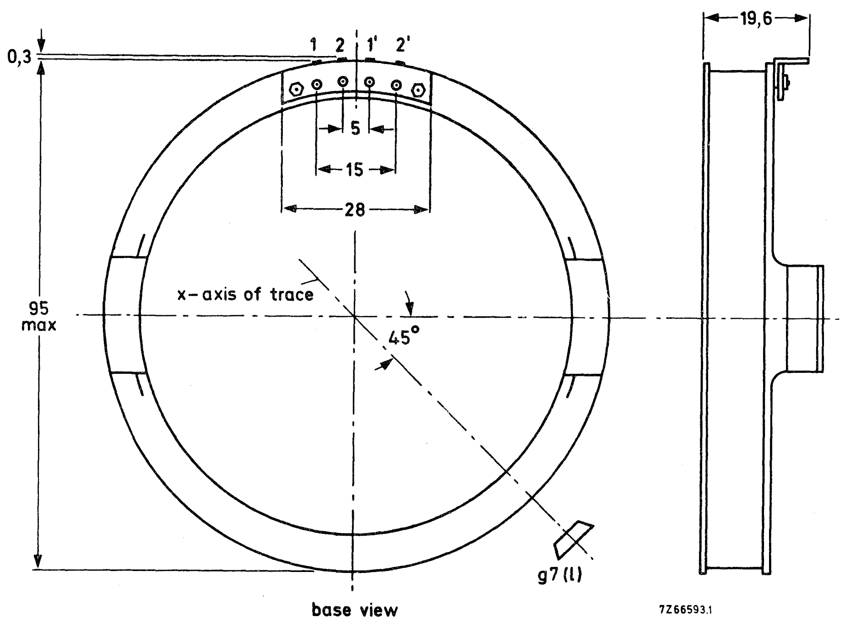
The E14-100GH is provided with a pair of coils L1 and L2 for image rotation which enable the alignment of the x-trace with the x-lines of the graticule.



The image rotating coils are wound concentrically around the tube neck. Under typical operating conditions 50A turns are required for the maximum rotation of 5°. Both coils have 850 turns. This means that a current of max. 30 mA per coil is required which can be obtained by using a 24 V supply when the coils are connected in series, or a 12 V supply when they are in parallel.

Connecting the coils

The coils have been connected to the 4 solderingtags as follows:



BEAM CENTRING MAGNET

Inherent to the split-beam system a slight difference between the two beam currents can occur after splitting, resulting in different intensities of the two traces. In order to equalize the beam currents, a beam centring magnet should be mounted near the base of the gun and adjusted for the required field direction and field strength.

INSTRUMENT CATHODE-RAY TUBE

The E14-101GH is equivalent to the E14-100GH but has no rotating coil.

INSTRUMENT CATHODE-RAY TUBE

14 cm diagonal, rectangular flat-faced direct-view storage tube with variable persistence and internal graticule, intended for oscilloscope applications.

QUICK REFERENCE DATA

Final accelerator voltage	$V_{g10(\ell)}$	8,5	kV
Display area (10 x 8 divisions of 9 mm)		90 x 72	mm^2
Deflection coefficient			
horizontal	M_x	9,5	V/div
vertical	M_y	4,1	V/div
Writing speed		2,5	div/μs

OPTICAL DATA

Screen	metal backed phosphor		
type	GH, colour green		
persistence, non-store mode	medium-short		
persistence, store mode	variable		
Useful screen dimensions	min.	90 x 72	mm
Useful scan			
horizontal	min.	90	mm
vertical	min.	72	mm
Spot eccentricity in horizontal and vertical directions	max.	6	mm

The scanned raster can be shifted and aligned with the internal graticule by means of correction coils fitted around the tube by the manufacturer.

HEATING

Writing section

Indirect by a.c. or d.c.; parallel supply

Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

Viewing section

Indirect by d.c.; parallel supply

Heater voltage	$V_{f'}$	6,3	V
Heater current	$I_{f'}$	300	mA
Heater voltage	$V_{f''}$	6,3	V
Heater current	$I_{f''}$	300	mA

MECHANICAL DATA

Mounting position any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube. The tags near the screen should not be subjected to mechanical stress.

Net mass	approx.	1,1	kg
Base	14 pin, all glass		
Dimensions and connections			
See also outline drawing, pages 4 and 5			
Overall length (socket included)	max.	445	mm
Face dimensions	max.	100 x 120	mm
Accessories			
Socket (supplied with tube)	type	55566	
Side contact connector (14 required)	type	55561	
Small ball contact connector (3 required)	type	4022 102 21590	

FOCUSING	electrostatic	
DEFLECTION	double electrostatic	
x-plates	symmetrical	
y-plates	symmetrical	
Angle between x and y-traces		90°
Angle between x-trace and x-axis of the internal graticule		0°

See also Correction coils

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	6,5	pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	6,5	pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	3	pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	3	pF
x_1 to x_2	C_{x1x2}	2,5	pF
y_1 to y_2	C_{y1y2}	2	pF
g_1 to all other elements	C_{g1}	5,5	pF
g_1' to all other elements	$C_{g1'}$	5,5	pF
g_1'' to all other elements	$C_{g1''}$	5,5	pF
k to all other elements	C_k	4,5	pF
k′ to all other elements	$C_{k'}$	5	pF
k″ to all other elements	$C_{k''}$	5	pF
g_7 to all other elements	C_{g7}	40	pF
g_9 to all other elements	C_{g9}	75	pF

DIMENSIONS AND CONNECTIONS

Dimensions in mm

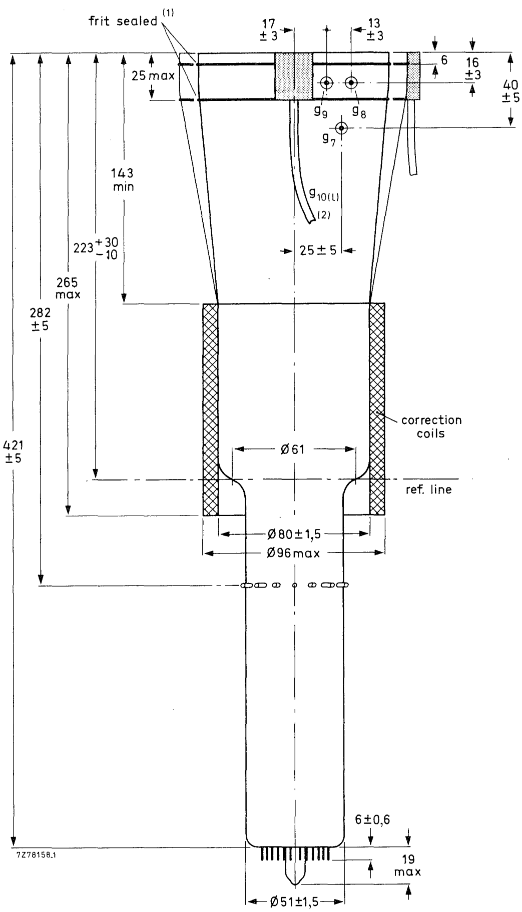


Fig. 1 Outlines.

(1) The bulge at the frit seal may increase the indicated maximum dimensions by not more than 3 mm.

(2) Minimum length of cable: 420 mm.

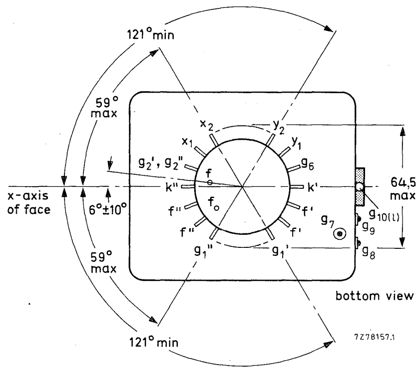


Fig. 2 Bottom view and side-contact arrangement.

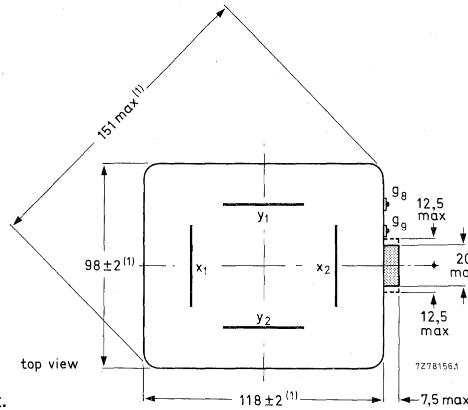


Fig. 3 Top view.

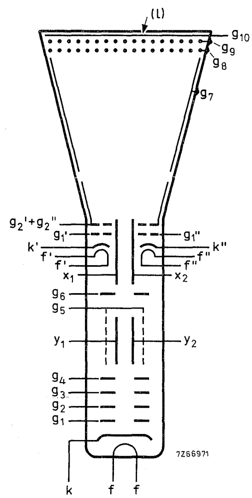


Fig. 4 Electrode configuration.

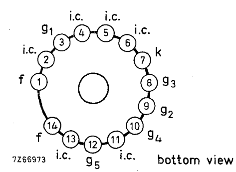


Fig. 5 Pin arrangement; bottom view.

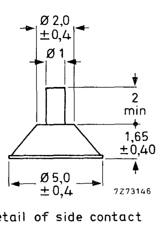


Fig. 6 Detail of side contact

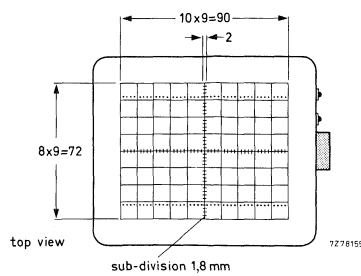


Fig. 7 Internal graticule
colour of graticule: brown-black;
line width : 0,15 mm;
dot diameter : 0,3 mm.

TYPICAL OPERATION (for notes see page 8)

Conditions

Writing section (voltages with respect to writing gun cathode k)

Final accelerator voltage	$V_{g10}(\ell)$	8500	V	note 1
Geometry control electrode voltage	V_{g6}	1500 ± 100	V	
Deflection plate shield voltage	V_{g5}	1500	V	note 2
Astigmatism control electrode voltage	V_{g4}	1500 ± 50	V	
Focusing electrode voltage	V_{g3}	400 to 600	V	
First accelerator voltage	V_{g2}	1500	V	
Control grid voltage for visual extinction of focused spot	V_{g1}	–40 to –80	V	

Viewing section (voltages with respect to viewing gun cathodes k' and k'')

Final accelerator voltage	$V_{g10}(\ell)$	7050	V	note 1
Backing electrode voltage,				
storage operation	V_{g9}	0 to 5	V	
non-storage operation	V_{g9}	–35	V	
Collector voltage	V_{g8}	150	V	
Collimator voltage	V_{g7}	30 to 120	V	note 3
First accelerator voltage	V_{g2}', V_{g2}''	50	V	note 4
Control grid voltage for cut-off	V_{g1}', V_{g1}''	–30 to –70	V	
Cathode current (each viewing gun)	I_k', I_k''	0,4	mA	

Performance

Useful scan				
horizontal		min. 90	mm	
vertical		min. 72	mm	
Deflection coefficient				
horizontal	M_x	9,5	V/div	
		max. 10,5	V/div	
vertical	M_y	4,1	V/div	
		max. 4,4	V/div	
Line width at the centre of the screen	l.w.	0,35	mm	note 5
Writing speed in store mode		greater than 250	div/ms	note 6
Storage time		greater than 1,5	min	note 7
Deviation of linearity of deflection		max. 2	%	note 8
Geometry distortion		see note 9		
Grid drive for 10 μA beam current		≈ 25	V	

LIMITING VALUES (Absolute maximum rating system)

Writing section (voltages with respect to writing gun cathode k)

Final accelerator voltage	$V_{g10(\ell)}$	max.	9500	V
		min.	7000	V
Geometry control electrode voltage	V_{g6}	max.	2100	V
Deflection plate shield voltage	V_{g5}	max.	2000	V
Astigmatism control electrode voltage	V_{g4}	max.	2100	V
		min.	1200	V
Focusing electrode voltage	V_{g3}	max.	1000	V
First accelerator voltage	V_{g2}	max.	2000	V
		min.	1250	V
Control grid voltage				
positive	V_{g1}	max.	0	V
negative	$-V_{g1}$	max.	200	V
Cathode to heater voltage				
positive	V_{kf}	max.	125	V
negative	$-V_{kf}$	max.	125	V
Voltage between astigmatism control electrode and any deflection plate	$V_{g4/x}$	max.	500	V
	$V_{g4/y}$	max.	500	V
Average grid drive		max.	30	V

Viewing section (voltages with respect to viewing gun cathodes k′ and k″ unless otherwise specified)

Final accelerator voltage	$V_{g10(\ell)}$	max.	8000	V
		min.	5500	V
Backing electrode voltage, storage operation	V_{g9}	max.	5	V
		min.	0	V
non-storage operation	$-V_{g9}$	max.	50	V
		min.	25	V
Collector voltage	V_{g8}	max.	180	V
		min.	120	V
Collimator voltage	V_{g7}	max.	200	V
		min.	0	V
First accelerator voltage	$V_{g2'}, V_{g2''}$	max.	60	V
		min.	40	V
Cathode to heater voltage				
positive	$V_{k'f'}, V_{k''f''}$	max.	125	V
negative	$-V_{k'f'}, -V_{k''f''}$	max.	125	V
Control grid voltage				
positive	$V_{g1'}, V_{g1''}$	max.	0	V
negative	$-V_{g1'}, -V_{g1''}$	max.	200	V

NOTES

1. These values are valid at cut-off of both flood guns and the writing gun. The H.T. unit must be capable of supplying 0,5 mA. To protect the tube against excessive surge current during erasure, an adequately dimensioned RC-network must be connected in series with the screen terminal lead (Fig. 8).

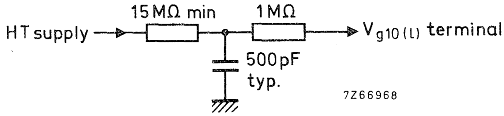


Fig. 8.

2. This voltage should be equal to the mean y-plate potential. The mean x and y-plate potentials should be equal for optimum spot quality.
3. The collimator electrode voltage should be adjusted for optimum uniformity of background illumination.
4. The voltage V_{g2}', V_{g2}'' should be equal to the mean x-plate potential.
5. Measured with the shrinking raster method in the centre of the screen under typical operating conditions, adjusted for optimum spot size at a beam current I_b = 10 μA (measured against x-plates).
6. The writing speed is defined as the maximum speed at which a written trace is just visible, starting from a background which is just black. The indicated value is guaranteed for the total graticule area, with the exception of maximum 5% in each corner. The writing speed can be increased to approx. 2,5 div/μs if some background is tolerated.
7. The storage time is defined as the time required for the brightness of the unwritten background to rise from just zero brightness (viewing-beam cut-off) to 10% of saturated brightness. At reduced intensity (by pulsing the flood beams) the storage time can be increased.
8. The sensitivity at a deflection less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.
9. A graticule, consisting of concentric rectangles of 88 mm x 70 mm and 86 mm x 68,5 mm is aligned with the electrical x-axis of the tube. With optimum corrections applied, a raster will fall between these rectangles.

CORRECTION COILS

General

The L14-111GH/55 is provided with a coil unit (see Fig. 9) consisting of:

– a pair of coils L3 and L4 which enable the angle between the x and y-traces at the centre of the screen to the made exactly 90° (orthogonality correction);

– a pair of coils L1 and L2 for image rotation which enable the alignment of the x-trace with the x-lines of the graticule.

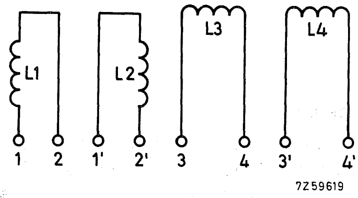


Fig. 9 Diagram of coil unit.

Orthogonality (coils L3 and L4)

The current required under typical operating conditions without a mu-metal shield being used is max. 20 mA for complete correction of orthogonality. It will be 30% to 50% lower with shield, depending on the shield diameter. The resistance of the coil is approx. 225 Ω.

Image rotation (coils L1 and L2)

The image rotation coils are wound concentrically around the tube neck. Under typical operating conditions 22 ampere-turns are required for maximum rotation of 5^{o}. Both coils have 850 turns. This means that a current of max. 12,5 mA per coil is required which can be obtained by using a 12 V supply when the coils are connected in series or a 6 V supply when they are in parallel.

Connecting the coils

The coils have been connected to 8 solder tags according to Fig. 10.

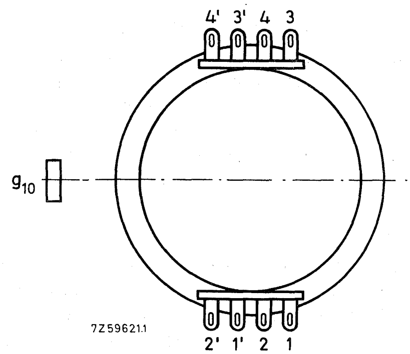


Fig. 10 Bottom view.

With L3 and L4 connected in series according to Fig. 11 a current in the direction indicated will produce a clockwise rotation of the vertical trace and an anti-clockwise rotation of the horizontal trace.

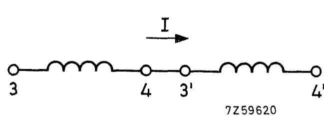


Fig. 11.

OPERATING NOTES

Modes of operation

Store mode

a. Dynamic erasure (variable persistence)

Dynamic erasure can be achieved by applying erasing pulses of positive polarity to the backing electrode. The pulse amplitude required is approximately 9V ($<$ 15 V) and the persistence of a stored display can be controlled by varying the duty factor of these pulses.

b. Static erasure.

If no dynamic erasing pulses are applied, the storage time is limited by the potential shift of the storage layer due to landing of positive ions. In order to erase a stored display, the backing electrode should first be connected to the collector electrode voltage and then returned to its original potential for about 100 ms; after that, an erasing pulse of positive polarity and a duration of not less than 300 ms should be applied. For the adjustment of the amplitude of this pulse see Procedure of adjustment.

Non-store mode

For non-store operation, it is sufficient to make the backing electrode about 35 V negative with respect to the viewing gun cathodes. The viewing guns should not be switched off in this mode of operation since slight variations in raster geometry and deflection sensitivity might otherwise be caused. Care should be taken, especially when switching from store mode to non-store mode, that excessive writing beam current is avoided, as otherwise the storage layer may be damaged.

Procedure of adjustment

a. Adjust the cathode current of each viewing gun to 0,4 mA by means of its control grid voltage.

b. Adjustment of the erasing pulse amplitude (static erasure)

The pulse amplitude should be just sufficient to suppress any background illumination at the centre of the display area (this adjustment should be done under low ambient light conditions). Data on storage time and maximum writing speed are based on erasure to "just black". A larger pulse amplitude (erasure to "blacker than black") yields a longer storage time at the expense of maximum writing speed. On the other hand, writing speed can be increased if some background illumination is tolerated. To erase to "just black" the amplitude of this pulse is approximately 9 V.

c. Adjustment of the collimator voltage

With dynamic erasing pulses applied and a persistence control setting that yields a convenient background illumination intensity, the collimator voltage is adjusted for optimum background uniformity. This voltage will be approximately 80 V with respect to the viewing gun cathode potential. If this voltage is too high or too low, there is a decrease of intensity at the four corners or at the centres of the vertical edges of the display area respectively. For a good erasure of the display, the collimator voltage should be as low as possible.

INSTRUMENT CATHODE-RAY TUBE

14 cm-diagonal rectangular flat-faced direct-view storage tube with split-beam writing gun, variable persistence and internal graticule, intended for oscilloscope applications.

QUICK REFERENCE DATA

Final accelerator voltage	V_{g10} (ℓ)	8,5	kV
Useful scan (10 x 8 divisions of 9 mm)		90 x 72	mm
Deflection coefficient			
horizontal	M_x	9,5	V/div
vertical, system 1	M_y'	8,5	V/div
vertical, system 2	M_y''	8,5	V/div
Overlap of the systems		100	%
Writing speed		1,25	div/μs

OPTICAL DATA

Screen	metal-backed phosphor		
type	GH, colour green		
persistence, non-store mode	medium short		
persistence, store mode	variable		
Useful screen dimensions	min.	90 x 72	mm
Useful scan			
horizontal	min.	90	mm
vertical (each system)	min.	72	mm
overlap		100	%
Spot eccentricity			
in horizontal direction	max.	6	mm
in vertical direction	max.	9	mm

The scanned raster can be aligned with the internal graticule by means of correction coils fitted around the tube by the manufacturer.

HEATING

Writing section

Indirect by a.c. or d.c.; parallel supply

Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

Viewing section

Indirect by d.c.; parallel supply

Heater voltage	V_f'	6,3	V
Heater current	I_f'	300	mA
Heater voltage	V_f''	6,3	V
Heater current	I_f''	300	mA

MECHANICAL DATA

Mounting position any

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube. The tags near the screen should not be subjected to mechanical stress.

Net mass	approx.	1,1 kg
Base	14 pin, all glass	
Dimensions and connections		
See also outline drawing, pages 4 and 5		
Overall length (socket included)	max.	445 mm
Face dimensions	max.	100 x 120 mm

Accessories

Socket (supplied with tube)	type	55566
Side contact connector (16 required)	type	55561
Small ball contact connector (3 required)	type	4022 102 21590

FOCUSING electrostatic

DEFLECTION double electrostatic

x-plates	symmetrical
y-plates	symmetrical

If use is made of the full deflection capabilities of the tube, the deflection plates will block part of the electron beams, hence a low impedance deflection plate drive is desirable.

Angle between x and y traces, each beam		90°
Angle between x-trace and x-axis of the internal graticule		0°
Angle between corresponding y-traces at the centre of the screen	max.	45′

CAPACITANCES

Writing section

x_1 to all other elements except x_2	$C_{x1(x2)}$	6,5 pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	6,5 pF
y_1' to all other elements except y_2'	$C_{y1'(y2')}$	5 pF
y_2' to all other elements except y_1''	$C_{y2'(y1')}$	6 pF
y_1'' to all other elements except y_2''	$C_{y1''(y2'')}$	6 pF
y_2'' to all other elements except y_1''	$C_{y2''(y1'')}$	5 pF
x_1 to x_2	$C_{x1\,x2}$	2,5 pF
y_1' to y_2'	$C_{y1'y2'}$	0,6 pF
y_1'' to y_2''	$C_{y1''y2''}$	0,6 pF
y_1' to y_1''	$C_{y1'y1''}$	4 fF
y_2' to y_2''	$C_{y2'y2''}$	5 fF
y_1' to y_2''	$C_{y1'y2''}$	0,3 fF
y_2' to y_1''	$C_{y2'y1''}$	8 fF
g_1 to all other elements	C_{g1}	5,5 pF
k to all other elements	C_k	4,5 pF

Viewing section

g_1' to all other elements	$C_{g1'}$	5,5 pF
g_1'' to all other elements	$C_{g1''}$	5,5 pF
k' to all other elements	$C_{k'}$	5 pF
k'' to all other elements	$C_{k''}$	5 pF
g_7 to all other elements	C_{g7}	45 pF
g_9 to all other elements	C_{g9}	75 pF

1 fF = 1 femto farad = 10^{-15} farad.

DIMENSIONS AND CONNECTIONS

Dimensions in mm

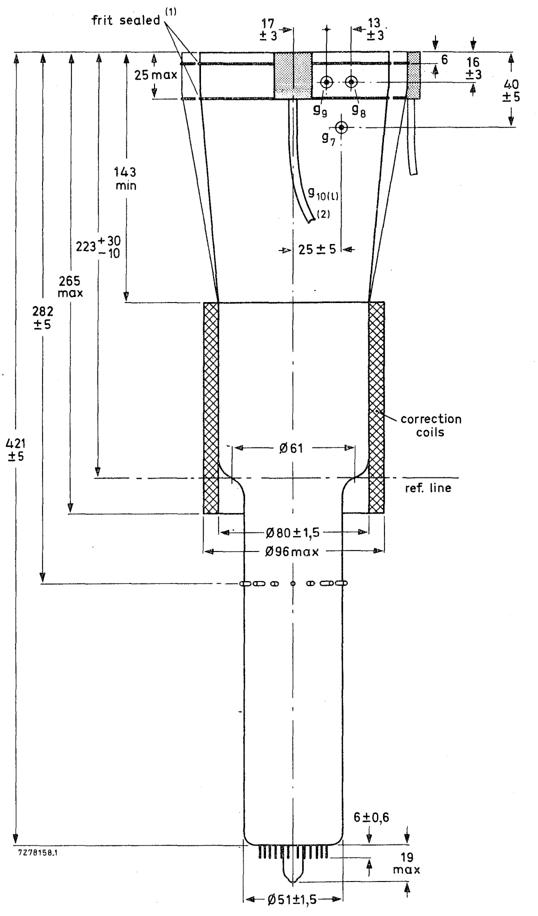


Fig. 1 Outlines.

(1) The bulge at the frit seal may increase the indicated maximum dimensions (Fig. 3) by not more than 3 mm.

(2) Minimum length of cable: 420 mm.

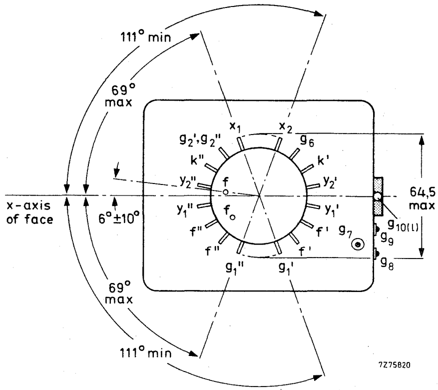


Fig. 2 Bottom view and side-contact arrangement.

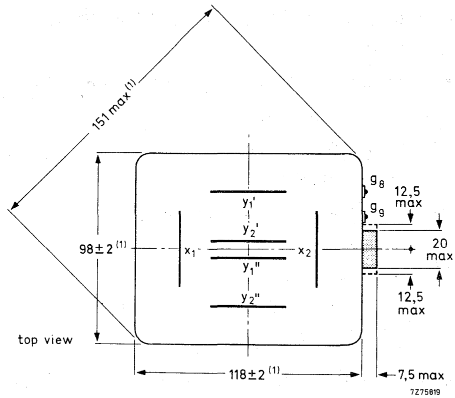


Fig. 3 Top view.

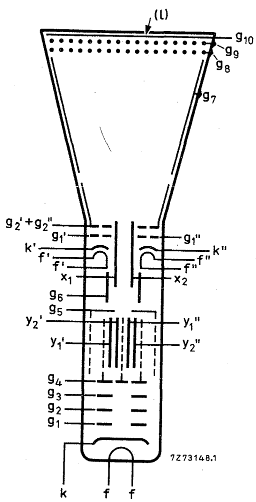


Fig. 4 Electrode configuration.

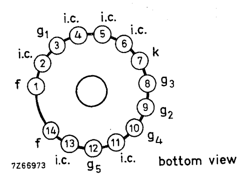


Fig. 5 Pin arrangement; bottom view.

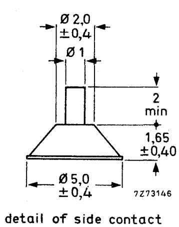


Fig. 6 Detail of side contact.

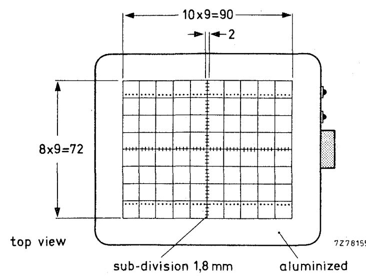


Fig. 7 Internal graticule.
Colour: brown-black;
line width: 0,15 mm;
dot diameter: 0,3 mm.

TYPICAL OPERATION (for notes see page 8)

Conditions

Writing section (voltages with respect to writing gun cathode k)

Final accelerator voltage	$V_{g10}(\ell)$	8500 V	note 1
Geometry control electrode voltage	V_{g6}	1500 ± 100 V	
Deflection plate shield voltage	V_{g5}	1500 V	note 2
Astignatism control electrode voltage	V_{g4}	1500 ± 75 V	
Focusing electrode voltage	V_{g3}	400 to 650 V	
First accelerator voltage	V_{g2}	1500 V	
Control grid voltage for visual extinction of focused spot	V_{g1}	−40 to −80 V	

Viewing section (voltages with respect to viewing gun cathode k′ and k″)

Final accelerator voltage	$V_{g10}(\ell)$	7050 V	note 1
Backing electrode voltage, storage operation	V_{g9}	1 V	
non-storage operation	V_{g9}	−35 V	
Collector voltage	V_{g8}	150 V	
Collimator voltage	V_{g7}	30 to 120 V	note 3
First accelerator voltage	$V_{g2'}, V_{g2''}$	50 V	note 4
Control grid voltage for cut-off	$V_{g1'}, V_{g1''}$	−30 to −70 V	
Cathode current (each viewing gun)	$I_{k'}, I_{k''}$	0,4 mA	

Performance

Useful scan, horizontal		min.	90 mm	
vertical		min.	72 mm	
Deflection coefficient, horizontal	M_x		9,5 V/div	
		max.	10,5 V/div	
vertical, system 1	$M_{y'}$		8,5 V/div	
		max.	9,5 V/div	
vertical, system 2	$M_{y''}$		8,5 V/div	
		max.	9,5 V/div	
Line width at the centre of the screen	l.w.		0,40 mm	note 5
Writing speed in store mode		greater than	125 div/ms	note 6
Storage time		greater than	1,5 min	note 7
Deviation of linearity of deflection		max.	2 %	note 8
Geometry distortion		see note 9		
Grid drive for 5 μA beam current, per system		approx.	30 V	

LIMITING VALUES (Absolute maximum rating system)

Writing section (voltages with respect to writing gun cathode k)

Final accelerator voltage	$V_{g10(\ell)}$	max. min.	9500 V 7000 V
Geometry control electrode voltage	V_{g6}	max.	2100 V
Deflection plate shield voltage	V_{g5}	max.	2000 V
Astigmatism control electrode voltage	V_{g4}	max. min.	2100 V 1200 V
Focusing electrode voltage	V_{g3}	max.	1000 V
First accelerator voltage	V_{g2}	max. min.	2000 V 1250 V
Control grid voltage			
positive	V_{g1}	max.	0 V
negative	$-V_{g1}$	max.	200 V
Cathode to heater voltage			
positive	V_{kf}	max.	125 V
negative	$-V_{kf}$	max.	125 V
Voltage between astigmatism control electrode and any deflection plate	$V_{g4/x}$ $V_{g4/y}$	max. max.	500 V 500 V
Average grid drive		max.	30 V

Viewing section (voltages with respect to viewing gun cathodes k′ and k″ unless otherwise specified)

Final accelerator voltage	$V_{g10(\ell)}$	max. min.	8000 V 5500 V
Backing electrode voltage, storage operation	V_{g9}	max. min.	5 V 0 V
non-storage operation	$-V_{g9}$	max. min.	50 V 25 V
Collector voltage	V_{g8}	max. min.	180 V 120 V
Collimator voltage	V_{g7}	max. min.	200 V 0 V
First accelerator voltage	$V_{g2'}, V_{g2''}$	max. min.	60 V 40 V
Cathode to heater voltage			
positive	$V_{k'f'}, V_{k''f''}$	max.	125 V
negative	$-V_{k'f'}, -V_{k''f''}$	max.	125 V
Control grid voltage			
positive	$V_{g1'}, V_{g1''}$	max.	0 V
negative	$-V_{g1'}, -V_{g1''}$	max.	200 V

NOTES

1. These values are valid at cut-off of both viewing (flood) guns and the writing gun. The H.T. unit must be capable of supplying 0,5 mA. To protect the tube against excessive surge current during erasure, an adequately dimensioned RC-network must be connected in series with the screen terminal lead (Fig. 8).

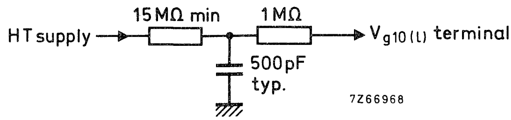


Fig. 8.

2. This voltage should be equal to the mean y-plate potential. The mean x and y-plate potentials should be equal for optimum spot quality.
3. The collimator electrode voltage should be adjusted for optimum uniformity of background illumination.
4. The voltage $V_{g2'}$, $V_{g2''}$ should be equal to the mean x-plate potential.
5. Measured with the shrinking raster method in the centre of the screen under typical operating conditions, adjusted for optimum spot size at a beam current I_b = 5 μA per system (measured against x-plates).
6. The writing speed is defined as the maximum speed at which a written trace is just visible, starting from a background which is just black. The indicated value is guaranteed for the total graticule area, with the exception of maximum 5% in each corner. The writing speed can be increased to approx. 1,25 div/μs if some background is tolerated.
7. The storage time is defined as the time required for the brightness of the unwritten background to rise from just zero brightness (viewing-beam cut-off) to 10% of saturated brightness. At reduced intensity (by pulsing the flood beams) the storage time can be increased.
8. The sensitivity at a deflection less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.
9. A graticule, consisting of concentric rectangles of 88 mm x 70 mm and 84,8 mm x 67,6 mm is aligned with the electrical x-axis of the tube. With optimum corrections applied, a raster will fall between these rectangles.

CORRECTION COILS

General

The L14-131GH/55 is provided with a coil unit (see Fig. 9) consisting of:

1. A pair of coils L3 and L4 which enable the angle between the x and y-traces at the centre of the screen to be made exactly 90° (orthogonality correction).
2. A pair of coils L1 and L2 for image rotation which enable the alignment of the x-trace with the x-lines of the graticule.

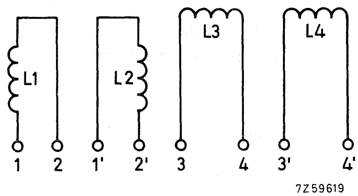


Fig. 9 Diagram of coil unit.

Orthogonality (coils L3 and L4)

The current required under typical operating conditions without a mu-metal shield being used is max. 20 mA for complete correction of orthogonality. It will be 30% to 50% lower with shield, depending on the shield diameter. The resistance of the coil is approx. 225 Ω.

Image rotation (coils L1 and L2)

The image rotation coils are wound concentrically around to the tube neck. Under typical operating conditions 22 ampere-turns are required for maximum rotation of 5^{o}. Both coils have 850 turns. This means that a current of max. 12,5 mA per coil is required which can be obtained by using a 12 V supply when the coils are connected in series or a 6 V supply when they are in parallel.

Connecting the coils

The coils have been connected to 8 solder tags according to Fig. 10.

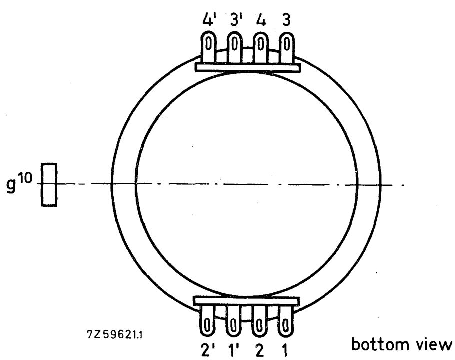


Fig. 10 Bottom view.

With L3 and L4 connected in series according to Fig. 11 a current in the direction indicated will produce a clockwise rotation of the vertical trace and an anti-clockwise rotation of the horizontal trace.

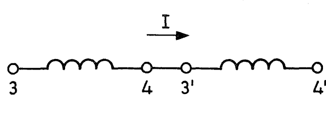


Fig. 11.

BEAM CENTRING MAGNET

Inherent to the split-beam system a slight difference between the two beam currents can occur after splitting, resulting in different intensities of the two traces. In order to equalize the beam currents, a beam centring magnet should be mounted near the base of the gun and adjusted for the required field direction and field strength.

OPERATING NOTES

Modes of operation

Store mode

a. Dynamic erasure (variable persistence).

Dynamic erasure can be achieved by applying erasing pulses of positive polarity to the backing electrode. The pulse amplitude required is approximately 9 V (< 15 V) and the persistence of a stored display can be controlled by varying the duty factor of these pulses.

b. Static erasure.

If no dynamic erasing pulses are applied, the storage time is limited by the potential shift of the storage layer due to landing of positive ions. In order to erase a stored display, the backing electrode should first be connected to the collector electrode voltage and then returned to its original potential for about 100 ms; after that, an erasing pulse of positive polarity and a duration of not less than 300 ms should be applied. For the adjustment of the amplitude of this pulse see Procedure of adjustment.

Non-store mode

For non-store operation, it is sufficient to make the backing electrode about 35 V negative with respect to the viewing gun cathodes. The viewing guns should not be switched off in this mode of operation since slight variations in raster geometry and deflection sensitivity might otherwise be caused. Care should be taken, especially when switching from store mode to non-store mode, that excessive writing beam current is avoided, as otherwise the storage layer may be damaged.

Procedure of adjustment

a. Adjust the cathode current of each viewing gun to 0,4 mA by means of its control grid voltage.

b. Adjustment of the erasing pulse amplitude (static erasure)

The pulse amplitude should be just sufficient to suppress any background illumination at the centre of the display area (this adjustment should be done under low ambient light conditions). Data on storage time and maximum writing speed are based on erasure to "just black". A larger pulse amplitude (erasure to "blacker than black") yields a longer storage time at the expense of maximum writing speed. On the other hand, writing speed can be increased if some background illumination is tolerated. To erase to "just black" the amplitude of this pulse is approximately 9 V.

c. Adjustment of the collimator voltage.

With dynamic erasing pulses applied and a persistence control setting that yields a convenient background illumination intensity, the collimator voltage is adjusted for optimum background uniformity. This voltage will be approximately 80 V with respect to the viewing gun cathode potential. If this voltage will be approximately 80 V with respect to the viewing gun cathode potential. If this voltage is too high or too low, there is a decrease of intensity at the four corners or at the centres of the vertical edges of the display area respectively.

INSTRUMENT CATHODE-RAY TUBE

14 cm diagonal, rectangular flat-faced direct-view charge transfer storage tube with internal graticule. The tube has vertical scan-magnification with 3 quadrupole lenses and is for wide-band (100 MHz) oscilloscopy with fast store mode and variable persistence.

QUICK REFERENCE DATA

Final accelerator voltage	$V_{g13(\ell)}$	10 kV
Minimum useful scan area		90 mm x 72 mm
Deflection coefficient		
horizontal	M_x	18,5 V/div
vertical	M_y	4,8 V/div
Writing speed		1 div/ns

OPTICAL DATA

Screen	metal backed phosphor	
type	GH, colour green	
persistence, non-store mode	medium-short	
persistence, store mode	variable	
Useful screen area		min. 90 mm x 72 mm
Useful scan area		min. 90 mm x 72 mm
Spot eccentricity		
in horizontal direction		max. 6 mm
in vertical direction		max. 8 mm
Internal graticule	type 95; see Fig. 6	

HEATING

Writing section

Indirect by a.c. or d.c.*

Heater voltage	V_f	6,3 V
Heater current	I_f	240 mA
Heating time to attain 10% of the cathode current at equilibrium conditions		approx. 5 s

Viewing section

Indirect by d.c.*

Heater voltage	V_{FGf}	12,6 V
Heater current	I_{FGf}	240 mA
Heating time to attain 10% of the cathode current at equilibrium conditions		approx. 5 s

* Not to be connected in series with other tubes.

MECHANICAL DATA

Mounting position

The tube can be mounted in any position. It should not be supported by the base alone or near the base region, and under no circumstances should the socket be allowed to support the tube. The tags near the screen should not be subjected to mechanical stress. Avoid any force on the side contacts.

Net mass	approx.	1,3	kg
Base	14 pin, all glass		
Dimensions and connections (see also outline drawing)			
Overall length (socket included)	max.	454	mm
Faceplate dimensions	118 ± 0,5 mm x 98 ± 0,5		mm
Accessories			
Socket (supplied with tube)	type	55572	
Side contact connector (8 required)	type	55561	
Small ball contact connected (6 required)	type	4022 102 21590	
FOCUSING	electrostatic		note 1
DEFLECTION	double electrostatic		
x-plates	symmetrical		
y-plates	symmetrical		
Angle between x and y-traces		$90 \pm 1^{\circ}$	
Angle between y-trace and y-axis of the internal graticule		$\leqslant 5^{\circ}$	note 2

NOTES

1. Because of the use of a quadrupole lens for the magnification of the vertical deflection, two more quadrupole lenses are used for focusing. Therefore, controls for two voltages have to be provided.
2. The tube has a rotation coil, concentrically wound around the tube neck, to allow alignment of the y-trace with the mechanical y-axis of the screen. The coil has 2000 turns and a maximum resistance of 650 Ω. Under typical operating conditions, a maximum of 30 ampere-turns is required for the maximum rotation of 5°. This means the required supply is 15 mA maximum at 12 V maximum.

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	5,5 pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	5,5 pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	2,7 pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	2,7 pF
x_1 to x_2	C_{x1x2}	3 pF
y_1 to y_2	C_{y1y2}	1,7 pF
g_1 to all other elements	C_{g1}	7 pF
k to all other elements	C_k	5 pF
g_{11} to all other elements	C_{g11}	80 pF
g_{12} to all other elements	C_{g12}	70 pF
g_{13} to all other elements	C_{g13}	85 pF
g_3 to all other elements	C_{g3}	17 pF
g_5 to all other elements	C_{g5}	17 pF
$g_{9\text{-}1}$ to all other elements	$C_{g9\text{-}1}$	30 pF
$g_{9\text{-}2}$ to all other elements	$C_{g9\text{-}2}$	70 pF
$g_{9\text{-}3}$ to all other elements	$C_{g9\text{-}3}$	60 pF
FGA to all other elements	C_{FGA}	20 pF
k′, k″ to all other elements	$C_{k', k''}$	12 pF

DIMENSIONS AND CONNECTIONS

Dimensions in mm

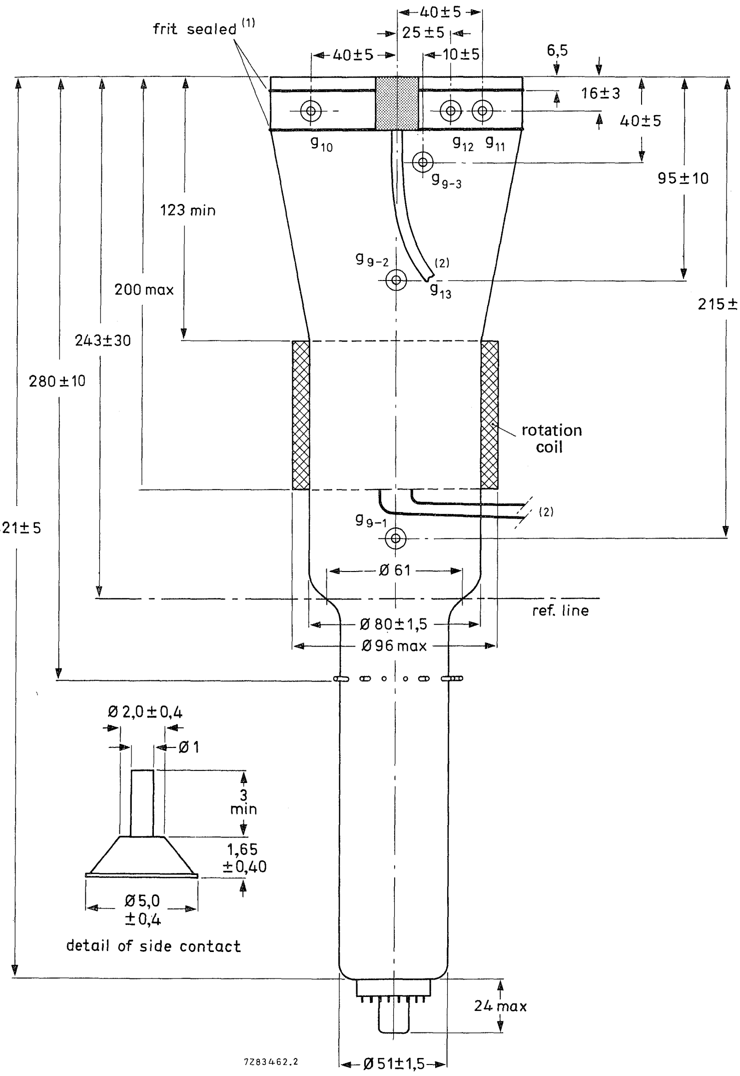


Fig. 1 Outlines

(1) Dimensions of faceplate only. The bulge at the frit seal may increase the indicated maximum dimensions by not more than 3 mm.
(2) Minimum length of cable: 350 mm.

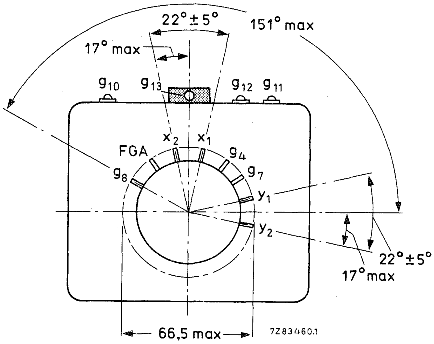


Fig. 2 Bottom view and side-contact arrangement.

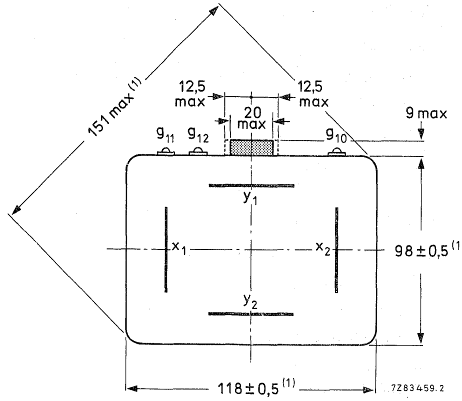


Fig. 3 Top view. For note (1) see opposite page.

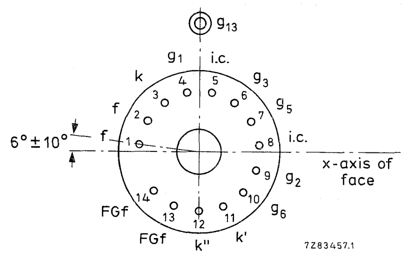


Fig. 5 Pin arrangement; bottom view.

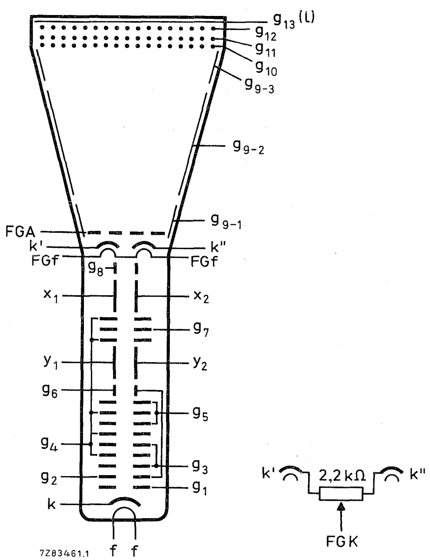


Fig. 4 Electrode configuration.

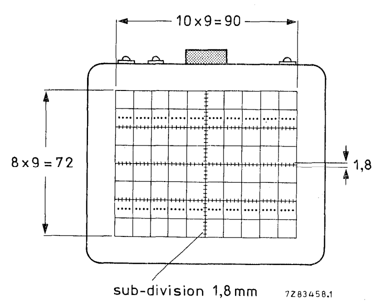


Fig. 6 Internal graticule
colour of graticule: brown-black;
line width : 0,2 mm;
dot diameter : 0,4 mm.

TYPICAL OPERATION (for notes see pages 7 and 8)

Conditions

Writing section (voltages with respect to writing gun cathode k, unless otherwise stated for optimum scan magnification ≈ 1,8).

Final accelerator voltage	$V_{g13(l)}$	10 000 V	note 1
Geometry control voltage	V_{g8}	3000 ± 100 V	
Scan magnifier electrode voltage (with respect to g_2)	V_{g7}	−600 V	
Horizontal alignment electrode voltage (with respect to g_2)	V_{g6}	± 100 V	note 2
Vertical focusing electrode voltage (with respect to g_2)	V_{g5}	−860 to −1100 V	
Correction electrode voltage (with respect to g_2)	V_{g4}	200 V	note 3
Horizontal focusing electrode voltage (with respect to g_2)	V_{g3}	−1300 to −1650 V	
First accelerator voltage	V_{g2}	3000 V	
Cut-off voltage for visual extinction of focused spot	$-V_{g1}$	75 to 130 V	

Viewing section (voltages with respect to viewing gun cathode FGK, Fig. 4)

		non-store mode	variable persistance mode	fast-store mode	
Final accelerator voltage (with respect to first accelerator FGA)	$V_{g13(l)}$	7000 V	7000 V	7000 V	note 1
Backing electrode voltages (d.c.)					
front mesh	V_{g12}	−50 V			note 4
fast mesh	V_{g11}	140 V	140 V	140 V	note 4
Collector mesh voltage (d.c.)	V_{g10}	130 V	130 V	130 V	note 4
Collimator voltage (d.c.)					
C3	$V_{g9\text{-}3}$	65 V	65 V	65 V	note 4
C2	$V_{g9\text{-}2}$	≈ 65 V	65 V	65 V	note 4
C1	$V_{g9\text{-}1}$	30 V	30 V	30 V	note 4
First accelerator voltage (d.c.)	V_{FGA}	20 V	20 V	20 V	note 4
Flood gun cathode voltage (d.c.)	V_{FGK}	0 V	0 V	0 V	note 4

The first accelerator voltage should be equal to the mean x-plate potential.

Performance

Useful scan area: min. 90 mm x 72 mm

Deflection coefficient horizontal	M_x	typ.	18,5	V/div
		max.	20,5	V/div
vertical	M_y	typ.	4,8	V/div
		max.	5,5	V/div

Deviation of deflection linearity		max.	2 %	note 5
Geometry distortion		see note 6		
Grid drive for 10 μA beam current	V_d	approx.	20 V	
Grid drive for specified writing speed	V_d	max.	80 V	
Line width at the centre of the screen	l.w.		0,4 mm	note 7

Writing speed (note 8)

Variable persistence mode
just black: ⩾ 250 div/ms
max. write: ⩾ 2,5 div/μs

Fast-store mode
max. write: ⩾ 1 div/ns

Storage view time (note 9)

Variable persistence mode
just black: ⩾ 60 s
max. write: ⩾ 15 s

Fast-store mode
max. write: ⩾ 15 s

NOTES

1. These values are valid at cut-off of both flood guns and the writing gun. The H.T. unit must be capable of supplying 0,5 mA. To protect the tube against excessive surge current during erasure, an RC-network as shown in Fig. 7 must be connected in series with the screen terminal lead; the resistance of 15 to 20 MΩ includes the internal resistance of the H.T. supply.

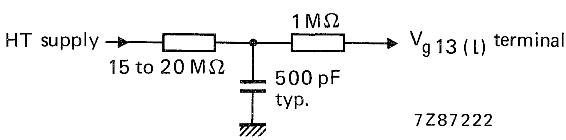


Fig. 7.

2. This voltage should be adjusted for equal brightness in the x-direction with respect to the electrical centre of the tube.
3. For minimum defocusing of vertical lines near the upper and lower edges of the scanned area this voltage should be the value indicated.
4. The indicated values concern the d.c. levels; during the erasing, preparing and transfering operation these electrodes are pulsed.
5. The sensitivity at a deflection less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.
6. A graticule, consisting of concentric rectangles of 90 mm x 72 mm and 87,8 mm x 70,5 mm is aligned with the electrical x-axis of the tube. With optimum corrections applied, a raster will fall between these rectangles.
7. Measured with the shrinking raster method in the centre of the screen under typical operating conditions, adjusted for optimum spot size at a beam current I_b = 10 μA (measured against x-plates).

NOTES (continued)

8. The writing speed is defined as the maximum speed at which a written trace is just visible starting from a background which is just black. The indicated value is guaranteed for the central 80% of the minimum screen area, except the outmost 3 mm of the screen. However, in any corner not more than 4 square divisions fall outside the guaranteed area. The writing speed can be increased, if some background is tolerated. Within the same area, a trace, written with the indicated value of max. write, remains just visible within the indicated storage time of max. write.

   The writing speed in max. write, with background, is defined as the maximum speed at which the written trace remains just visible within the indicated storage time.

9. The storage time in just black mode is defined as the time required for the brightness of the unwritten background to rise from zero brightness (viewing beam cut-off) to 10% of saturated brightness. At reduced intensity (by pulsing the flood beams) the storage time can be increased.

   The storage time in max. write and fast is related to the writing speed.

LIMITING VALUES (absolute maximum rating system)

Writing section (Voltages with respect to writing gun cathode k, unless otherwise stated)

Final accelerator voltage	$V_{g13(l)}$	max.	10500	V
		min.	8500	V
Geometry control voltage (with respect to g_2)	V_{g8}	max.	500	V
		min.	−500	V
Scan magnifier electrode voltage (with respect to g_2)	V_{g7}	max.	550	V
		min.	−700	V
Horizontal alignment electrode voltage (with respect to g_2)	V_{g6}	max.	500	V
		min.	−500	V
Vertical focusing electrode voltage (with respect to g_2)	V_{g5}	max.	−750	V
		min.	−1200	V
Correction electrode voltage (with respect to g_2)	V_{g4}	max.	500	V
		min.	0	V
Horizontal focusing electrode voltage (with respect to g_2)	V_{g3}	max.	−1200	V
		min.	−1800	V
First accelerator voltage	V_{g2}	max.	3500	V
		min.	2500	V
Control grid voltage				
positive	V_{g1}	max.	0	V
negative	$-V_{g1}$	max.	200	V
Cathode to heater voltage				
positive	V_{kf}	max.	125	V
negative	$-V_{kf}$	max.	125	V
Voltage between correction electrode and any deflection plate	$V_{g4/x}$	max.	500	V
	$V_{g4/y}$	max.	500	V
Grid drive, averaged over 1 ms	V_d	max.	30	V

Viewing section (voltages with respect to viewing gun cathode FGK)

Screen voltage	$V_{g13(l)}$	max.	7500	V
		min.	5500	V
Backing electrode voltage (d.c.)				
front mesh	V_{g12}	max.	600	V
		min.	−50	V
fast mesh	V_{g11}	max.	200	V
		min.	−50	V
Collector mesh voltage (d.c./a.c.)	V_{g10}	max.	200	V
		min.	100	V
Collimator voltages (d.c./a.c.)	$V_{g9\text{-}1;\,9\text{-}2;\,9\text{-}3}$	max.	150	V
		min.	0	V
First accelerator voltage	V_{FGA}	max.	100	V
		min.	0	V
Cathode to heater voltage	$V_{k'FGf}$, $V_{k''FGf}$	max.	125	V
	$-V_{k'FGf}$, $-V_{k''FGf}$	max.	125	V

OPERATING NOTES

Scan magnifier

A scan magnification $M_{sc} \approx 1{,}8$ is the best compromise between line width and sensitivity. This is obtained with $V_{g7} = -600$ V and $V_{g4} = 200$ V. Performance is tested and specified under this condition and no adjustment will be necessary for individual tubes.

Focusing is separate for horizontal and vertical directions with V_{g3} and V_{g5} respectively. Both focus settings may depend on beam current with different steepness. Although both electrodes are positive with respect to cathode, reverse current may result from secondary electrons leaving grid 3 (max. 5 μA) and grid 5 (max. 50 μA).

Normal current direction from beam interception is to be expected on the horizontal correction electrode g_6 (up to 500 μA) and, as usual, on g_2 and deflection plates.

Modes of operations

Non-store mode

For non-store operation the front mesh V_{g12} is set to −50 V with respect to FGK.

The viewing guns should not be switched off in this mode of operation since slight variations in raster geometry and deflection sensitivity might otherwise be caused. Care should be taken, especially when switching from store mode to non-store mode, that excessive writing beam current is avoided, as otherwise the storage layer may be damaged.

Variable persistence mode

The fast mesh is switched off for this operation and used as collector by setting $V_{g11} = 140$ V.

a. Static erasure

If no dynamic erasing pulses are applied the storage time is limited by the potential shift of the storage layer due to landing of positive ions.

In order to erase a stored display, V_{g12} is increased to 500 V for 100 ms and than returned to its original potential for about 500 ms; after that, an erasing pulse of positive polarity (max. 20 V) and a duration of 600 ms should be applied.

While the erasing pulse amplitude is to be adjusted with zero d.c. level for "just black", the background illumination can be changed — even with a stored signal — by varying the d.c. level for optimum contrast or maximum writing speed.

Background egality can be optimized by balancing the viewing gun cathodes by means of a potentiometer of 2,2 kΩ, proper collimator adjustment, and by increasing V_{FGA}. $V_{g9\text{-}1}$ and $V_{g9\text{-}3}$ in positive direction during erasure.

Before first installation, depending on transport conditions, demagnetization of the tube face region may be necessary.

b. Dynamic erasure

Dynamic erasure can be achieved by applying extra erasing pulses of positive polarity to the backing electrode of the front mesh (g_{12}). The amplitude of these extra pulses is equal to that of the original erasing pulse, the frequency is 120 Hz and the persistence of the display can be controlled by varying the duty factor.

Fast-store mode

For erasure in the fast mode the front mesh has to be erased first in the same way as in the variable persistence mode but separate adjustments should be foreseen.

The fast mesh is to be prepared by reducing V_{g11} from 140 V to the stabilizing level (0 to max. 20 V) during the erasing pulse on the front mesh.

After writing, at the end of the unblanking pulse, a transfer pulse (500 V, 100 ms) is to be applied on the front mesh.

During the transfer pulse, V_{g11} is further reduced about 1 V for enhanced transmission during transfer. This reduction has to be carefully adjusted for optimum contrast and writing speed.

During the whole cycle, FGA, V_g9-1 and V_g9-3 may be increased for more viewing gun current. Details on the adjustment procedure and the voltage range to be provided for can be made available.

INSTRUMENT CATHODE-RAY TUBE

- 14 cm diagonal rectangular flat face
- direct - view storage tube
- internal graticule
- for oscilloscope applications

QUICK REFERENCE DATA

Final accelerator voltage	$V_{g10(\ell)}$	8,5 kV
Minimum useful scan area		90 mm x 72 mm
Deflection coefficient		
horizontal	M_x	9,5 V/div
vertical	M_y	4,1 V/div
Writing speed		2,5 div/µs

OPTICAL DATA

Screen	metal-backed phosphor
type	GH, colour green
persistence, non-store mode	medium-short
persistence, store mode	variable
Useful screen area	min. 90 mm x 72 mm
Useful scan area	min. 90 mm x 72 mm
Spot eccentricity in horizontal and vertical directions	max. 6 mm
Internal graticule	typ. 95; see Fig. 6

HEATING

Writing section

Indirect by a.c. or d.c.*

Heater voltage	V_f	6,3 V
Heater current	I_f	240 mA
Heating time to attain 10% of the cathode current at equilibrium conditions		approx. 5 s

Viewing section

Indirect by d.c.*

Heater voltage	V_{FGf}	12,6 V
Heater current	I_{FGf}	240 mA
Heating time to attain 10% of the cathode current at equilibrium conditions		approx. 5 s

* Not to be connected in series with other tubes.

MECHANICAL DATA

Dimensions and connections (see also outline drawings)

Overall length (socket included)	⩽ 452 mm
Faceplate dimensions (final accelerator contact excluded)	118 ± 0,5 mm x 98 ± 0,5 mm
Net mass	approx. 1,3 kg
Mase	14 pin, all glass

Mounting position

The tube can be mounted in any position. It should not be supported by the base alone or near the base region, and under no circumstances should the socket be allowed to support the tube. The tags near the screen should not be subjected to mechanical stress. Avoid any force on the side contacts.

Accessories

Socket (supplied with tube)	type 55566
Side contact connector (7 required)	type 55561
Small ball contact connector (5 required)	type 4022 102 21590

FOCUSING	electrostatic
DEFLECTION	double electrostatic
x-plates	symmetrical
y-plates	symmetrical
Angle between x and y-traces	90 ± 1°
Angle between x-trace and x-axis of the internal graticule	⩽ 5°*

* The tube has a rotation coil, concentrically wound around the tube neck, to allow alignment of the x-trace with the mechanical x-axis of the screen. The coil has 2000 turns and a maximum resistance of 650 Ω. Under typical operating conditions, a maximum of 20 ampere-turns is required for the maximum rotation of 5°. This means the required supply is 10 mA maximum at 8 V maximum.

CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	5,5 pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	5,5 pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	3,5 pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	3,5 pF
x_1 to x_2	C_{x1x2}	2,5 pF
y_1 to y_2	C_{y1y2}	2 pF
g_1 to all other elements	C_{g1}	6 pF
k to all other elements	C_k	3,5 pF
g_3 to all other elements	C_{g3}	4,5 pF
$g_{7\text{-}1}$ to all other elements	$C_{g7\text{-}1}$	30 pF
$g_{7\text{-}2}$ to all other elements	$C_{g7\text{-}2}$	65 pF
$g_{7\text{-}3}$ to all other elements	$C_{g7\text{-}3}$	60 pF
g_9 to all other elements	C_{g9}	60 pF
g_{10} to all other elements	C_{g10}	80 pF
FGA to all other elements	C_{FGA}	15 pF
FGK′ to all other elements	$C_{FGK'}$	8 pF
FGK″ to all other elements	$C_{FGK''}$	8 pF

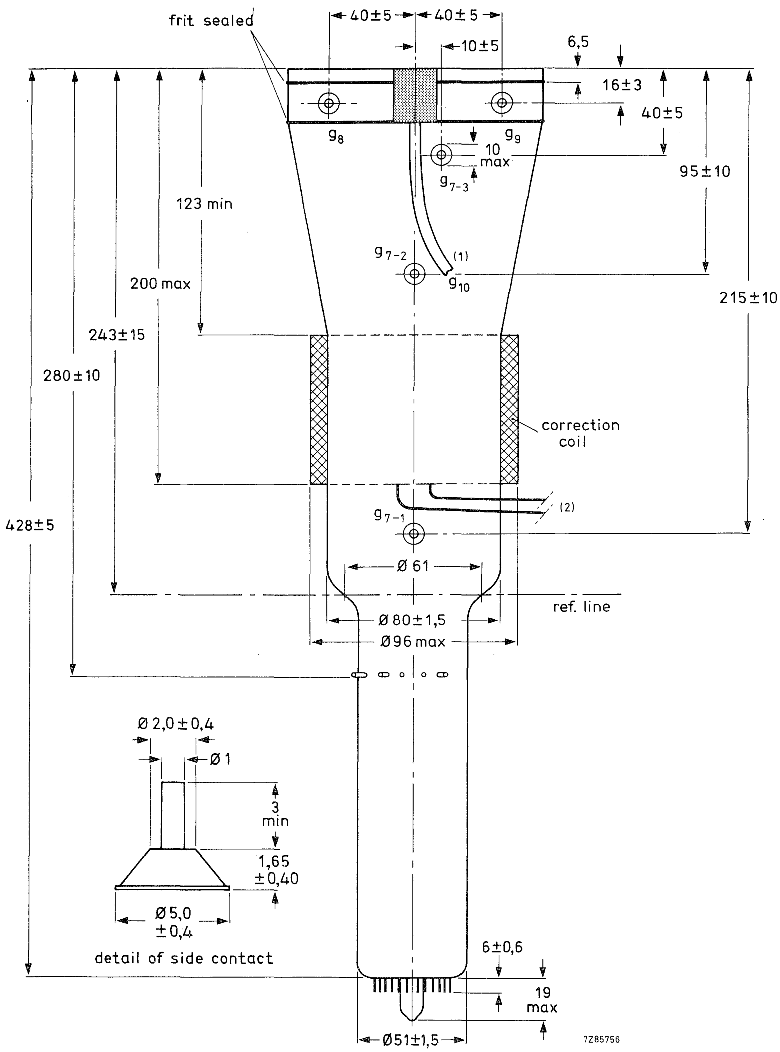


Fig. 1 Outlines.

(1) Minimum cable length is 420 mm.
(2) Minimum length of connecting leads is 350 mm.
(3) Dimensions of faceplate only. The bulge at the frit seal may increase the indicated maximum dimensions by not more than 3 mm.

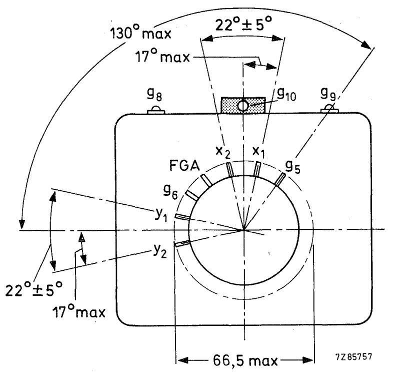


Fig. 2 Bottom view and side-contact arrangement.

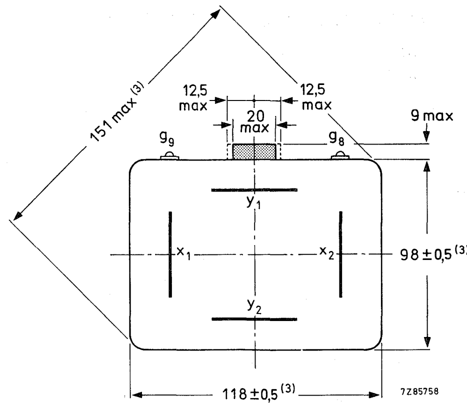


Fig. 3 Top view. For note (3) see opposite page.

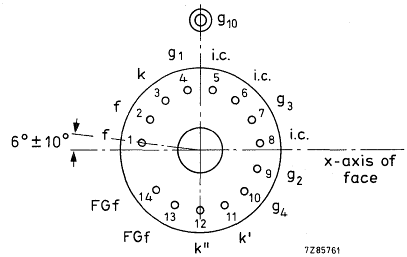


Fig. 5 Pin arrangement; bottom view.

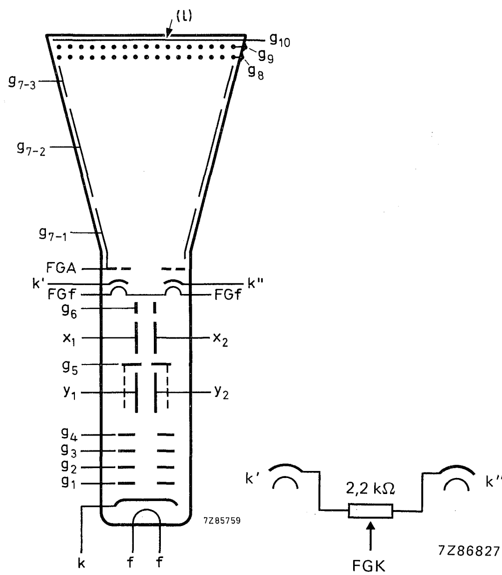


Fig. 4 Electrode configuration.

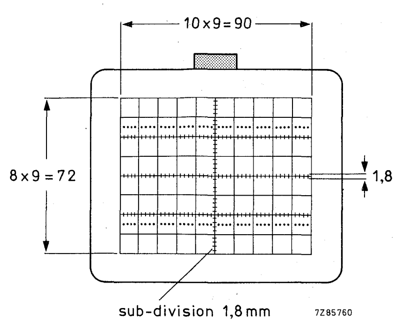


Fig. 6 Internal graticule
colour of graticule: black;
line width: 0,2 mm;
dot diameter: 0,4 mm.

INTERNAL GRATICULE ALIGNMENT

The internal graticule is aligned with the faceplate by using the faceplate reference points A1, A2 and A3, see Fig. 7.

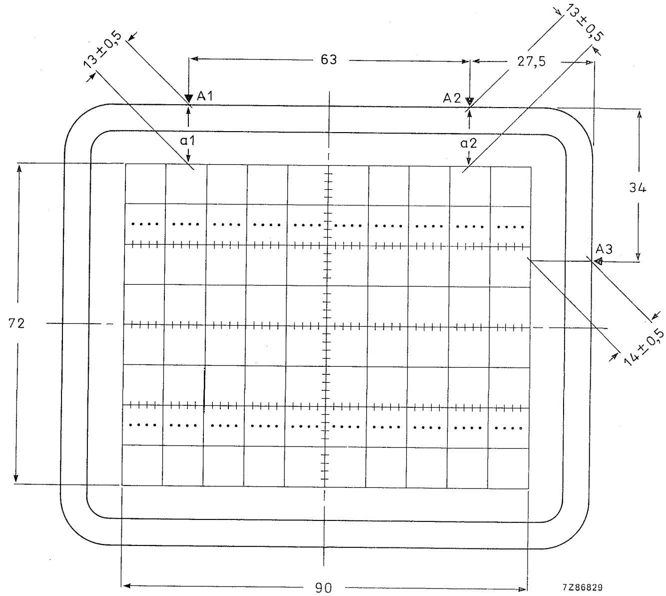


Fig. 7 Front view of tube with internal graticule. $|a1 - a2| \leqslant 0{,}3$ mm.

TYPICAL OPERATION (for notes see page 10)

Conditions

Writing section (voltages with respect to writing gun cathode k)

Final accelerator voltage	$V_{g10(\ell)}$	8500 V	note 1
Geometry control electrode voltage	V_{g6}	1500 ± 100 V	
Deflection plate shield voltage	V_{g5}	1500 V	note 2
Astigmatism control electrode voltage	V_{g4}	1500 ± 50 V	note 3
Focusing electrode voltage	V_{g3}	400 to 600 V	
First accelerator voltage	V_{g2}	1500 V	
Cut-off voltage for visual extinction of focused spot	$-V_{g1}$	45 to 85 V	

Viewing section (voltages with respect to viewing gun cathode FGK, Fig. 8)

See Fig. 9.

Note: The d.c. voltage on the first accelerator of the flood guns (FGA) should be equal to the mean x-plate potential.

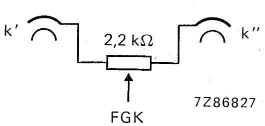


Fig. 8.

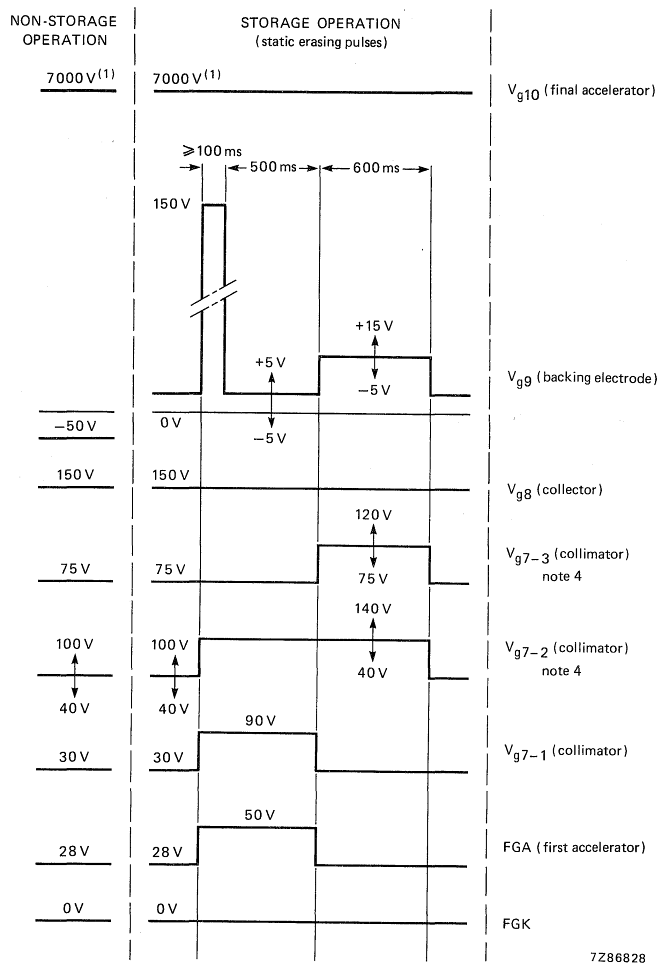


Fig. 9 Diagram of non-storage and storage operation.

(1) With respect to FGA.

Performance

Useful scan				
horizontal		min. 90 mm		
vertical		min. 72 mm		
Deflection coefficient				
horizontal	M_x	9,5 V/div max. 10,5 V/div		
vertical	M_y	4,1 V/div max. 4,4 V/div		
Line width at the centre of the screen	l.w.	0,35 mm	note 5
Writing speed in storage operation				
just black		$\geqslant$ 250 div/ms	note 6
max. write		$\geqslant$ 2,5 div/μs	note 6
Storage view time				
just black		$\geqslant$ 90 s	note 7
max. write		$\geqslant$ 15 s	note 7
Deviation of deflection linearity		max. 2 %	note 8
Geometry distortion		see note 9	
Grid drive for 10 μA beam current	V_d	approx. 25 V	
Grid drive for specified writing speed	V_d	max. 45 V	
Total cathode current of both viewing guns			
at FGA = 28 V		approx. 1 mA	
at FGA = 50 V		approx. 2 mA	

LIMITING VALUES (Absolute maximum rating system)

Writing section (voltages with respect to writing gun cathode k)

Final accelerator voltage	$V_{g10(\ell)}$	max. min.	9000 7000	V V
Geometry control electrode voltage	V_{g6}	max.	2100	V
Deflection plate shield voltage	V_{g5}	max.	2000	V
Astigmatism control electrode voltage	V_{g4}	max. min.	2100 1200	V V
Focusing electrode voltage	V_{g3}	max.	1000	V
First accelerator voltage	V_{g2}	max. min.	2000 1250	V V
Control grid voltage				
positive	V_{g1}	max.	0	V
negative	$-V_{g1}$	max.	200	V
Cathode to heater voltage				
positive	V_{kf}	max.	125	V
negative	$-V_{kf}$	max.	125	V
Voltage between astigmatism control electrode and any deflection plate	$V_{g4/x}$ $V_{g4/y}$	max. max.	500 500	V V
Grid drive, averaged over 1 ms	V_d	max.	30	V
Screen dissipation	W_{ℓ}	max.	8	mW/cm^2

Viewing section (voltages with respect to viewing gun cathode FGK)

Final accelerator voltage	$V_{g10(\ell)}$	max. min.	7500 5500	V V
Backing electrode voltage				
storage operation	V_{g9}	max. min.	+ 150 −5	V V
non-storage operation	$-V_{g9}$	max. min.	50 25	V V
Collector voltage	V_{g8}	max. min.	180 120	V V
Collimator voltage	$V_{g7\text{-}1}, V_{g7\text{-}2}, V_{g7\text{-}3}$	max. min.	200 0	V V
First accelerator voltage	V_{FGA}	max. min.	60 0	V V
Cathode to heater voltage				
positive	$V_{k'FGf}, V_{k''FGf}$	max.	125	V
negative	$-V_{k'FGf}, -V_{k''FGf}$	max.	125	V

NOTES

1. These values are valid at cut-off of both flood guns and the writing gun. The H.T. unit must be capable of supplying 0,5 mA. To protect the tube against excessive surge current during erasure, an RC network as shown in Fig. 10 must be connected in series with the screen terminal lead; the resistance of 15 to 20 MΩ includes the internal resistance of the H.T. supply.

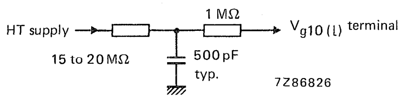


Fig. 10.

2. This voltage should be equal to the mean y-plate potential. The mean x and y-plate potentials should be equal for optimum spot quality.
3. When putting the tube into operation, the astigmatism control voltage should be adjusted only once for optimum spot size in the screen centre. The control voltage will be within the stated range, provided the conditions of note 2 are adhered to.
4. The collimator electrode voltage $V_{g7\text{-}2}$ and $V_{g7\text{-}3}$ should be adjusted for optimum uniformity of background illumination.
5. Measured with the shrinking raster method in the centre of the screen under typical operating conditions, adjusted for optimum spot size at a beam current I_b = 10 μA (measured on x-plates).
6. The writing speed is defined as the maximum speed at which a written trace is just visible starting from a background which is just black. The indicated value is guaranteed for the central 75% of the minimum screen area, except the outmost 4 mm of the screen. However, in any corner not more than 4 square divisions fall outside the guaranteed area. The writing speed can be increased, if some background is tolerated. Within the same area, a trace, written with the indicated value of max. write, remains just visible within the indicated storage time of max. write.

   The writing speed in max. write, with background, is defined as the maximum speed at which the written trace remains just visible within the indicated storage time.
7. The storage time in just black mode is defined as the time required for the brightness of the unwritten background to rise from zero brightness to 10% of saturated brightness. At reduced intensity (by pulsing the flood beams) the storage time can be increased.

   The storage time in max. write is related to the writing speed.
8. The sensitivity at a deflection less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.
9. A graticule, consisting of concentric rectangles of 72 mm x 54 mm and 69,8 mm x 52,5 mm is aligned with the electrical x-axis of the tube. With optimum corrections applied, a raster will fall between these rectangles.

OPERATING NOTES

Modes of operations

Non-storage mode

For non-storage operation the front mesh V_{g9} is set to −50 V with respect to FGK.

The viewing guns should not be switched off in this mode of operation since slight variations in raster geometry and deflection sensitivity might otherwise be caused.

Variable persistence mode

a. Dynamic erasure

Dynamic erasure can be achieved by applying extra erasing pulses of positive polarity to the backing electrode V_{g9}. The amplitude of these extra pulses is equal to that of the original erasing pulse, the frequency is 120 Hz and the persistence of the display can be controlled by varying the duty factor.

b. Static erasure (Fig. 9)

If no dynamic erasing pulses are applied the storage time is limited by the potential shift of the storage layer due to landing of positive ions.

In order to erase a stored display, V_{g9} is increased to 150 V for 100 ms and than returned to its original potential for about 500 ms; after that, an erasing pulse of positive polarity (max. 15 V) and a duration of 600 ms should be applied.

While the erasing pulse amplitude is to be adjusted with zero d.c. level for "just black", the background illumination can be changed — even with a stored signal — by varying the d.c. level for optimum contrast or maximum writing speed.

Back ground egality can be optimized by balancing the viewing gun cathodes by means of a potentiometer of 2,2 kΩ, proper collimator adjustment, and by increasing V_{FGA}. $V_{g7\text{-}1}$, $V_{g7\text{-}2}$ and $V_{g7\text{-}3}$ in positive direction during erasure.

Before first installation, depending on transport conditions, demagnetization of the tube face region may be necessary.

MONITOR AND DISPLAY TUBES

SURVEY OF MONITOR AND DISPLAY TUBES

PREFERRED TYPES: recommended for new design

M17–140W

M17–141W

M38–200

MAINTENANCE TYPES: no longer recommended for equipment production

M24–100W

M24–101W

M31–130W

M31–131W

M38–120W

M38–121W

SCREENS

Although W is the standard screen, certain applications require screens of a different persistence and/or colour (e.g. GH, GR, GM). Tubes with such screens are supplied to special order.

BONDED FACEPLATES

Tubes with bonded faceplates are supplied to special order.

MONITOR TUBE

17 cm flat-faced rectangular picture tube primarily intended for use as a viewfinder in television cameras.

QUICK REFERENCE DATA			
Deflection angle, diagonal		70	°
Focusing		electrostatic	
Resolution	min.	650	lines
Overall length	max.	234	mm

SCREEN

Metal-backed phosphor

Luminescence	white
Useful rectangle	min. 124 x 93 mm^2

HEATING

Indirect by A.C. or D.C.; parallel supply

Heater voltage	V_f	6.3	V
Heater current	I_f	300	mA

MECHANICAL DATA

Mounting position: any

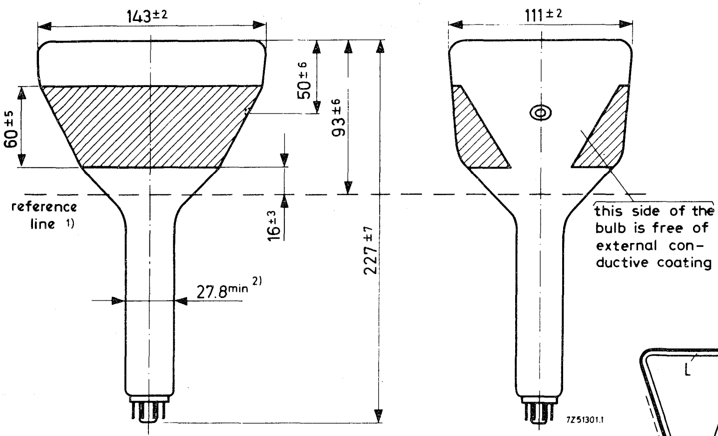
Base:	Neo Eightar (B8H)
Cavity contact	CT8

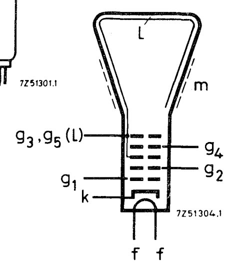
Accessories

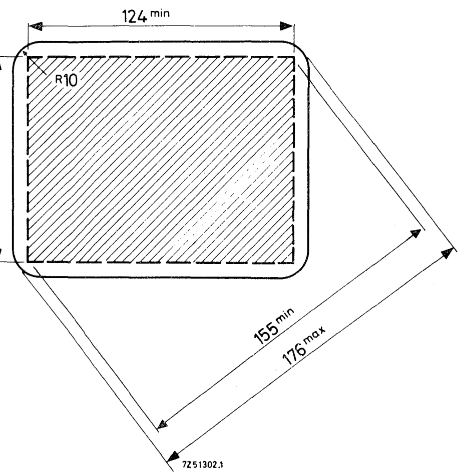
Final accelerator contact connector	55563A

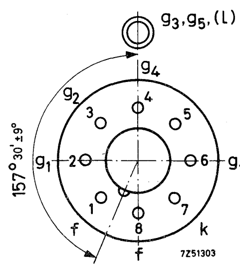
MECHANICAL DATA

Dimensions in mm









1) Reference line, determined by the plane of the upper edge of the flange of the reference line gauge when the gauge is resting on the cone.

2) The maximum dimension is determined by the reference line gauge.

FOCUSING Electrostatic

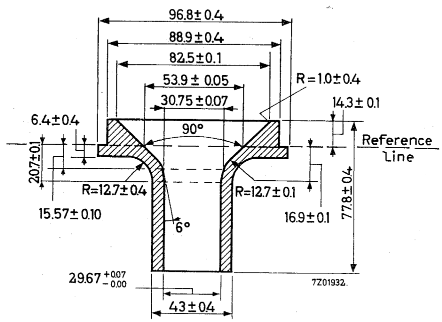
The range of focus voltage shown under "Typical operating conditions" results in optimum focus at a beam current of 50 μA.

DEFLECTION Magnetic [1]

Diagonal deflection angle 70°

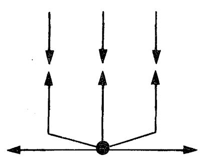
REFERENCE LINE GAUGE

Dimensions in mm



REMARK

With the high voltage used with this tube internal flash-overs may occur, which may destroy the cathode. Therefore it is necessary to provide protective circuits using sparkgaps. The sparkgaps must be connected as follows:



No other connections between outer conductive coating and chassis are permissible.

CAPACITANCES

Final accelerator to external conductive coating	$C_{g_3,g_5(\ell)/m}$	300	pF
Cathode to all other elements	C_k	5	pF
Grid No. 1 to all other elements	C_{g_1}	7	pF

[1]) Recommended deflection coil AT1071/07

TYPICAL OPERATING CONDITIONS

Final accelerator voltage	$V_{g_3, g_5(\ell)}$		14	kV
Focusing electrode voltage	V_{g_4}	0 to	400	V
First accelerator voltage	V_{g_2}		400	V
Grid no. 1 voltage for extinction of focused raster	V_{g_1}	-30 to	-62	V

RESOLUTION

Resolution at screen centre measured with shrinking raster method (non-interlaced raster)

at $V_{g_3, g_5(\ell)} = 14$ kV, $V_{g_2} = 400$ V,
$I_\ell = 50\ \mu A$, $B = 500\ cd/m^2$ (500 nit) min. 650 lines [1]

LIMITING VALUES (Absolute max. rating system)

Final accelerator voltage	$V_{g_3, g_5(\ell)}$	max.	16	kV	
		min.	12	kV	
Focusing electrode voltage	V_{g_4}	max.	1	kV	
	$-V_{g_4}$	max.	0.5	kV	
First accelerator voltage	V_{g_2}	max.	800	V	
		min.	300	V	
Grid no. 1 voltage, negative	$-V_{g_1}$	max.	150	V	
positive	V_{g_1}	max.	0	V	
positive peak	$V_{g_{1p}}$	max.	2	V	
Cathode to heater voltage, positive	V_{kf}	max.	250	V	
positive peak	V_{kf_p}	max.	300	V	[2]
negative	$-V_{kf}$	max.	135	V	
negative peak	$-V_{kf_p}$	max.	180	V	

WARNING

X-ray shielding of the cone is advisable to give protection against possible danger of personal injury arising from prolonged exposure at close range to this tube when operated above 14 kV.

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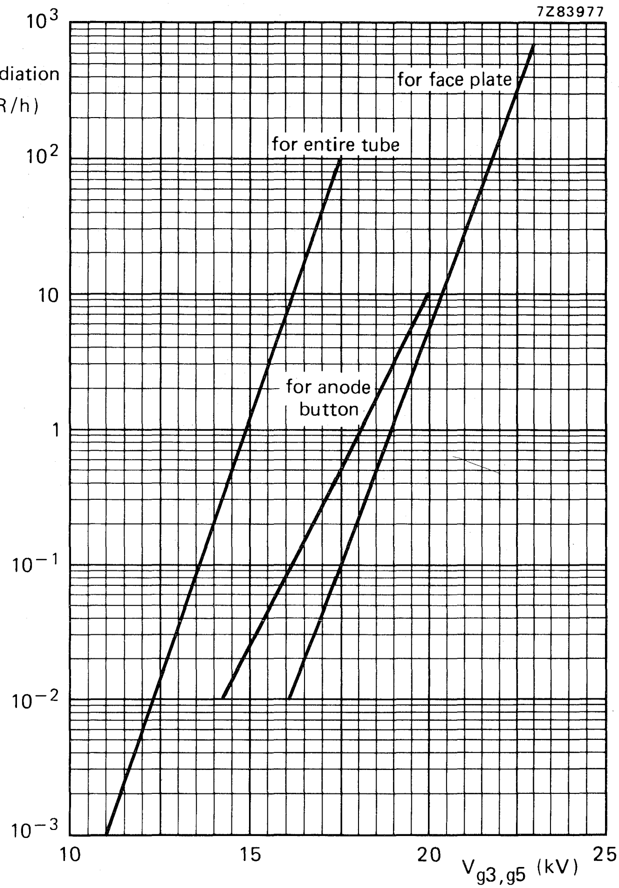
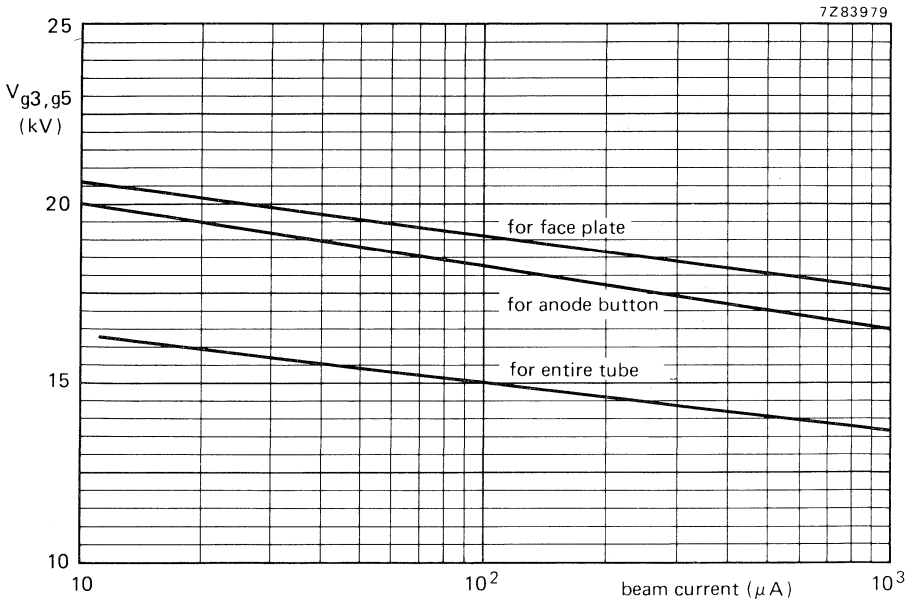
[1]) If necessary the resolution can be inproved by the use of a beam centring magnet. This magnet, type number 3322 142 11401, is supplied with each tube.

[2]) During a warm-up period not exceeding 15 s the heater may be 410 V negative with respect to the cathode.



X-radiation limit curves, at a constant anode current of 250 μA, measured according to JEDEC 64D.



0,5 mR/h isoexposure-rate limit curves, measured according to JEDEC 64D.

MONITOR TUBE

17 cm flat-faced rectangular picture tube primarily intended for use as a viewfinder in television cameras. The tube is provided with a bonded face plate and a metal mounting band.

QUICK REFERENCE DATA			
Deflection angle, diagonal		70	^{o}
Focusing		electrostatic	
Resolution	min.	700	lines
Overall length	max.	240	mm

SCREEN

Metal-backed phosphor

Luminescence	white
Useful rectangle	min. 124 x 93 mm^2

HEATING

Indirect by A.C. or D.C.; parallel supply

Heater voltage	V_f	6.3	V
Heater current	I_f	300	mA

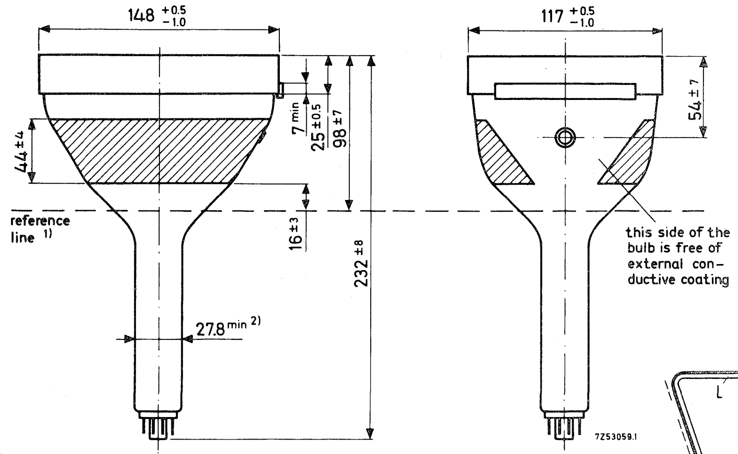
MECHANICAL DATA

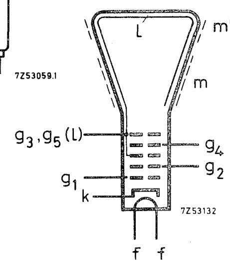
Mounting position: any

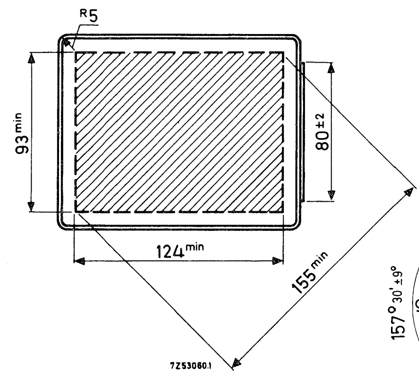
Base:	Neo Eightar (B8H)
Cavity contact	CT8
Accessories	
Final-accelerator contact connector	55563A

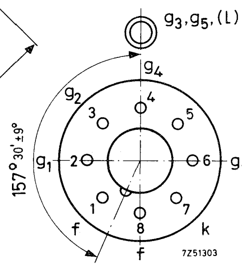
MECHANICAL DATA

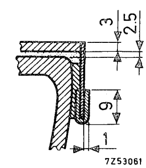
Dimensions in mm











1) Reference line, determined by the plane of the upper edge of the flange of the reference line gauge when the gauge is resting on the cone.

2) The maximum dimension is determined by the reference line gauge.

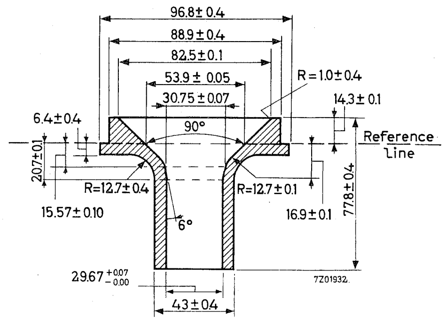
FOCUSING Electrostatic

The range of focus voltage shown under "Typical operating conditions" results in optimum focus at a beam current of 50 μA.

DEFLECTION Magnetic [1]

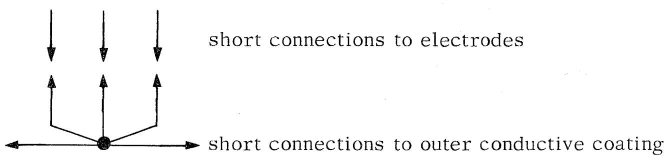
Diagonal deflection angle 70°

REFERENCE LINE GAUGE Dimensions in mm



REMARK

With the high voltage used with this tube internal flash-overs may occur, which may destroy the cathode. Therefore it is necessary to provide protective circuits using sparkgaps. The sparkgaps must be connected as follows:



No other connections between outer conductive coating and chassis are permissible.

CAPACITANCES

Final accelerator to metal band	$C_{g_3, g_5(\ell)/m'}$	135 pF
Final accelerator to external conductive coating	$C_{g_3, g_5(\ell)/m}$	240 pF
Cathode to all other elements	C_k	5 pF
Grid No.1 to all other elements	C_{g_1}	7 pF

[1]) Recommended deflection coil AT1071/07

TYPICAL OPERATING CONDITIONS

Final accelerator voltage	$V_{g3,g5(\ell)}$	14	16	kV
Focusing electrode voltage	V_{g4}	0 to 400	0 to 400	V
First accelerator voltage	V_{g2}	400	600	V
Grid no.1 voltage for extinction of focused raster	V_{g1}	-30 to -62	-40 to -90	V

RESOLUTION

Resolution at screen centre measured with shrinking raster method (non-interlaced raster)

at $V_{g3,g5(\ell)}$ = 14 kV, V_{g2} = 400 V, I_ℓ = 50 μA, B = 500 cd/m^2 (500 nit)	min.	650	lines	1)
at $V_{g3,g5(\ell)}$ = 16 kV, V_{g2} = 600 V, I_ℓ = 50 μA, B = 600 cd/m^2 (600 nit)	min.	700	lines	1)

LIMITING VALUES (Absolute max. rating system)

Final accelerator voltage	$V_{g3g5(\ell)}$	max.	18	kV	
		min.	12	kV	
Focusing electrode voltage	V_{g4}	max.	1	kV	
	$-V_{g4}$	max.	0.5	kV	
First accelerator voltage	V_{g2}	max.	800	V	
		min.	300	V	
Grid no.1 voltage, negative	$-V_{g1}$	max.	150	V	
positive	V_{g1}	max.	0	V	
positive peak	V_{g1_p}	max.	2	V	
Cathode to heater voltage, positive	V_{kf}	max.	250	V	
positive peak	V_{kf_p}	max.	300	V	2)
negative	$-V_{kf}$	max.	135	V	
negative peak	$-V_{kf_p}$	max.	180	V	

WARNING

X-ray shielding of the cone is advisable to give protection against possible danger of personal injury arising from prolonged exposure at close range to this tube when operated above 14 kV.

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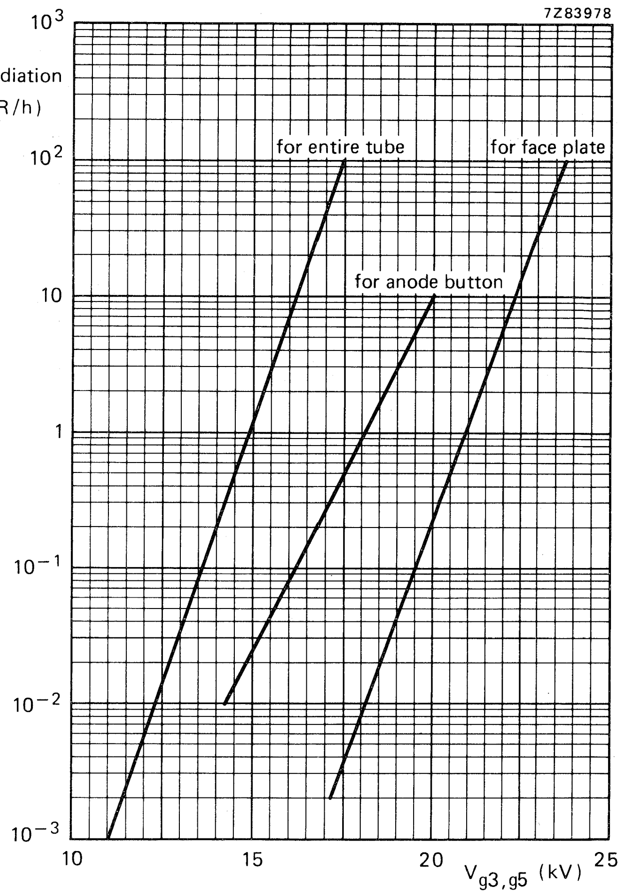
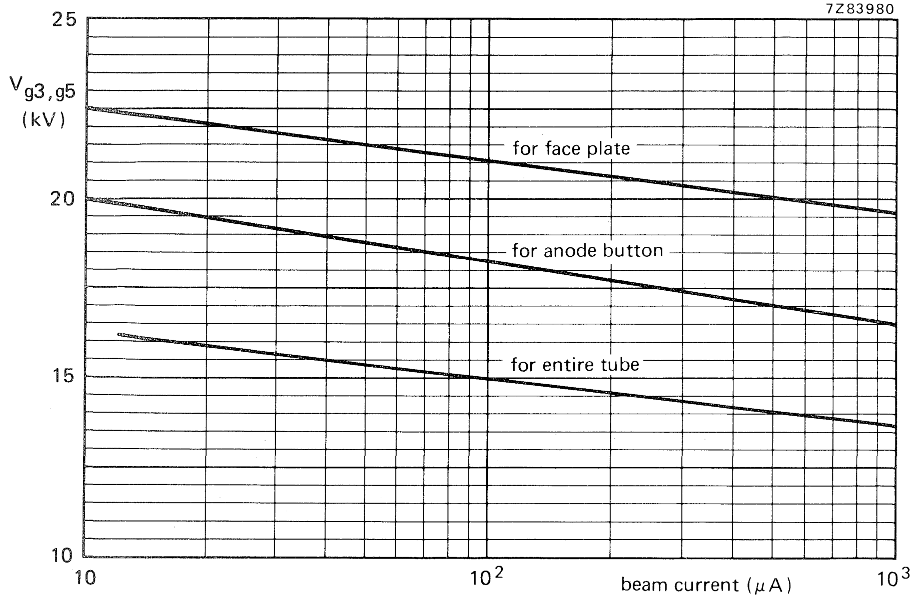
1) If necessary the resolution can be improved by the use of a beam centring magnet. This magnet, type number 3322 142 11401, is supplied with each tube.

2) During a warm-up period not exceeding 15 s the heater may be 410 V negative with respect to cathode.



X-radiation limit curves, at a constant anode current of 250 μA, measured according to JEDEC 64D.



0,5 mR/h isoexposure-rate limit curves, measured according to JEDEC 64D.

MONITOR TUBE

The M24-100W is a 24 cm-diagonal rectangular television tube with metal-backed screen primarily intended for use as a monitor or display tube.

QUICK REFERENCE DATA			
Deflection angle		90	^{o}
Focusing		electrostatic	
Resolution		900	lines
Overall length	max.	260	mm

SCREEN

Metal-backed phosphor				
Luminescence			white	
Light transmission of face glass			52	%
Useful diagonal		min.	225	mm
Useful width		min.	190	mm
Useful height		min.	140	mm

HEATING

Indirect by a.c. or d.c.; parallel supply

Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

CAPACITANCES

Final accelerator to external conductive coating	$C_{g_3,g_5(\ell)/m}$	420	pF
Cathode to all other elements	C_k	5	pF
Control grid to all other elements	C_{g_1}	7	pF

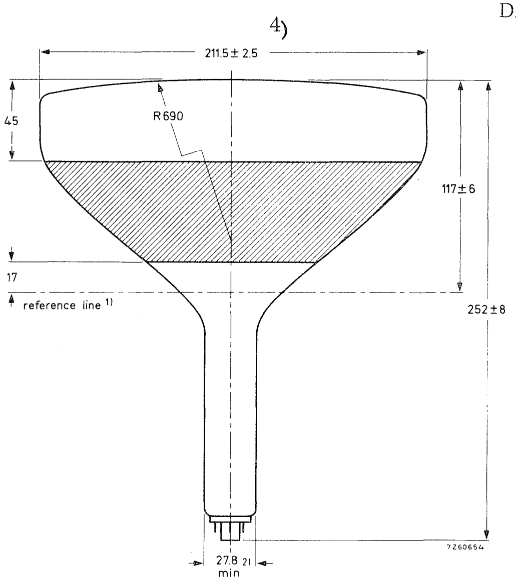
FOCUSING — electrostatic

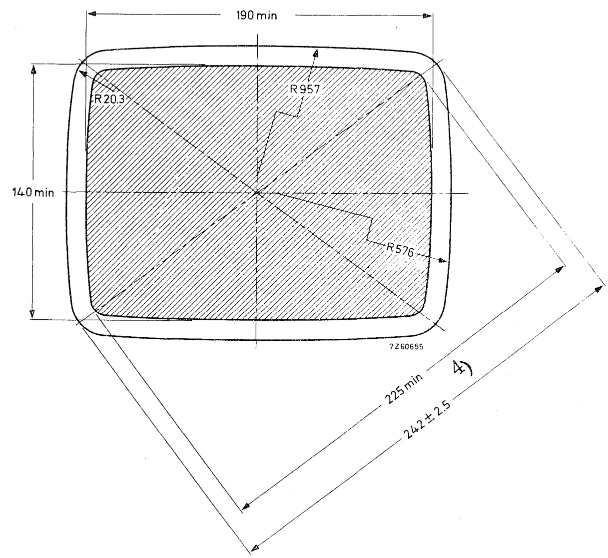
For focusing voltage providing optimum focus at a beam current of 100 μA see under "Typical operating conditions".

DEFLECTION 3) magnetic

Diagonal deflection angle 90°

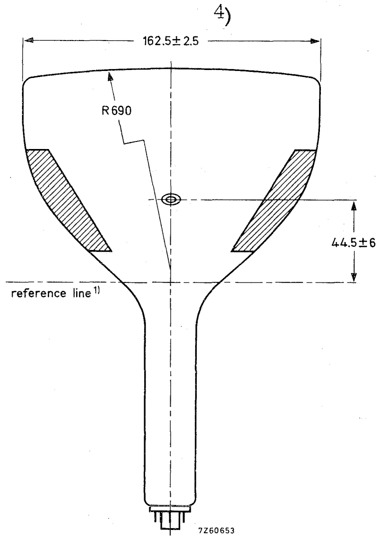
MECHANICAL DATA Dimensions in mm

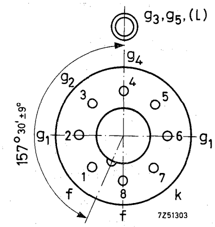


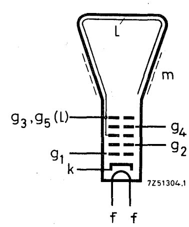


Notes see page 3

MECHANICAL DATA (continued)







Mounting position : any, except vertical with the screen downward and the axis of the tube making an angle of less than 20° with the vertical.

Base	Neo eightar (B8H)
Cavity contact	CT8
Accessories	
Socket	2422 501 06001
Final accelerator contact connector	type 55563A

PICTURE CENTRING MAGNET

Field intensity perpendicular to the tube axis adjustable from 0 to 800 A/m (0 to 10 Oe). Adjustment of the centring magnet should not be such that a general reduction in brightness or shading of the raster occurs.

NOTES

1) The reference line is determined by the plane of the upper edge of the of the flange of reference line gauge when the gauge is resting on the cone.

2) The maximum dimension is determined by the reference line gauge.

3) Deflection coil AT1071/03 is recommended. If another coil is considered, it is advisable to contact the local tube supplier.

4) The bulge at the spliceline seal may increase the indicated maximum values for envelope width, diagonal and height by not more than 6,4 mm, but at any point around the seal the bulge will not protrude more than 3,2 mm beyond the envelope surface.

TYPICAL OPERATING CONDITIONS

Final accelerator voltage	$V_{g3,g5(\ell)}$			16	kV
Focusing electrode voltage	V_{g4}	0	to	400	V
First accelerator voltage	V_{g2}			600	V
Grid no.1 voltage for extinction of focused raster	V_{g1}	-32	to	-85	V

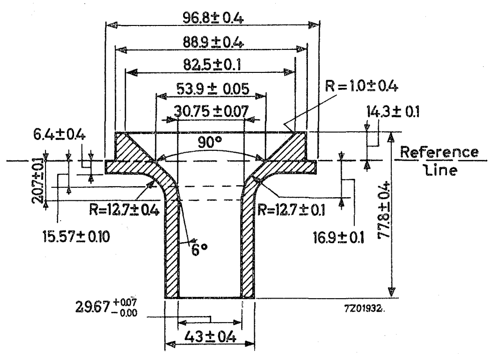
RESOLUTION

Resolution at screen centre measured with the shrinking raster method (non-interlaced raster), under typical operating conditions, at a beam current of 50 μA (200cd/m^2 = 200 nit)
The resolution can be improved by the use of beam centring magnet catalogue number 3322 142 11401, supplied on request. 900 lines

LIMITING VALUES (Absolute max. rating system)

Final accelerator voltage	$V_{g3,g5(\ell)}$	max.	18	kV
		min.	10	kV
Focusing electrode voltage	V_{g4}	max.	1	kV
	$-V_{g4}$	max.	0,5	kV
First accelerator voltage	V_{g2}	max.	800	V
		min.	300	V
Grid no.1 voltage, negative	$-V_{g1}$	max.	150	V
positive	V_{g1}	max.	0	V
positive peak	V_{g1p}	max.	2	V
Cathode to heater voltage, positive	V_{kf}	max.	250	V
positive peak	V_{kf_p}	max.	300	V [1]
negative	$-V_{kf}$	max.	135	V
negative peak	$-V_{kf_p}$	max.	180	V

REFERENCE LINE GAUGE



[1] During a warm-up period not exceeding 15 s the heater may be 410 V negative with respect to the cathode.

MONITOR TUBE

The M24-101W is a 24 cm-diagonal rectangular television tube with integral protection primarily intended for use as a monitor or display tube.

QUICK REFERENCE DATA			
Deflection angle		90 ^{o}	
Focusing		electrostatic	
Resolution		900	lines
Overall length	≤	260	mm

SCREEN

Metal backed phosphor			
Luminescence		white	
Light transmission of face glass		52	%
Useful diagonal	≥	225	mm
Useful width	≥	190	mm
Useful height	≥	140	mm

HEATING

Indirect by a.c. or d.c.; parallel supply

Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

FOCUSING

electrostatic

For focusing voltage providing optimum focus at a beam current of 100 μA see under "Typical operating conditions".

DEFLECTION

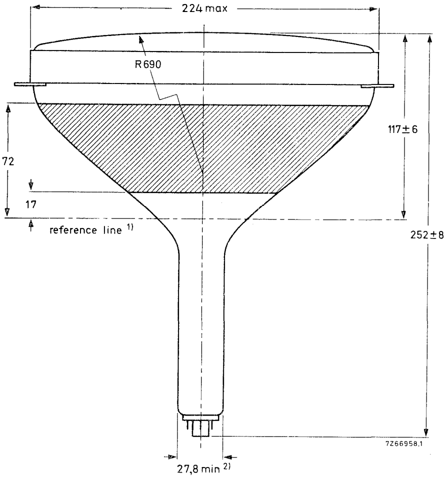
magnetic

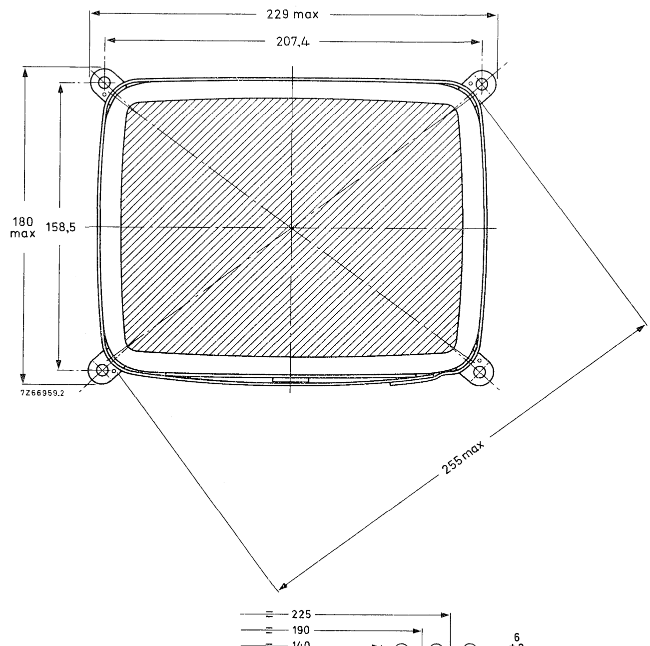
Diagonal deflection angle	90 ^{o}
Horizontal deflection angle	80 ^{o}
Vertical deflection angle	65 ^{o}

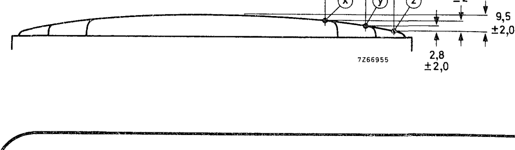
Deflection coil AT1071/03 is recommended.

MECHANICAL DATA

Dimensions in mm

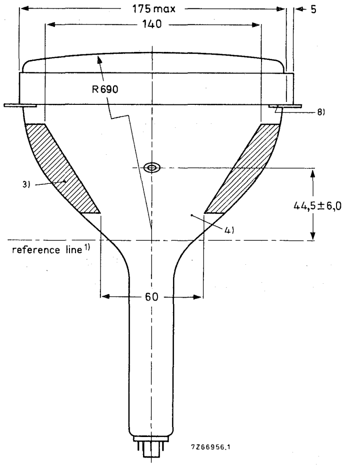


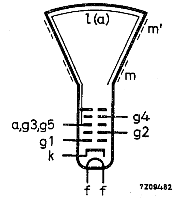


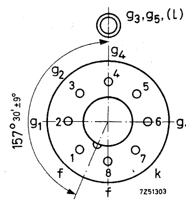


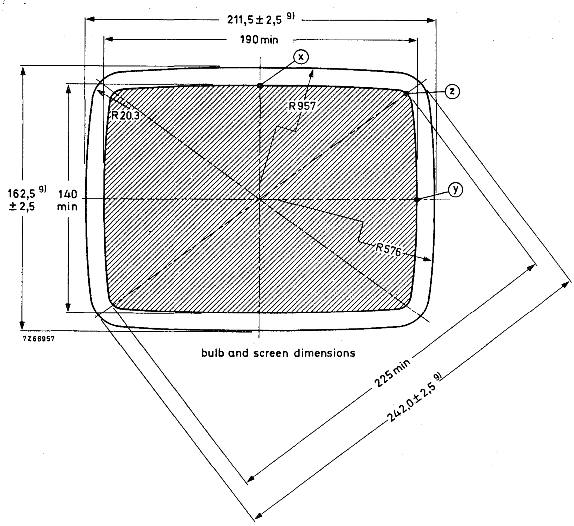
Notes see page 4.

MECHANICAL DATA (continued)

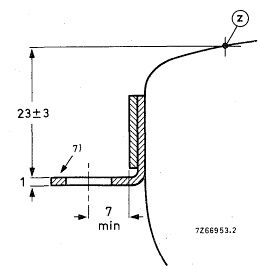


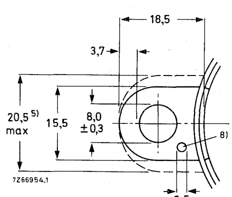






bulb and screen dimensions





Notes see page 4.

MECHANICAL DATA (continued)

Mounting position : any

Base	Neo eightar (B8H), IEC 67-I-31a
Cavity contact	CT8, IEC67-III-2
Accessories	
Socket	2422 501 06001
Final accelerator contact connector	

PICTURE CENTRING MAGNET

Field intensity perpendicular to the tube axis adjustable from 0 to 800 A/m (0 to 10 Oe). Adjustment of the centring magnet should not cause a general reduction in brightness or shading of the raster.

NOTES TO OUTLINE DRAWINGS

1) The reference line is determined by the plane of the upper edge of the flange of the reference line gauge with the gauge resting on the cone.

2) The maximum dimension is determined by the reference line gauge.

3) This tube has an external conductive coating (m), which must be earthed. The capacitance of this coating to the final accelerator is used for smoothing the EHT. The tube marking and warning labels are on the side of the cone opposite the final accelerator contact, and this side should not be used for making contact to the conductive coating.

4) This area must be kept clean.

5) Minimum space to be reserved for mounting lugs.

6) The mounting screws in the cabinet must be situated within a circle with a diameter of 4 mm drawn around the true geometrical position (corners of a rectangle of 207,4 mm x 158,5 mm).

7) The maximum displacement of any lug with respect to the plane through the other three lugs is 2 mm.

8) The metal rim-band must be earthed. The hole of 2,5 mm diameter in each lug is provided for this purpose.

9) The bulge at the spliceline seal may increase the indicated maximum values for envelope width, diagonal and height by not more than 6,4 mm, but at any point around the seal the bulge will not protrude more than 3,2 mm beyond the envelope surface.

CAPACITANCES

Final accelerator to external conductive coating	$C_{g3,\ g5(\ell)/m}$			420	pF
Final accelerator to metal band	$C_{g3,\ g5(\ell)/m'}$			200	pF
Cathode to all other elements	C_k			5	pF
Control grid to all other elements	C_{g1}			7	pF

TYPICAL OPERATING CONDITIONS

Final accelerator voltage	$V_{g3,\ g5(\ell)}$			16	kV
Focusing electrode voltage	V_{g4}	0	to	400	V
First accelerator voltage	V_{g2}			600	V
Grid 1 voltage for extinction of focused raster	V_{g1}	-32	to	-85	V

RESOLUTION

Resolution at screen centre measured with the shrinking raster method (non-interlaced raster), under typical operating conditions, and at a beam current of 50 μA: 900 lines (luminance ≈200 cd/m^2).

If necessary, the picture quality can be improved by using a beam centring magnet. This magnet, catalogue number 3322 142 11401, can be supplied on request.

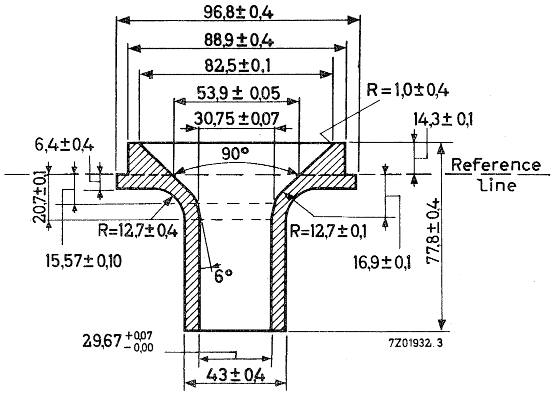
LIMITING VALUES (Absolute max. rating system)

Final accelerator voltage		$V_{g3,\ g5(\ell)}$	max.	18	kV
			min.	10	kV
Focusing electrode voltage,	positive	V_{g4}	max.	1000	V
	negative	$-V_{g4}$	max.	500	V
First accelerator voltage		V_{g2}	max.	800	V
			min.	300	V
Grid 1 voltage,	negative	$-V_{g1}$	max.	150	V
	positive	V_{g1}	max.	0	V
	positive peak	V_{g1p}	max.	2	V
Cathode to heater voltage,	positive	V_{kf}	max.	250	V
	positive peak	V_{kfp}	max.	300	V [1]
	negative	$-V_{kf}$	max.	135	V
	negative peak	$-V_{kfp}$	max.	180	V

[1] During a warm-up period not exceeding 15 s the heater may be 410 V negative with respect to the cathode.

REFERENCE LINE GAUGE

Dimensions in mm



MONITOR TUBE

The M31-130W is a 31 cm-diagonal rectangular television tube with metal-backed screen primarily intended for use as a monitor or display tube.

QUICK REFERENCE DATA			
Deflection angle		90 °	
Focusing	electrostatic		
Resolution		900	lines
Overall length	max.	310	mm

SCREEN

Metal-backed phosphor			
Luminescence		white	
Light transmission of face glass	approx.	50	%
Useful diagonal	min.	295	mm
Useful width	min.	257	mm
Useful height	min.	195	mm

HEATING

Indirect by a.c. or d.c.; parallel supply

Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

FOCUSING electrostatic

For focusing voltage providing optimum focus at a beam current of 100 μA see under "Typical operating conditions".

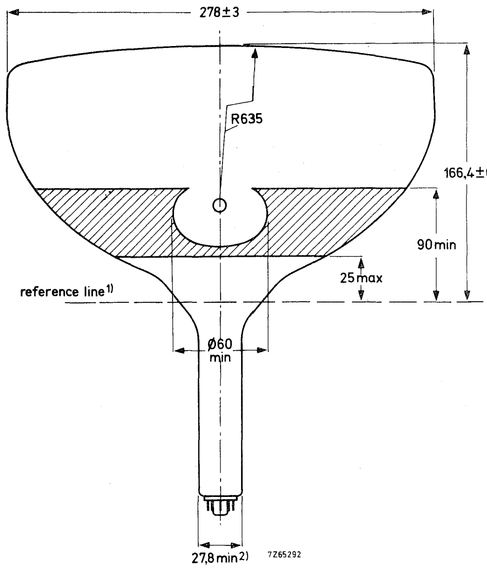
DEFLECTION magnetic

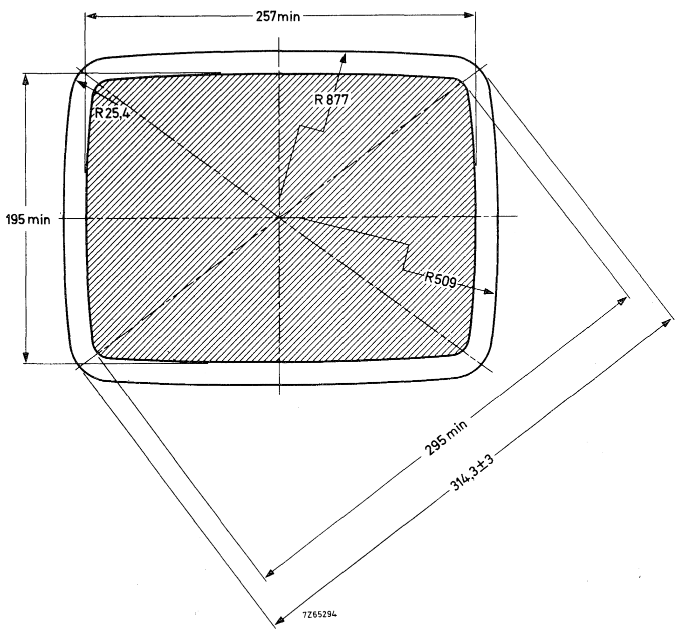
Diagonal deflection angle 90 °

Deflection coil AT1071/03 is recommended.

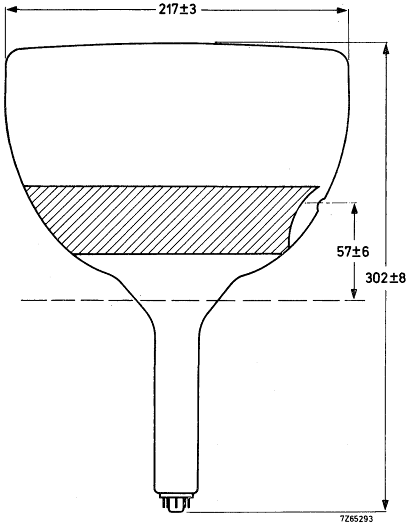
MECHANICAL DATA

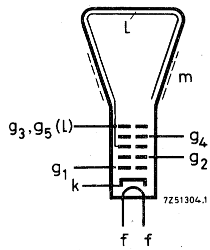
Dimensions in mm

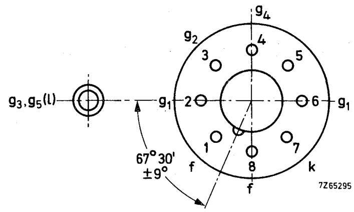




MECHANICAL DATA (continued)







Mounting position: any, except vertical with the screen down and the axis of the tube making an angle of less than 20^{o} with the vertical.

Base	Neo eightar (B8H), IEC67-I-31a
Cavity contact	CT8, IEC67-III-2
Accessories	
Socket	2422 501 06001
Final accelerator contact connector	type 55563A

CAPACITANCES

Final accelerator to external conductive coating	$C_{g3,\, g5(\ell)/m}$	1100	pF
Cathode to all other elements	C_k	5	pF
Control grid to all other elements	C_{g1}	7	pF

[1]) The reference line is determined by the plane of the upper edge of the flange of the reference line gauge with the gauge resting on the cone.

[2]) The maximum dimension is determined by the reference line gauge.

TYPICAL OPERATING CONDITIONS

Final accelerator voltage	$V_{g3,\,g5(\ell)}$	16	kV
Focusing electrode voltage	V_{g4}	0 to 400	V
First accelerator voltage	V_{g2}	600	V
Grid no. 1 voltage for extinction of focused raster	V_{g1}	−32 to −85	V

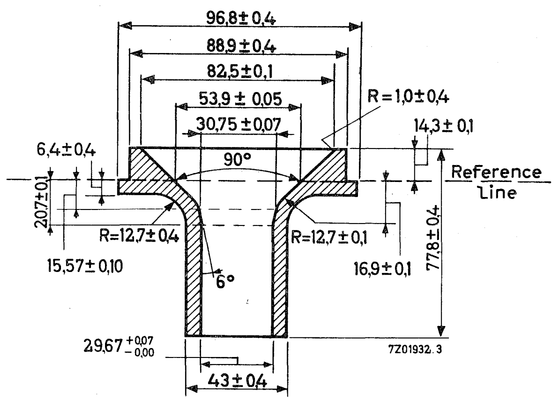
RESOLUTION

Resolution at screen centre measured with the shrinking raster method (non-interlaced raster), under typical operating conditions, and at a beam current of 50 μA: 900 lines
The resolution can be improved by the use of beam centring magnet, catalogue number 3322 142 11401, supplied on request.

LIMITING VALUES (Absolute max. rating system)

Final accelerator voltage	$V_{g3},\ g5(\ell)$	max.	18	kV	
		min.	10	kV	
Focusing electrode voltage, positive	V_{g4}	max.	1000	V	
	$-V_{g4}$	max.	500	V	
First accelerator voltage	V_{g2}	max.	800	V	
		min.	300	V	
Grid no. 1 voltage, negative	$-V_{g1}$	max.	150	V	
positive	V_{g1}	max.	0	V	
positive peak	V_{g1p}	max.	2	V	
Cathode to heater voltage, positive	V_{kf}	max.	250	V	
positive peak	V_{kfp}	max.	300	V	1)
negative	$-V_{kf}$	max.	135	V	
negative peak	$-V_{kfp}$	max.	180	V	

REFERENCE LINE GAUGE



1) During a warm-up period not exceeding 15 s the heater may be 410 V negative with respect to the cathode.

MONITOR TUBE

The M31-131W is a 31 cm-diagonal rectangular television tube with integral protection primarily intended for use as a monitor or display tube.

QUICK REFERENCE DATA			
Deflection angle		90 ^{o}	
Focusing		electrostatic	
Resolution		900	lines
Overall length	≤	310	mm

SCREEN

Metal backed phosphor

Luminescence		white	
Light transmission of face glass	approx.	50	%
Useful diagonal	≥	295	mm
Useful width	≥	257	mm
Useful height	≥	195	mm

HEATING

Indirect by a.c. or d.c.; parallel supply

Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

FOCUSING — electrostatic

For focusing voltage providing optimum focus at a beam current of 100 µA see under "Typical operating conditions".

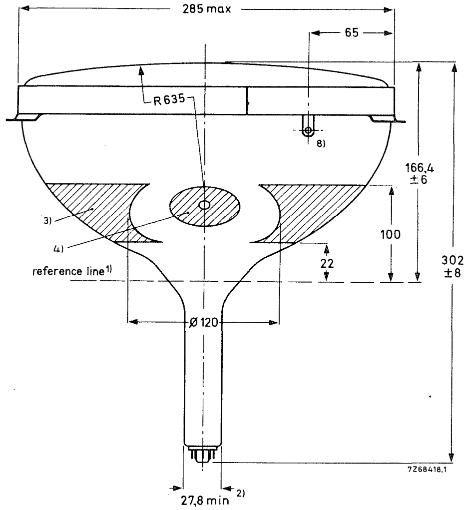
DEFLECTION — magnetic

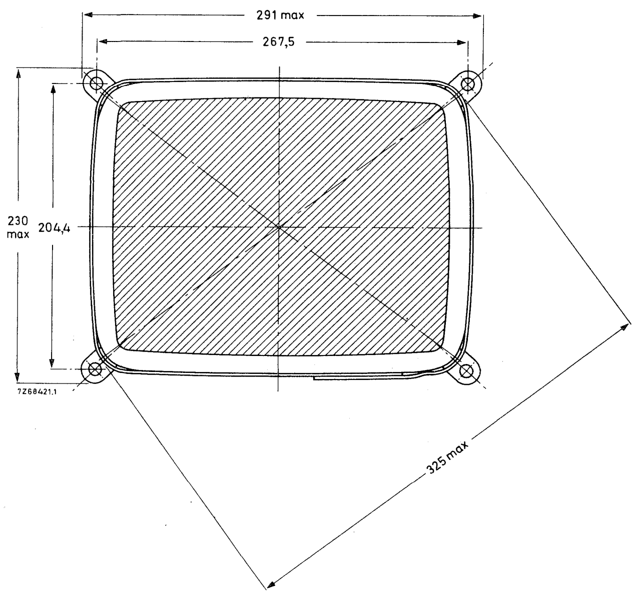
Diagonal deflection angle 90 ^{o}

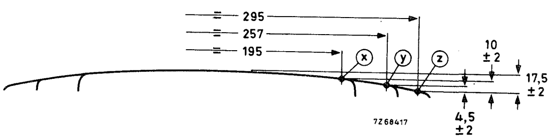
Deflection coil AT1071/03 is recommended.

MECHANICAL DATA

Dimensions in mm



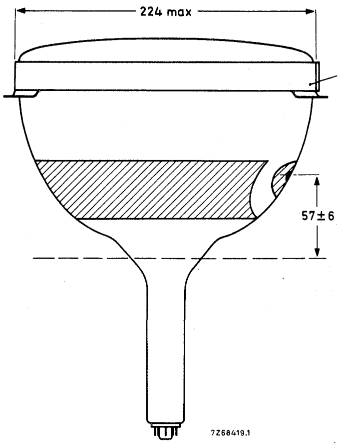


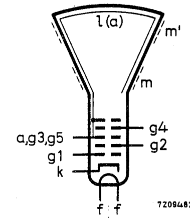


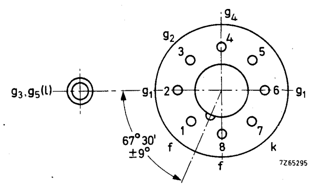
Notes see page 4

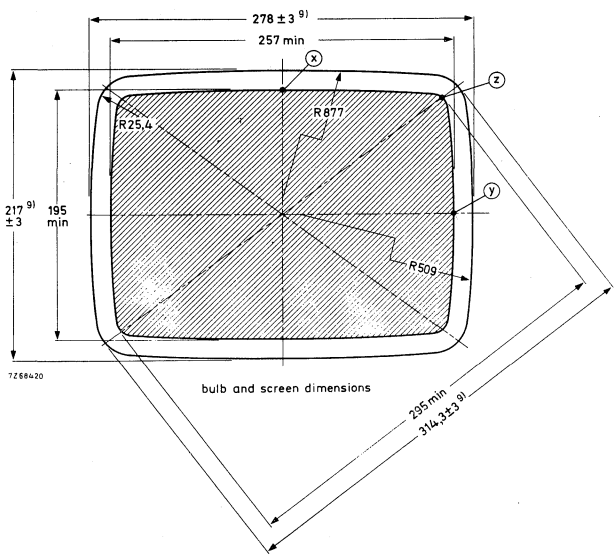
MECHANICAL DATA (continued)

Dimensions in mm

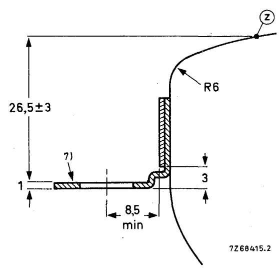


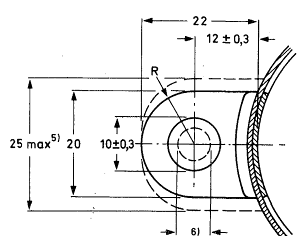






bulb and screen dimensions





Notes see page 4.

MECHANICAL DATA (contimued)

Mounting position : any

Base	Neo eightar (B8H), IEC 67-I-31a
Cavity contact	CT8, IEC 67-III-2
Accessories	
Socket	2422 501 06001
Final accelerator contact connector	type 55563A

PICTURE CENTRING MAGNET

Field intensity perpendicular to the tube axis adjustable from 0 to 800 A/m (0 to 10 Oe). Adjustment of the centring magnet should not cause a general reduction in brightness or shading the raster.

NOTES TO OUTLINE DRAWINGS

1) The reference line is determined by the plane of the upper edge of the flange of the reference line gauge with the gauge resting on the cone.
2) The maximum dimension is determined by the reference line gauge.
3) This tube has a external conductive coating (m), which must be earthed. The capacitance of this coating to the final accelerator is used for smoothing the EHT. The tube marking and warning labels are on the side of the cone opposite the final accelerator contact, and this side should not be used for making contact to the conductive coating.
4) This area must be kept clean.
5) Minimum space to be reserved for mounting lugs.
6) The mounting screws in the cabinet must be situated within a circle with a diameter of 6 mm drawn around the true geometrical position (corners of a rectangle of 267, 5 mm x 204, 4 mm).
7) The maximum displacement of any lug, with respect to the plane through the other three lugs is 2 mm.
8) The metal rim-band must be earthed. For this purpose the band is provided with a tag.
9) The bulge of the spliceline seal may increase the indicated maximum values for envelope width, diagonal, and height by not more than 6, 4 mm, but at any point around the seal the bulge will not protrude more than 3, 2 mm beyond the envelope surface.

CAPACITANCES

Final accelerator to external conductive coating	$C_{g3, g5(\ell)/m}$	1200	pF
Final accelerator to metal band	$C_{g3, g5(\ell)/m}$	150	pF
Cathode to all other elements	C_k	5	pF
Control grid to all other elements	C_{g1}	7	pF

TYPICAL OPERATING CONDITIONS

Final accelerator voltage	$V_{g3, g5(\ell)}$	16	kV
Focusing electrode voltage	V_{g4}	0 to 400	V
First accelerator voltage	V_{g2}	600	V
Grid 1 voltage for extinction of focused raster	V_{g1}	-32 to -85	V

RESOLUTION

Resolution at screen centre measured with the shrinking raster method (non-interlaced raster), under typical operating conditions, and at a beam current of 50 μA: 900 lines

If necessary, the picture quality can be improved by using a beam centring magnet. This magnet, catalogue number 3322 142 11401, can be supplied on request.

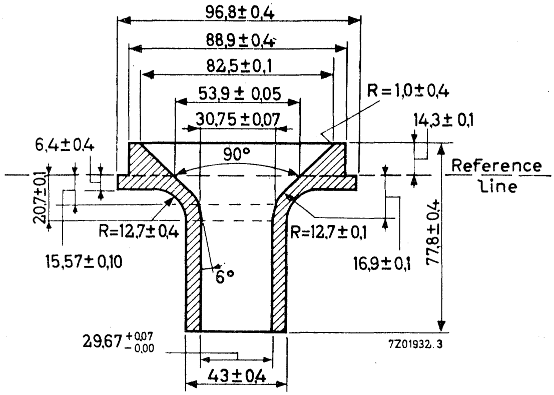
LIMITING VALUES (Absolute max. rating system)

Final accelerator voltage	$V_{g3, g5(\ell)}$	max.	18	kV
		min.	10	kV
Focusing electrode voltage, positive	V_{g4}	max.	1000	V
negative	$-V_{g4}$	max.	500	V
First accelerator voltage	V_{g2}	max.	800	V
		min.	300	V
Grid voltage, negative	$-V_{g1}$	max.	150	V
positive	V_{g1}	max.	0	V
positive peak	V_{g1p}	max.	2	V
Cathode to heater voltage, positive	V_{kf}	max.	250	V
positive peak	V_{kf_p}	max.	300	V
negative	$-V_{kf}$	max.	135	V [1]
negative peak	$-V_{kf_p}$	max.	180	V

1) During a warm-up period not exceeding 15 s the heater may be 410 V negative with respect to the cathode.

REFERENCE LINE GAUGE

Dimensions in mm



MONITOR TUBE

The M38-120W is a 38 cm-diagonal rectangular television tube with metal backed screen and integral protection primarily intended for use as a monitor tube.
On request this tube can also be supplied with a WA screen phosphor.

QUICK REFERENCE DATA			
Deflection angle		110 ^{o}	
Focusing		electrostatic	
Resolution	min.	650	lines
Overall length	max.	279,5	mm

SCREEN

Metal backed phosphor

Luminescence		white	
Light transmission of face glass		50	%
Useful diagonal	min.	350	mm
Useful width	min.	290	mm
Useful height	min.	226	mm

HEATING

Indirect by a.c. or d.c.; parallel or series supply

Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

FOCUSING

electrostatic

For focusing voltage providing optimum focus at screen centre at a beam current of 100 μA see under "Typical operating conditions".

DEFLECTION

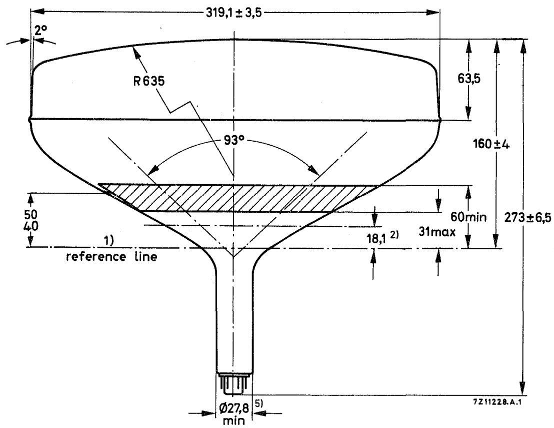
magnetic

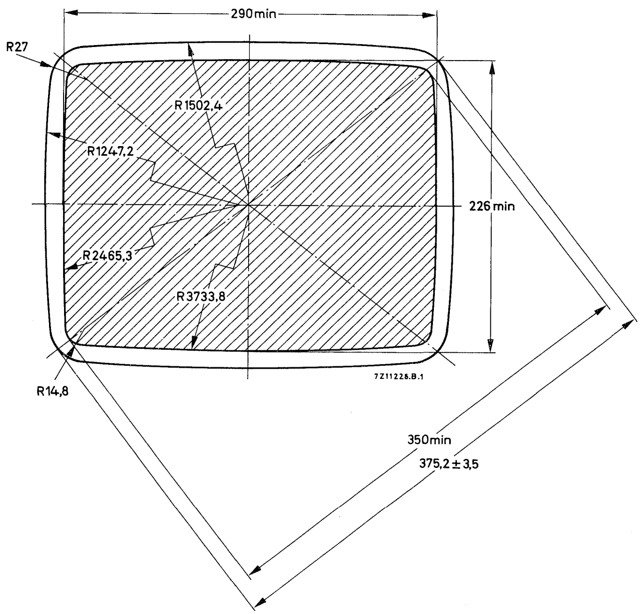
Diagonal deflection angle	110 ^{o}
Horizontal deflection angle	93 ^{o}
Vertical deflection angle	76 ^{o}

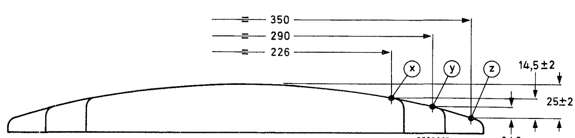
Deflection coil AT1038/40A or AT1039/.. is recommended.

MECHANICAL DATA

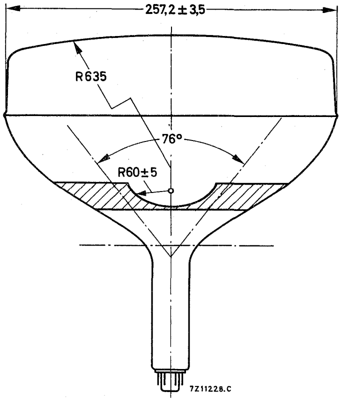
Dimensions in mm

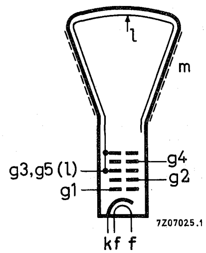


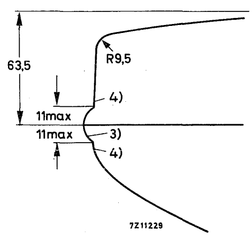


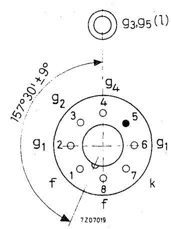


MECHANICAL DATA (continued)









Mounting position: any

Base	Neo eightar (B8H), IEC67-I-31a
Cavity contact	CT8, IEC67-III-2
Accessories	
Final accelerator contact connector	type 55563A
Socket	2422 501 06001

NOTES TO OUTLINE DRAWING

1) The reference line is determined by the plane of the upper edge of the flange of referencc line gauge, (JEDEC126) when the gauge is resting on the cone.

2) End of guaranteed contour. The maximum neck and cone contour is given by the Reference line gauge (see page 4).

3) Bulge at splice-line seal may increase the indicated maximum value for envelope width, diagonal and height by not more than 6,4 mm, but at any point around the seal, the bulge will not protrude more than 3,2 mm beyond the envelope surface at the location specified for dimensioning the envelope width, diagonal and height.

4) The tube should be supported on both sides of the bulge. The mechanism used should provide clearance for the maximum dimensions of the bulge.

5) The maximum dimension is determined by the reference line gauge

PICTURE CENTRING MAGNET

Field intensity perpendicular to the tube axis adjustable from 0 to 800 A/m (0 to 10 oersted). Adjustment of the centring magnet should not be such that a general reduction in brightness or shading of the raster occurs.

CAPACITANCE

Control grid to all other elements	C_{g1}	6,0	pF
Cathode to all other elements	C_k	5,0	pF
Final accelerator to external conductive coating	$C_{g3,g5(\ell)/m}$	600	pF

TYPICAL OPERATING CONDITIONS

Final accelerator voltage	$V_{g3,g5(\ell)}$	16	kV
Focusing electrode voltage	V_{g4}	0 to 400	V [1]
First accelerator voltage	V_{g2}	400	V
Grid No. 1 voltage for visual extinction of a focused raster	$-V_{g1}$	40 to 85	V

RESOLUTION

Resolution at screen centre, measured with the shrinking raster method (non-interlaced raster), under typical operating conditions, a beam current of 100 μA, and focusing voltage adjusted for optimum spot size min. 650 lines

LIMITING VALUES (Absolute max. rating system)

Voltages are specified with respect to cathode unless otherwise stated.

Final accelerator voltage		$V_{g3,g5(\ell)}$	max.	18	kV
			min.	13	kV
Focusing electrode voltage		V_{g4}	max.	1	kV
		$-V_{g4}$	max.	0,5	kV
First accelerator voltage		V_{g2}	max.	550	V
			min.	350	V
Control grid voltage,	negative	$-V_{g1}$	max.	150	V
	positive	V_{g1}	max.	0	V
	positive peak	V_{g1_p}	max.	2	V
Cathode to heater voltage,	positive	V_{kf}	max.	250	V
	positive peak	V_{kf_p}	max.	300	V
	negative	$-V_{kf}$	max.	135	V
	negative peak	$-V_{kf_p}$	max.	180	V

[1]) With the small change in focus spot size with variation of focus voltage the limit of 0 to 400 V is such that an acceptable focus quality is obtained within this range. If it is required to pass through the point of focus, a voltage of at least −100 V to +500 V will be required.

CIRCUIT DESIGN VALUES

Focusing electrode current, positive	I_{g_4}	max.	25	μA
negative	$-I_{g_4}$	max.	25	μA
Grid no. 2 current, positive	I_{g_2}	max.	5	μA
negative	$-I_{g_2}$	max.	5	μA

MAXIMUM CIRCUIT VALUES

Resistance between cathode and heater	R_{kf}	max.	1	MΩ
Impedance between cathode and heater (f = 50 Hz)	Z_{kf}	max.	500	kΩ
Resistance between grid no. 1 and earth	R_{g_1}	max.	1,5	MΩ
Impedance between cathode and earth (f = 50 Hz)	Z_k	max.	100	kΩ

WARNING

X-ray shielding is advisable to give protection against possible danger of personal injury arising from prolonged exposure at close range to this tube when operated above 16 kV.

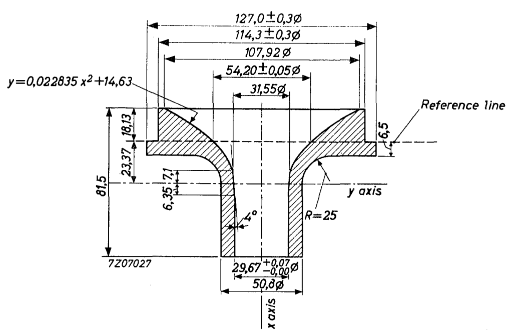
EXTERNAL CONDUCTIVE COATING

This tube has an external conductive coating (m), which must be earthed and capacitance of this to the final electrode is used to provide smoothing for the EHT supply. The tube marking and warning labels are on the side of the cone opposite the final electrode connector and this side should not be used for making contact to the external conductive coating.

REFERENCE LINE GAUGE

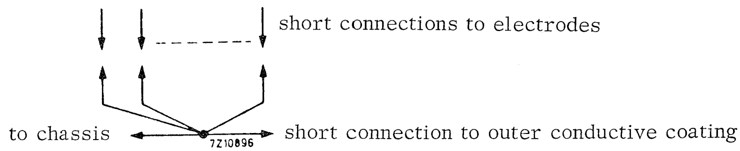
Dimensions in mm

JEDEC 126



REMARK

With the high voltage used with this tube internal flash-overs may occur. These may destroy the cathode of the tube. Therefore it is necessary to provide protective circuits, using spark gaps.
The spark gaps must be connected as follows:



No other connections between the outer conductive coating and the chassis are permissible.

On request the tube can be supplied with spark traps mounted in the base (ring trap base).

MONITOR TUBE

The M38-121 is a 38 cm-diagonal rectangular television tube with metal backed screen and integral protection primarily intended for use as a monitor or display tube.

QUICK REFERENCE DATA			
Deflection angle		110°	
Focusing		electrostatic	
Resolution	min.	650	lines
Overall length	max.	279,5	mm

SCREEN

Metal backed phosphor			
Luminescence		white	
Light transmission of face glass		50	%
Useful diagonal	min.	350	mm
Useful width	min.	290	mm
Useful height	min.	226	mm

HEATING

Indirect by a.c. or d.c.; parallel or series supply

Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

FOCUSING — electrostatic

For focusing voltage providing optimum focus at screen centre at a beam current of 100 μA see under "Typical operating conditions".

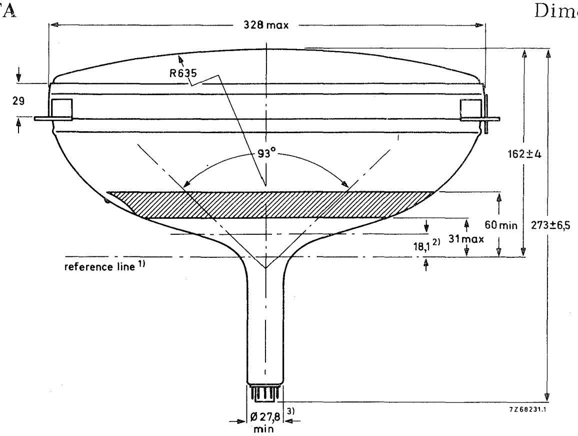
DEFLECTION — magnetic

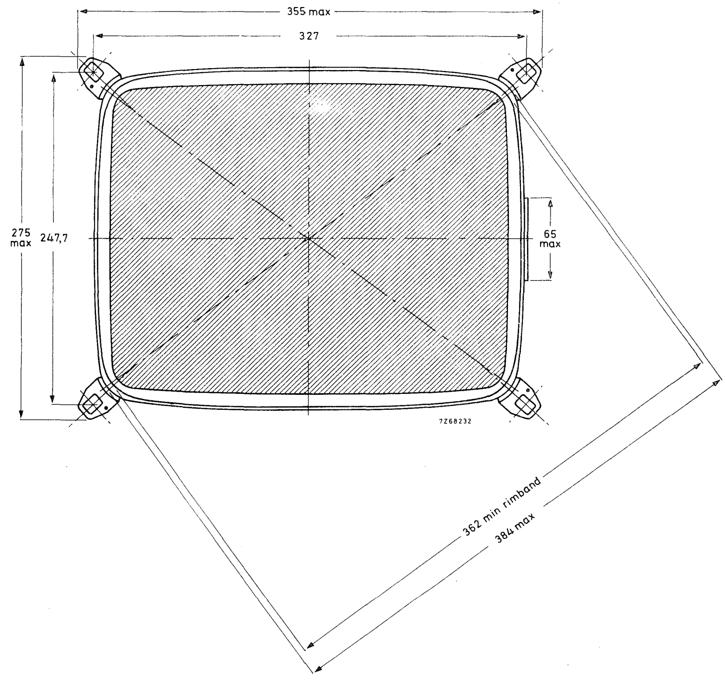
Diagonal deflection angle	110°
Horizontal deflection angle	93°
Vertical deflection angle	76°

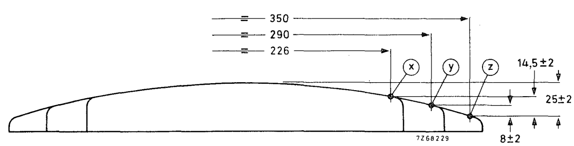
Deflection coil AT1038/40A or AT1039/.. is recommended.

MECHANICAL DATA

Dimensions in mm

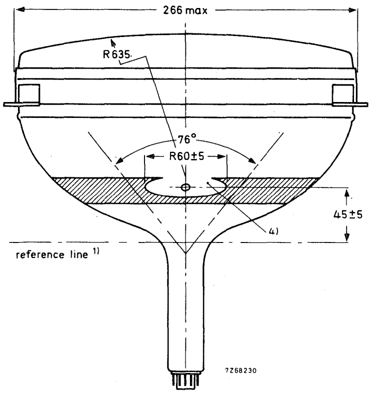


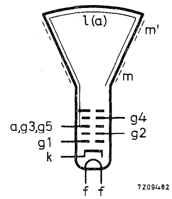


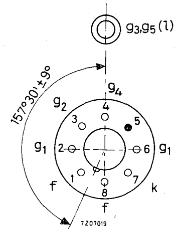


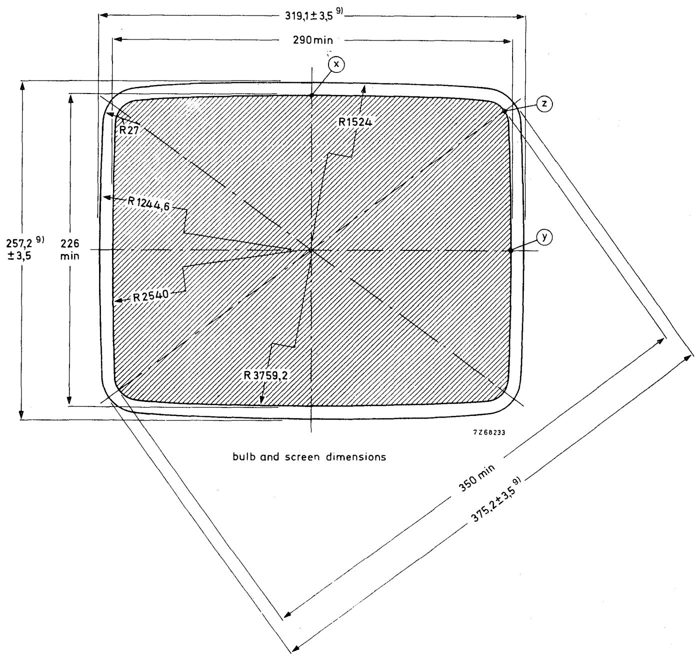
MECHANICAL DATA (continued)

Dimensions in mm

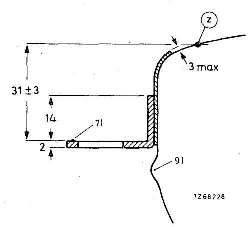


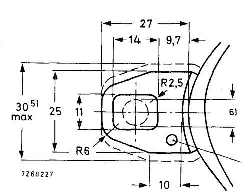






bulb and screen dimensions





MECHANICAL DATA (continued)

Mounting position: any

Base	Neo eightar (B8H), IEC67-I-31a
Cavity contact	CT8, IEC67-III-2
Accessories	
Socket	2422 501 06001
Final accelerator contact connector	type 55563

PICTURE CENTRING MAGNET

Field intensity perpendicular to the tube axis from 0 to 800 A/m (0 to 10 Oe). Adjustment of the centring magnet should not cause a general reduction in brightness or shading of the raster.

NOTES TO OUTLINE DRAWING

1) The reference line is determined by the plane of the upper edge of the flange of the reference line gauge, (JEDEC 126) when the gauge is resting on the cone.

2) End of guaranteed contour. The maximum neck and cone countour is given by the reference line gauge.

3) The maximum dimension is given by the reference line gauge.

4) This area must be kept clean.

5) Minimum space to the reserved for mounting lugs.

6) The mounting screws in the cabinet must be situated within a circle with a diameter of 7,5 mm drawn around the true geometrical positions (corners of a rectangle of 327 mm x 247,7 mm).

7) The maximum displacement of any lug with respect to the plane trough the other three lugs is 2 mm.

8) The metal rimband must be earthed. Holes of 3 mm diameter in each lug are provided for this purpose.

9) The bulge at the pliceline seal may increase the indicated maximum value for envelope width, diagonal and height by not more than 6,4 mm, but at any point around the seal the bulge will not protrude more than 3,2 mm beyond the envelope surface.

CAPACITANCES

Final accelerator to external conductive coating	$C_{g3,\,g5(\ell)/m}$	450 to 650	pF
Final accelerator to metal band	$C_{g3,\,g5\&\ell 9/m'}$	240	pF
Cathode to all other elements	C_k	5	pF
Control grid to all other elements	C_{g1}	6	pF

TYPICAL OPERATING CONDITIONS

Final accelerator voltage	$V_{g3,\,g5(\ell)}$	16	kV
Focusing electrode voltage	V_{g4}	0 to 400	V [1]
First accelerator voltage	V_{g2}	400	V
Grid No. 1 voltage for visual extinction of a focused raster	$-V_{g1}$	40 to 85	V

RESOLUTION

Resolution at screen centre, measured with the shrinking raster method (non-interlaced raster), under typical operating conditions, a beam current of 100 μA, and focusing voltage adjusted for optimum spot size min. 650 lines

LIMITING VALUES (Absolute max. rating system)

Voltages are specified with respect to cathode unless otherwise stated.

Final accelerator voltage	$V_{g3,\,g5(\ell)}$	max. 18	kV
		min. 13	kV
Focusing electrode voltage	V_{g4}	max. 1000	V
	$-V_{g4}$	max. 500	V
First accelerator voltage	V_{g2}	max. 550	V
		min. 350	V
Control grid voltage, negative	$-V_{g1}$	max. 150	V
positive	V_{g1}	max. 0	V
positive peak	V_{g1p}	max. 2	V
Cathode to heater voltage, positive	V_{kf}	max. 250	V
positive peak	V_{kfp}	max. 300	V
negative	$-V_{kf}$	max. 135	V
negative peak	$-V_{kfp}$	max. 180	V

[1]) With the small change in focus spot size with variation of focus voltage the limit of 0 to 400 V is such that an acceptable focus quality is obtained within this range. If it is required to pass through the point of focus, a voltage range of at least -100 to +500 V will be required.

CIRCUIT DESIGN VALUES

Focusing electrode current, positive	I_{g4}	max.	25	μA
negative	$-I_{g4}$	max.	25	μA
Grid No. 2 current, positive	I_{g2}	max.	5	μA
negative	$-I_{g2}$	max.	5	μA

MAXIMUM CIRCUIT VALUES

Resistance between cathode and heater	R_{kf}	max.	1	MΩ
Impedance between cathode and heater (f = 50 Hz)	Z_{kf}	max.	500	kΩ
Resistance between grid no. 1 and earth	R_{g1}	max.	1,5	MΩ
Impedance between cathode and earth (f = 50 Hz)	Z_k	max.	100	kΩ

WARNING

X-ray shielding is advisable to give protection against possible danger of personal injury arising from prolonged exposure at close range to this tube when operated above 16 kV.

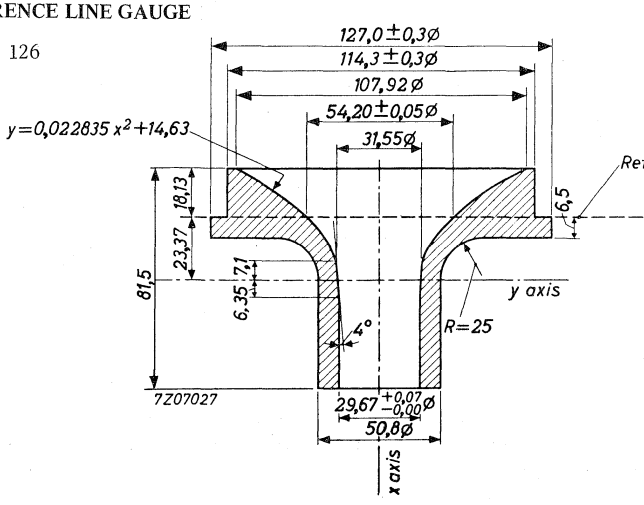
EXTERNAL CONDUCTIVE COATING

This tube has an external conductive coating (m), wich must be earthed and capacitance of this to the final electrode is used to provide smoothing for the EHT supply. The tube marking and warning labels are on the side of the cone opposite the final electrode connector and this side should not be used for making contact to the external conductive coating.

REFERENCE LINE GAUGE

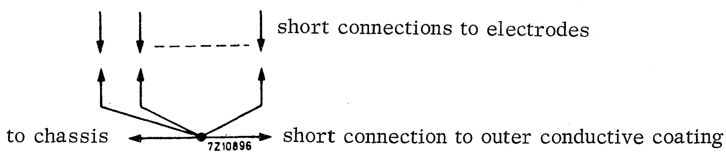
JEDEC 126

Dimensions in mm



REMARK

With the high voltage used with this tube internal flash -overs may occur. These may destroy the cathode of the tube. Therefore it is necessary to provide protective circuits, using spark gaps.
The spark gaps must be connected as follows:



No other connections between the outer conductive coating and the chassis are permissible.

On request the tube can be supplied with spark traps mounted in the base (ring trap base).

VERY HIGH RESOLUTION CATHODE-RAY TUBE

The M38-200 is a 38 cm, 70° data graphic display tube with a resolution of more than 6,6 line pairs per mm (corresponding to 3000 TV lines). Used in conjunction with deflection unit AT1991 it is eminently suitable for full page document display.
The resolution easily meets the stringent requirements of the CCITT recommendations for digital group III, high resolution facsimile transmission, and those of graphic displays for computer-aided design.

Tubes with white (WA) or green (GH) screen phosphors are standard; other phosphors are available to special order. The tubes have a metal-backed screen and rim band for implosion protection.

QUICK REFERENCE DATA

Deflection angle	70°
Face diagonal	38 cm
Overall length	478 mm
Neck diameter	36,8 mm
Screen dimensions	226 mm x 291 mm
Resolution	1728 x 2288 pixels*

* Pixel = picture element.

ELECTRICAL DATA

Capacitances		
cathode to all other electrodes	C_k	4 pF
grid 1 to all other electrodes	C_{g1}	12 pF
final accelerator to external conductive coating	$C_{g3,\,g5(l)/m}$	1100 pF
final accelerator to tension band	$C_{g3,\,g5(l)/m'}$	220 pF
Focusing method	electrostatic	
Deflection method	magnetic*	
Deflection angle	approx. 70°	
Heating	indirect by a.c. or d.c.	
heater voltage	V_f	6,3 V ± 5 %
heater current	I_f	190 mA**

OPTICAL DATA

Screen	metal-backed phosphor	
Phosphor type	GH	WA
fluorescent colour	green	white
persistence	medium short	medium
Screen dimensions	226 mm x 291 mm	
Minimum useful screen diagonal	352 mm	
Preferable useful scanning area	200 mm x 270 mm	
Reduction for A4 size (297 mm x 210 mm)	9%	
Reduction for 11″ x 8½″ size (279 mm x 216 mm)	7,4%	
Light transmission of screen	approx. 50%	

* To obtain the best tube performance, deflection unit AT1991 should be used.
** Liable to be modified into 240 mA.

MECHANICAL DATA (see also the figures on the following pages)

Overall length	478 ± 6,5 mm
Neck diameter	36,8 ± 0,8 mm
Base	JEDEC B12-246
Final accelerator contact	cavity contact, CT8; IEC 67-III-2
Mounting position	any
Implosion protection	rim band
Net mass	approx. 6 kg
Accessories	
socket	type 55589
final accelerator contact connector	type 55563A
deflection unit	type AT1991

DEVELOPMENT SAMPLE DATA

MECHANICAL DATA (continued)

Dimensions in mm

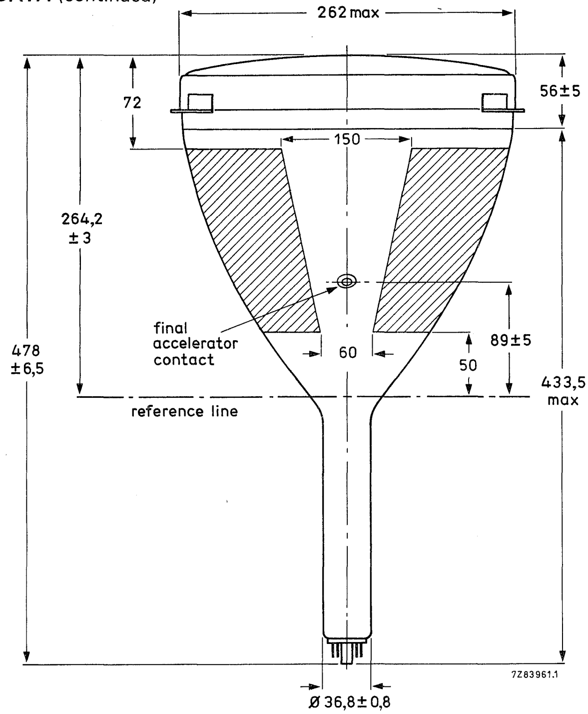


Fig. 1a.

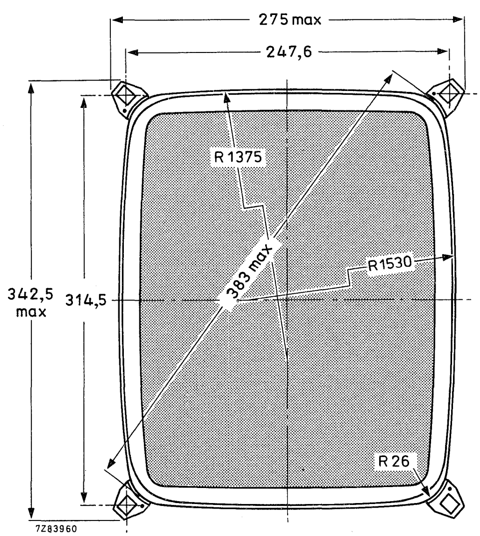


Fig. 1b.

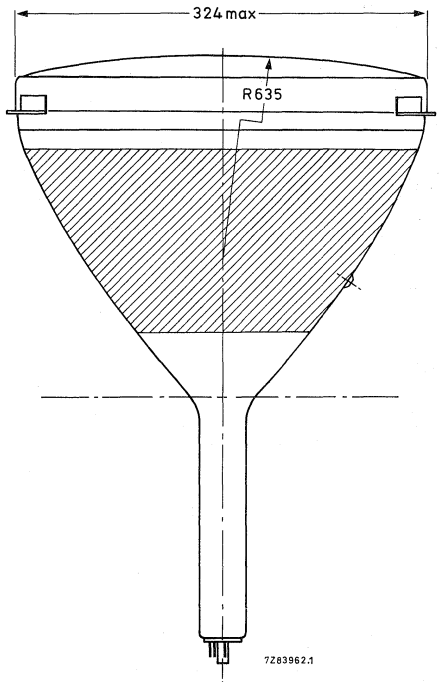


Fig. 1c.

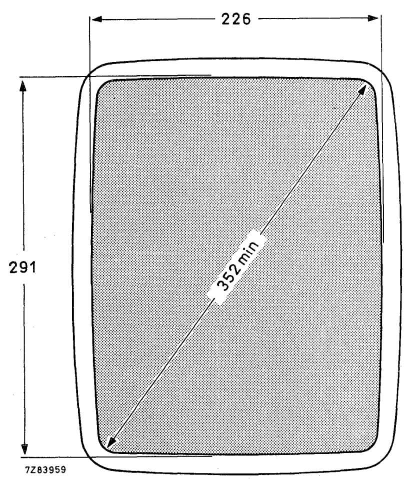


Fig. 2.

DEVELOPMENT SAMPLE DATA

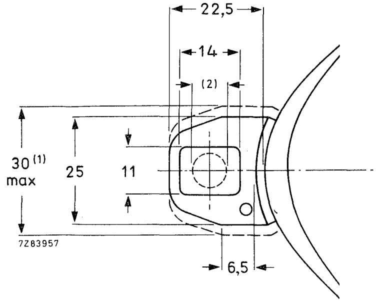


Fig. 3.

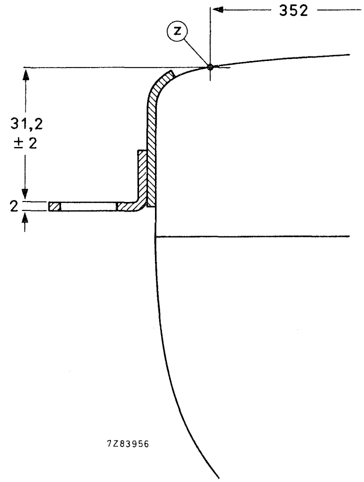


Fig. 4.

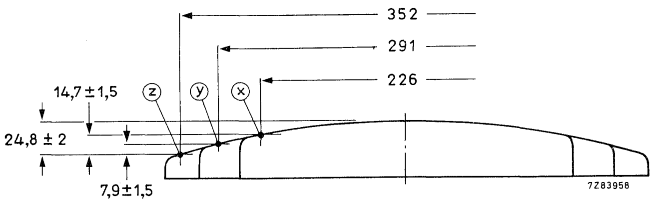


Fig. 5.

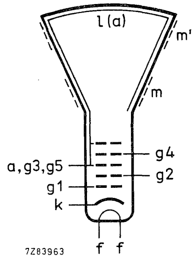


Fig. 6.

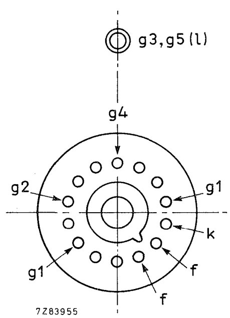


Fig. 7.

Notes

1. Minimum space to be reserved for mounting lugs.
2. The mounting screws in the cabinet must be situated within a circle with a diameter 7,5 mm drawn around the true geometrical positions (corners of a rectangle of 314,5 mm x 247,6 mm).

Reference line gauge, JEDEC 110

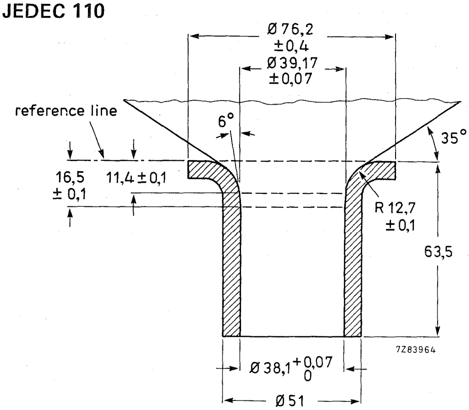


Fig. 8.

DEVELOPMENT SAMPLE DATA

RECOMMENDED OPERATING CONDITIONS; voltages with respect to cathode

Final accelerator voltage	$V_{g3,\,g5}$	18	kV
Focusing electrode voltage	V_{g4}	5 to 7	kV*
Dynamic focusing	ΔV_{g4}	200 to 300	V**
First accelerator voltage	V_{g2}	800	V
Cut-off voltage for visual extinction of focused spot	$-V_{g1}$	50 to 110	V
Grid drive for 30 μA screen current	V_d	approx. 20	V

RESOLUTION

With a beam current (I_a) of 30 μA, the spot diameter at a brightness level of 50% is approx. 120 μm (see Fig. 9).

CIRCUIT DESIGN VALUES

Grid 4 current				
positive	I_{g4}	max.	25	μA
negative	$-I_{g4}$	max.	25	μA
Grid 2 current				
positive	I_{g2}	max.	5	μA
negative	$-I_{g2}$	max.	5	μA

* For optimum focus at screen centre.

** To obtain optimum focus over the whole useful screen area, dynamic correction voltages should be applied in N-S and E-W directions; these voltages should be adjustable separately within the indicated range.

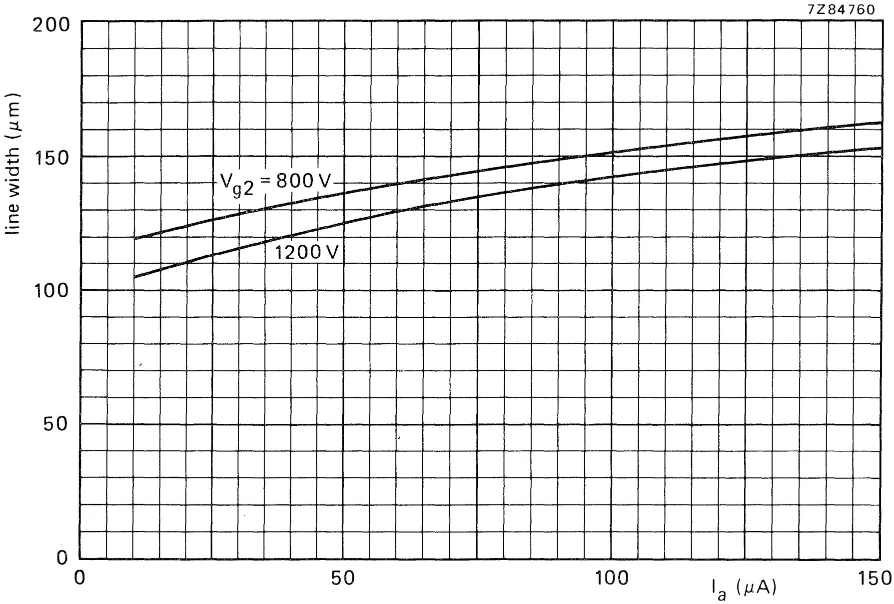

7Z84760
200
150
100
50
0
line width (μm)
V_{g2} = 800 V
1200 V
0
50
100
150
I_a (μA)

Fig. 9.

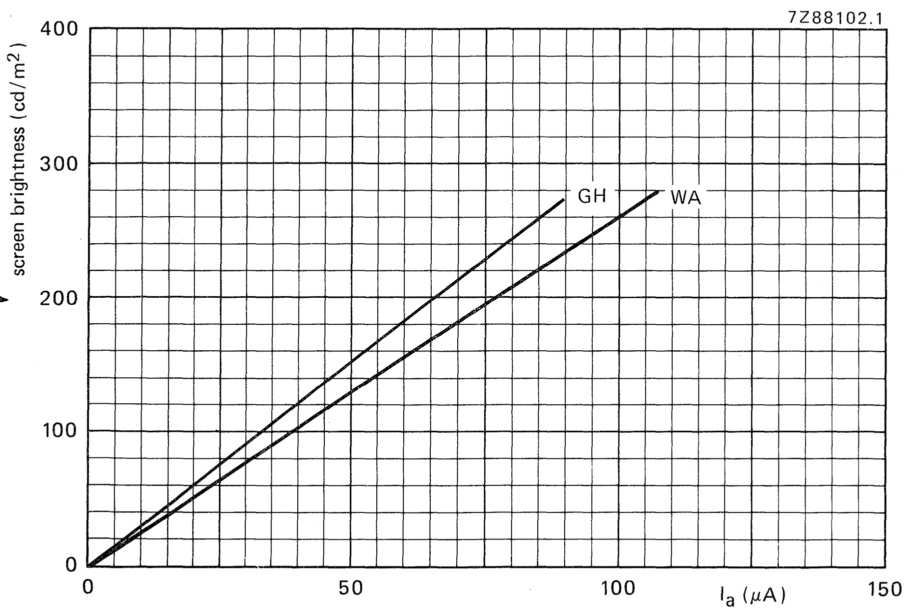

7Z88102.1
400
300
200
100
0
screen brightness (cd/m²)
GH
WA
0
50
100
150
I_a (μA)

Fig. 10.

LIMITING VALUES (Absolute maximum rating system)

Voltages are specified with respect to cathode unless otherwise stated.

Final accelerator voltage	$V_{g3,\ g5(\ell)}$	max.	20 kV
Focusing electrode voltage	V_{g4}	max.	8 kV
		min.	4 kV
First accelerator voltage	V_{g2}	max.	1,2 kV
Control grid voltage			
negative	$-V_{g1}$	max.	140 V
positive, non-repetitive	V_{g1}	max.	0 V
Cathode to heater voltage			
positive	V_{kf}	max.	250 V
positive peak	V_{kfp}	max.	300 V
negative	$-V_{kf}$	max.	135 V
negative peak	$-V_{kfp}$	max.	180 V

LIMITING CIRCUIT VALUES

Resistance between cathode and heater	R_{kf}	max.	1 MΩ
Impedance between cathode and heater (f = 50 Hz)	Z_{kf}	max.	500 kΩ
Grid 1 circuit resistance	R_{g1}	max.	1,5 MΩ
Impedance between cathode and earth	Z_k	max.	100 kΩ

X-RADIATION

Radiation emitted will not exceed 0,5 mR/h throughout the useful life of the tube when operated within the given ratings.

FLASHOVER PROTECTION

With the high voltage used with this tube internal flashovers may occur. These may destroy the cathode of the tube. Therefore it is necessary to provide protective circuits, using spark gaps. The spark gaps must be connected as follows:

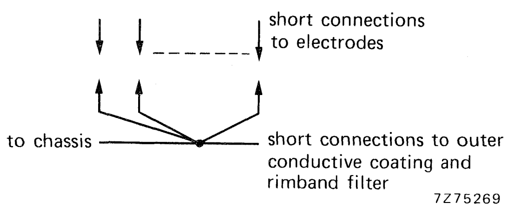


Fig. 11.

No other connections between the outer conductive coating and the chassis are permissible.

DEVELOPMENT SAMPLE DATA

CRTs FOR SPECIAL APPLICATIONS

PROJECTION TUBE

The M.13-38 is a 13 cm diameter projection tube designed for large screen projection of colour TV displays.

QUICK REFERENCE DATA			
Final accelerator voltage	$V_{g2(\ell)}$	50	kV
Deflection angle		47	deg
Focusing		magnetic	

SCREEN

Type	MG13-38	MU13-38	MY13-38
Colour	green	blue	red
Colour point	x = 0,19 y = 0,72	x = 0,17 y = 0,13	x = 0,66 y = 0,33

Useful screen area 92 x 69 mm^2

Luminance

MG13-38	2000	mcd/cm^2
MU13-38	290	mcd/cm^2
MY13-38	600	mcd/cm^2

measured at $V_{g2(\ell)}$ = 50 kV; I_ℓ = 500 µA, raster size 92 mm x 69 mm

HEATING

Indirect by a.c. or d.c.; parallel series supply

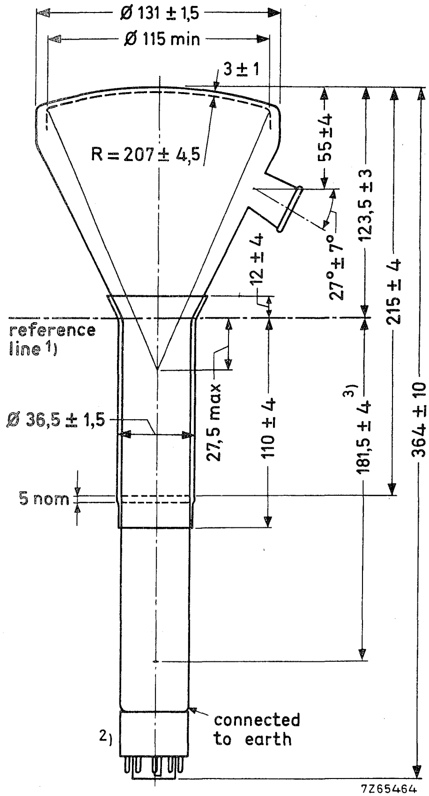
Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

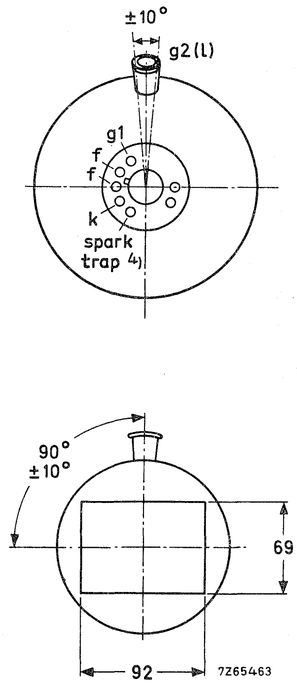
CAPACITANCES

Control grid to all other elements	C_{g1}	< 10	pF
Cathode to all other elements	C_k	< 9	pF

MECHANICAL DATA

Dimensions in mm





1) The reference line is determined by the position where a gauge 38, 1 $^{+0,05}_{-0,00}$ mm diameter and 50 mm long will rest on the cone of the envelope.

2) The socket for this base should not be rigidly mounted; it should have flexible leads and be allowed to move freely. The bottom circumreference of the base shell will fall within a circle with a diameter of 50 mm concentric with the cone axis.

3) Distance reference line to top-centre of grid.

4) This pin must be connected to earth.

MECHANICAL DATA (continued)

Mounting position: any, except screen downwards with the axis at an angle of less than 50° to the vertical.
The tube should not be supported by the base alone and under no condition should the socket be allowed to support the tube.

Base	Duodecal 7 p
Dimensions and connections	
Overall length	max. 374 mm
Face diameter	max. 132,5 mm
Net mass	approx. 950 g
Accessories	
Socket	type 5912/20
Final accelerator contact connector	supplied with tube*

FOCUSING magnetic

Distance from the centre of the air gap of the focusing coil to the front of the screen 240 mm

DEFLECTION double magnetic
deflection angle 47°

TYPICAL OPERATING CONDITIONS

Accelerator voltage	$V_{g2(\ell)}$		50	kV
Control grid voltage for visual extinction of a focused raster	V_{g1}		−100 to −170	V
Peak accelerator current	I_{g2_p}	min.	2500	μA

* If a tube is replaced, the final accelerator contact connector has also to be replaced.

LIMITING VALUES (Absolute max. rating system)

Measured with respect to cathode

Accelerator voltage	$V_{g2(\ell)}$	max.	55	kV	
		min.	40	kV	
Control grid voltage,					
negative	$-V_{g1}$	max.	200	V	
positive	V_{g1}	max.	0	V	
positive peak	V_{g1_p}	max.	0	V	
Accelerator current	$I_{g2(\ell)}$	max.	500	µA	1)
Cathode to heater voltage,					
cathode positive	V_{kf}	max.	100	V	2)
cathode negative	$-V_{kf}$	max.	50	V	
Resistance between heater and cathode	R_{kf}	max.	20	kΩ	
Resistance between grid no. 1 and earth	R_{g1}	max.	1,5	MΩ	
Impedance between grid no. 1 and earth (f = 50 Hz)	Z_{g1}	max.	0,5	MΩ	

1) To prevent the possible occurrence of cracked faces the accelerator should be kept lower than the indicated value for images with concentrated bright areas (high screen loads). This applies particulary for stationary pictures.

2) To avoid excessive hum, the A.C. component of the heater to cathode voltage should be as low as possible and must not exceed a r.m.s. value of 20 V.

GENERAL OBSERVATIONS

It is essential that means be provided for the instantaneous removal of the beam current if either one or both time-bases should fail. Unless such a safety device is incorporated, a failure of this type will immediately destroy the screen of the tube.

Shielding, equivalent to a lead thickness of 1 mm, is required to protect the observer against X-radiation.

The raster dimensions should not come below the minimum of 92 x 69 mm^2.

The screen shall be given adequate cooling by exposure to a continuous airblast of approx. 0,06 m^3/s.

To prevent damage to the tube caused by a momentary internal arc, a resistor of 50 kΩ must be connected between the anode contact and the power supply.

Before removing the tube, the screen and the cone should be discharged.

The spark trap and the outer coating of the tube must be connected to earth.

It is recommend to use the E.H.T. connector supplied with each tube.

It is necessary to centre the focusing coil for optimum sharpness.

PROJECTION TUBE

The MW13-38 is a 13 cm diameter projection tube designed for large screen projection of TV displays.

QUICK REFERENCE DATA			
Final accelerator voltage	$V_{g2(\ell)}$	50	kV
Deflection angle		47	deg
Focusing		magnetic	

SCREEN

Metal backed			
Colour		white	
Useful screen area		92 x 69	mm^2
Luminance		870	mcd/cm^2

measured at $V_{g2(\ell)}$ = 50 kV
I_ℓ = 500 µA
raster size 92 x 69 mm^2

HEATING

Indirect by a.c. or d.c.; parallel series supply

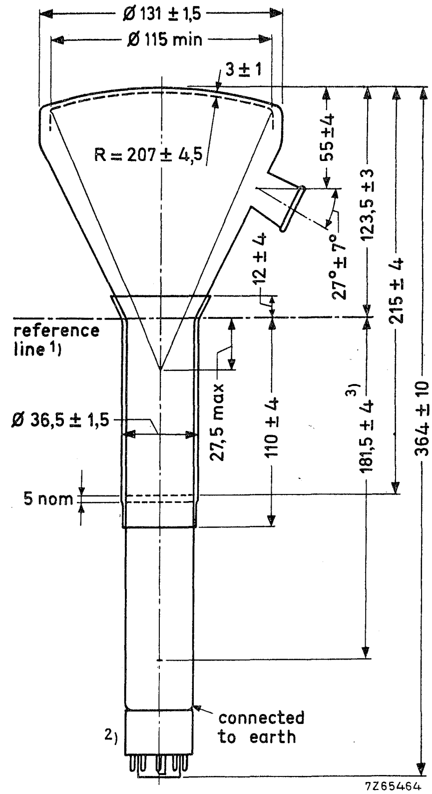
Heater voltage	V_f	6,3	V
Heater current	I_f	300	mA

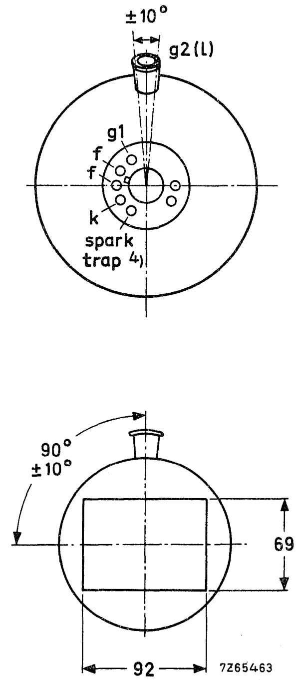
CAPACITANCES

Control grid to all other elements	C_{g1}	<	10	pF
Cathode to all other elements	C_k	<	9	pF

MECHANICAL DATA

Dimensions in mm





1) The reference line is determined by the position where a gauge $38,1\ ^{+0,05}_{-0,00}$ mm diameter and 50 mm long will rest on the cone of the envelope.

2) The socket for this base should not be rigidly mounted; it should have flexible leads and be allowed to move freely. The bottom circumreference of the base shell will fall within a circle with a diameter of 50 mm concentric with the cone axis.

3) Distance reference line to top-centre of grid.

4) This pin must be connected to earth.

MECHANICAL DATA (continued)

Mounting position: any, except with screen downwards with the axis at an angle of less than 50° to the vertical.
The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Base	Duodecal 7 p
Dimensions and connections	
Overall length	max. 374 mm
Face diameter	max. 132,5 mm
Net weight	approx. 950 g
Accessories	
Socket	type 5912/20
Final accelerator contact connector	supplied with tube*

FOCUSING magnetic

Distance from the centre of the air gap of the focusing coil to the front of the screen: 240 mm

DEFLECTION double magnetic

deflection angle 47°

TYPICAL OPERATING CONDITIONS

Accelerator voltage	$V_{g2(\ell)}$		50	kV
Control grid voltage for visual extinction of focused raster	V_{g1}	-100 to	-170	V
Peak accelerator current	$I_{g2(\ell)p}$	min.	2500	µA

*If a tube is replaced, the final accelerator contact connector has also to be replaced.

LIMITING VALUES (Absolute max. rating system)

Measured with respect to cathode

Accelerator voltage	$V_{g2(\ell)}$	max.	55	kV	
		min.	40	kV	
Control grid voltage,					
negative	$-V_{g1}$	max.	200	V	
positive	V_{g1}	max.	0	V	
positive peak	V_{g1_p}	max.	0	V	
Accelerator current	$I_{g2(\ell)}$	max.	500	μA	1)
Cathode to heater voltage,					
cathode positive	V_{kf}	max.	100	V	
cathode negative	$-V_{kf}$	max.	50	V	2)
Resistance between heater and cathode	R_{kf}	max.	20	kΩ	
Resistance between grid no. 1 and earth	R_{g1}	max.	1,5	MΩ	
Impedance between grid no. 1 and earth (f = 50 Hz)	Z_{g1}	max.	0,5	MΩ	

1) To prevent the possible occurrence of cracked faces, the accelerator current should be kept lower than the indicated value for images with concentrated bright areas (high screen loads). This applies particularly for stationary pictures.

2) To avoid excessive hum, the A.C. component of the heater to cathode voltage should be as low as possible and must not exceed a r.m.s. value of 20 V.

GENERAL OBSERVATIONS

It is essential that means be provided for the instantaneous removal of the beam current if either one or both time-bases should fail. Unless such a safety device is incorporated, a failure of this type will immediately destroy the screen of the tube.

Shielding, equivalent to a lead thickness of 1 mm, is required to protect the observer against X-radiation.

The raster dimensions should not come below the minimum of 92 x 69 mm^2.

The screen shall be given adequate cooling by exposure to a continuous airblast of approx. 0,06 m^3/s.

To prevent damage to the tube caused by a momentary internal arc, a resistor of 50 kΩ must be connected between the anode contact and the power supply.

Before removing the tube, the screen and the cone should be discharged.

The spark trap and the outer coating of the tube must be connected to earth.

It is recommend to use the E.H.T. connector supplied with each tube.

It is necessary to centre the focusing coil for optimum sharpness.

FLYING SPOT SCANNER TUBE

The Q13-110.. is a 13 cm diameter cathode-ray tube intended for flying spot applications.

QUICK REFERENCE DATA		
Accelerator voltage	25	kV
Deflection angle	40°	
Resolution	1000	lines

SCREEN

Metal backed

	Colour	Persistence
Q13-110BA	Purplish blue	Very short
Q13-110GU	White	Very short

Useful screen diameter min. 108 mm

HEATING

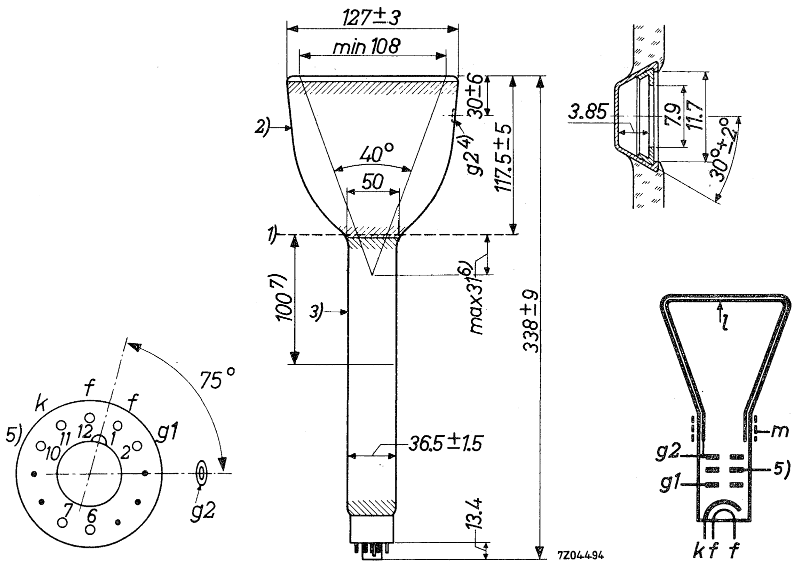
Indirect by A.C. or D.C.; series or parallel supply

Heater voltage	V_f	6.3	V
Heater current	I_f	300	mA

CAPACITANCES

Grid No.1 to all other electrodes	C_{g1}	6.5	pF
Cathode to all other electrodes	C_k	6.5	pF
Accelerator to outer conductive coating	$C_{g2(\ell)/m}$	250 to 450	pF

MECHANICAL DATA Dimensions in mm



Mounting position: any, except with screen downwards and the axis of the tube making an angle of less than 50° with the vertical.

Base Duodecal 7p.

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1) Reference line, determined by the plane of the upper edge of the reference line gauge when the gauge is resting on the cone.

2) Insulating outer coating; should not be in close proximity to any metal part.

3) Conductive outer coating; to be grounded.

4) Recessed cavity contact.

5) Spark trap; to be grounded.

6) The distance between the deflection centre and the reference line should not exceed 31 mm.

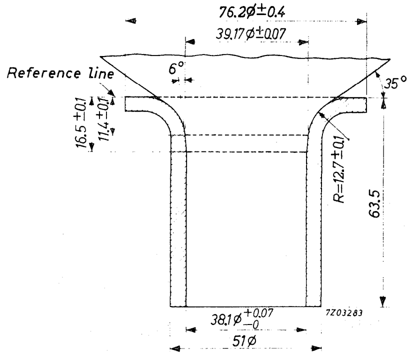
7) Distance between the centre of the magnetic length of the focusing unit and the reference line.

FOCUSING magnetic

DEFLECTION magnetic

REFERENCE LINE GAUGE

Dimensions in mmm



OPERATING CHARACTERISTICS

Accelerator voltage	$V_{g2(\ell)}$	25	kV
Beam current	I_ℓ	50 to 150	μA
Negative grid No. 1 cut-off voltage	$-V_{g1}(I_\ell=0)$	50 to 100	V

Resolution at centre of screen better than 1000 lines

LIMITING VALUES (Absolute max. rating system)

Accelerator voltage	$V_{g_2(\ell)}$	max.	27	kV
		min.	20	kV
Grid No.1 voltage,				
negative value	$-V_{g_1}$	max.	200	V
positive value	$+V_{g_1}$	max.	0	V
peak positive value	$+V_{g_{1p}}$	max.	2	V
Cathode current	I_k	max.	150	μA
Voltage between heater and cathode [1]				
cathode negative	V_{kf} (k neg.)	max.	125	V
cathode positive	V_{kf} (k pos.)	max.	200	V
peak value, cathode positive	V_{kf_p} (k pos.)	max.	410	V [2]
External resistance between heater and cathode	R_{kf}	max.	1	MΩ
External grid No.1 resistance	R_{g_1}	max.	1.5	MΩ
External grid No.1 impedance at a frequency of 50 Hz	Z_{g_1} (f = 50 Hz)	max.	0.5	MΩ

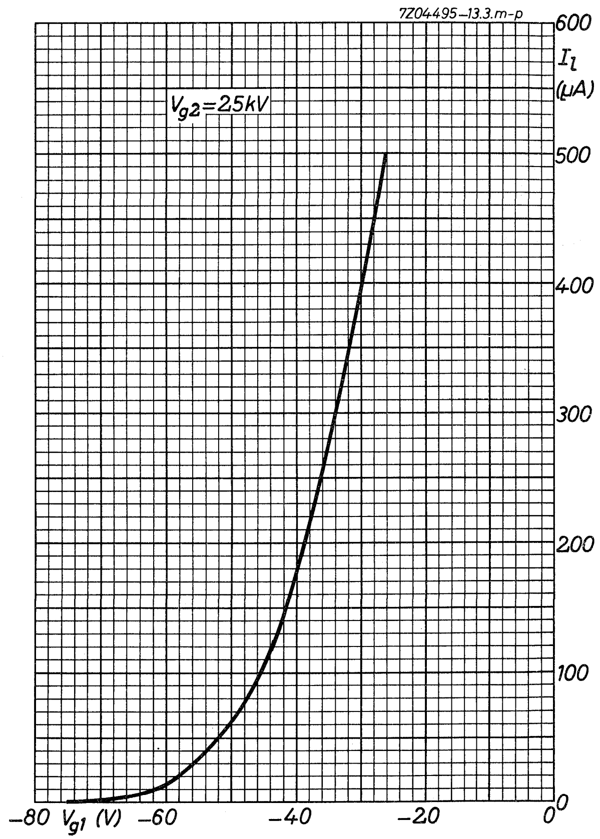
REMARKS

Measures should be taken for the beam current to be switched off immediately when one of the time-base circuits becomes defective.

An X-ray radiation shielding with an equivalent lead thickness of 0.5 mm is required to protect the observer.

[1] In order to avoid excessive hum, the A.C. component of the heater to cathode voltage should be as low as possible and should not exceed 20 V_{RMS}.

[2] During a heating-up period not exceeding 45 sec.


7Z04495-13.3.m-p
V_{g2}=25kV
600
I_l
(μA)
500
400
300
200
100
0
-80
V_{g1} (V)
-60
-40
-20
0

ACCESSORIES

replaces AT1038/40

DEFLECTION UNIT

- For Monochrome Data Graphic Displays

QUICK REFERENCE DATA

Monitor tube	
diagonal	31 cm (12 in), 38 cm (15 in)
neck diameter	28 mm
Deflection angle	110^o
Line deflection current, edge to edge at 17 kV	4,56 A (p-p)
Inductance of line coils, parallel connected	700 μH
Field deflection current, edge to edge at 17 kV	1,13 A (p-p)
Resistance of field coils, parallel connected	7,6 Ω

APPLICATION

This deflection unit has been designed for use with 31 cm (12 in) and 38 cm (15 in) 110^o monochrome monitor tubes in conjunction with:
line output transformer AT2102/04C or AT2102/06C;
linearity control unit AT4042/42 or AT4042/08;
line driver transformer AT4043/59.

DESCRIPTION

The saddle-shaped line deflection coils are moulded so that the deflection centre is well within the conical part of the monitor tube. The field deflection coils are wound on a Ferroxcube yoke ring which is flared so that the field and line deflection centres coincide. Provisions are made for centring, and correction of pin-cushion distortion. The unit meets the self-extinguishing and non-dripping requirements of IEC 65-14 and UL492.3, category 94-V1.

MOUNTING

The unit should be mounted as far forward as possible on the neck of the monitor tube, so that it touches the cone.

To orient the raster correctly, the unit may be rotated by hand on the neck of the monitor tube, with which it makes a slip fit. A screw-tightened clamping ring permits it to be locked, both axially and radially, in the desired position.

MECHANICAL DATA

Dimensions in mm

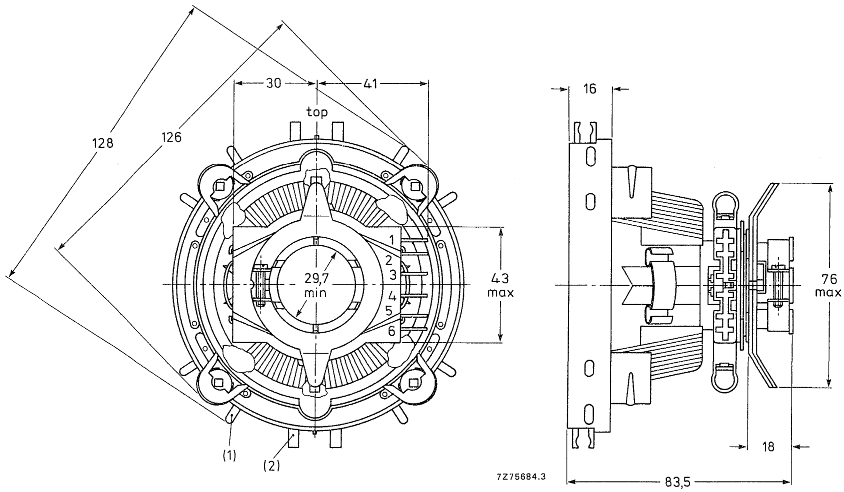


Fig. 1 Deflection unit AT1038/40A.
(1) for plastic-bonded FXD magnets 3122 104 94120.
(2) for plastic-bonded FXD magnet rods 3122 104 90360.

ELECTRICAL DATA

The electrical values apply at an ambient temperature of 25 °C.

Line deflection coils, parallel connected (Fig. 2a); terminals 3 and 4	
Inductance	700 μH ± 4,5%
Resistance	1,1 Ω ± 8%
Field deflection coils, parallel or series connected (Fig. 2b); terminals 1 and 2 for parallel connected coils (terminals 1 and 6, and 2 and 5 to be interconnected); terminals 2 and 6 for series connected coils (terminals 1 and 5 to be interconnected)	
Inductance (parallel connected coils)	14,1 mH ± 8%
Inductance (series connected coils)	56,4 mH ± 8%
Resistance (parallel connected coils)	7,6 Ω ± 8%
Resistance (series connected coils)	30,4 Ω ± 8%
Maximum d.c. voltage between line and field coils	2500 V
Maximum operating temperature	95 °C

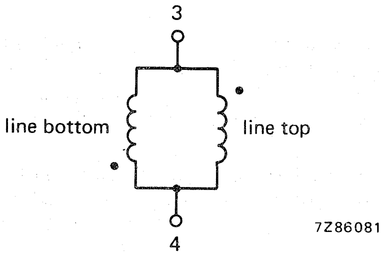


Fig. 2a Line coils.

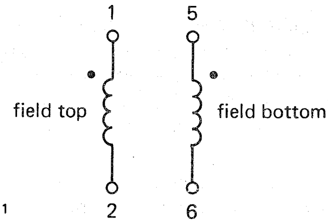


Fig. 2b Field coils.

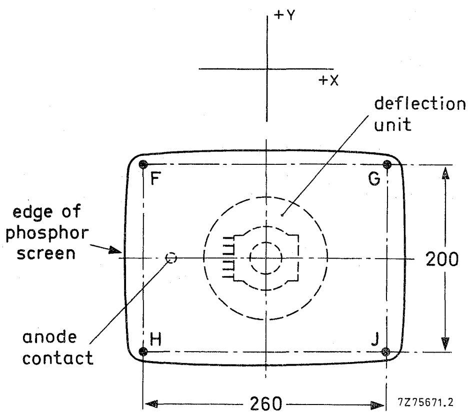
The beginning of the windings is indicated with ●.

The following characteristics are measured at an e.h.t. of 17 kV on a 38 cm (15 in) reference tube.

Sensitivity

Deflection current edge to edge	
in line direction	4,56 A (p-p)
in field direction	1,13 A (p-p)

Geometric distortion measured without correction magnets on a 38 cm (15 in) reference tube.



Fy : $+4^{+2\frac{1}{4}}_{-2\frac{1}{4}}$	Fx : $-4^{-2\frac{1}{4}}_{+2\frac{1}{4}}$
Gy : $+4^{+2\frac{1}{4}}_{-2\frac{1}{4}}$	Gx : $+4^{+2\frac{1}{4}}_{-2\frac{1}{4}}$
Jy : $+4^{-2\frac{1}{4}}_{+2\frac{1}{4}}$	Jx : $+4^{+2\frac{1}{4}}_{-2\frac{1}{4}}$
Hy : $+4^{-2\frac{1}{4}}_{+2\frac{1}{4}}$	Hx : $-4^{-2\frac{1}{4}}_{+2\frac{1}{4}}$

Fig. 3.

CORRECTION FACILITIES

For centring

After adjustment of the linearity of the deflection current, the eccentricity of the monitor tube and the deflection unit can be corrected by means of two independently movable centring magnets of plastic-bonded Ferroxdure. These magnets are magnetized diametrically. By turning the magnets with respect to each other the resulting field strength is varied. The direction of the resulting magnetic field is adjusted by turning the magnets simultaneously.

These centring magnets cannot be used for compensating the effects of non-linearity or of phase differences between the synchronization and time base, as otherwise the correction needed becomes excessive. Even if the correction is within the range of the magnets, curved lines may appear in the centre of the raster.

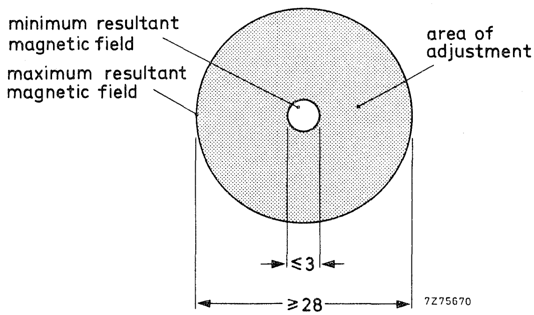


Fig. 4.

For pin-cushion distortion

Pin-cushion distortion can be corrected by four Ferroxdure magnets with pole-shoe brackets, which have been mounted on the deflection unit. Limited correction of asymmetrical pin-cushion distortion can be achieved by unequal movement of these magnets. The field strength can be adjusted by rotation of these magnets.

To correct the top and bottom of the raster, two plastic-bonded Ferroxdure magnet rods* can be fitted (Fig. 1). To correct the corners of the raster, four plastic-bonded Ferroxdure magnets** can be fitted (Fig. 1).

* Available under catalogue number 3122 104 90360.
** Available under catalogue number 3122 104 94120.

DEFLECTION UNIT

QUICK REFERENCE DATA

Monitor tube	
diagonal	24 cm (9 in), 31 cm (12 in)
neck diameter	20 mm*, 28 mm
Deflection angle	90°
Line deflection current, edge to edge at 16 kV	9,3 A (p-p)
Inductance of line coils, parallel connected	93 μH
Field deflection current, edge to edge at 16 kV	0,91 A (p-p)
Resistance of field coils, parallel connected	6,75 Ω

APPLICATION

This deflection unit has been designed for use with 24 cm (9 in) or 31 cm (12 in) 90° monochrome monitor tubes in conjunction with:

line output transformer AT2102/02;
linearity control unit AT4036;
line driver transformer AT4043/56.

DESCRIPTION

The saddle-shaped line deflection coils are moulded so that the deflection centre is well within the conical part of the monitor tube. The field deflection coils are wound on a Ferroxcube yoke ring which is flared so that the frame and line deflection centres coincide. Provisions are made for centring, and correction of pin-cushion distortion. The unit meets the self-extinguishing and non-dripping requirements of IEC 65.

MOUNTING

The unit should be mounted as far forward as possible on the neck of the monitor tube, so that it touches the cone.

To orient the raster correctly, the unit may be rotated by hand on the neck of the monitor tube, with which it makes a slip fit. A screw-tightened clamping ring permits it to be locked, both axially and radially, in the desired position.

Note: Use of the deflection unit with a monitor tube with a neck diameter of 20 mm requires the use of a packing piece, catalogue number 3122 134 07820.

* Packing piece required, see Mounting.

MECHANICAL DATA

Dimensions in mm

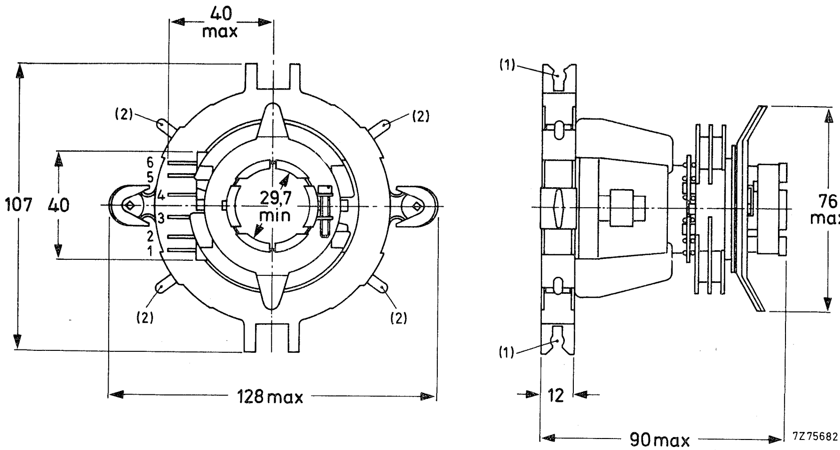


Fig. 1 Deflection unit AT1071/03. Facilities for fitting correction magnets:
(1) for plastic-bonded FXD magnet rods, catalogue number 3122 104 90360;
(2) for plastic-bonded FXD magnets, catalogue number 3122 104 94120.

The unit is provided with solder pins for connection. The pin numbering in Fig. 1 corresponds to that in the connection diagram (Figs 2a and 2b).

ELECTRICAL DATA

Line deflection coils, parallel connected (Fig. 2a); terminals 3 and 4	
Inductance	93 μH
Resistance	0,15 Ω
Field deflection coils, parallel or series connected (Fig. 2b); terminals 1 and 2 for parallel connected coils (terminals 1 and 6, and 2 and 5 to be interconnected); terminals 2 and 6 for series connected coils (terminals 1 and 5 to be interconnected)	
Inductance (parallel connected coils)	14 mH
Inductance (series connected coils)	56 mH
Resistance (parallel connected coils)	6,75 Ω
Resistance (series connected coils)	27 Ω
Maximum d.c. voltage between terminals of line and field coils	2000 V
Maximum operating temperature	95 ^{o}C

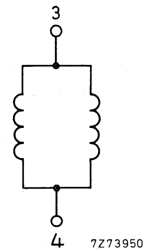


Fig. 2a Line coils.

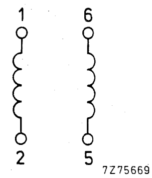


Fig. 2b Field coils.

The following characteristics are measured at an e.h.t. of 16 kV on a 24 cm (9 in) reference tube.

Sensitivity

Deflection current edge to edge	
in line direction	9,3 A (p-p)
in field direction	0,91 A (p-p)

Geometric distortion measured without correction magnets on a 24 cm (9 in) reference tube.

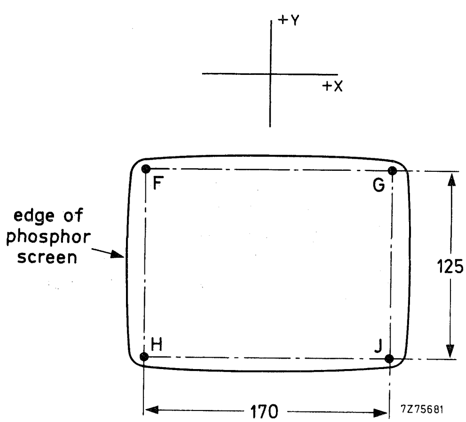


Fig. 3.

Fy	: $+1{,}75\,^{+1{,}25}_{-1{,}25}$	Fx	: $-1{,}25\,^{-1{,}25}_{+1{,}25}$
Gy	: $+1{,}75\,^{+1{,}25}_{-1{,}25}$	Gx	: $+1{,}25\,^{+1{,}25}_{-1{,}25}$
Jy	: $-1{,}75\,^{-1{,}25}_{+1{,}25}$	Jx	: $+1{,}25\,^{+1{,}25}_{-1{,}25}$
Hy	: $-1{,}75\,^{-1{,}25}_{+1{,}25}$	Hx	: $-1{,}25\,^{-1{,}25}_{+1{,}25}$

CORRECTION FACILITIES

For centring

After adjustment of the linearity of the deflection current, the eccentricity of the monitor tube and the deflection unit can be corrected by means of two independently movable centring magnets of plastic-bonded Ferroxdure. These magnets are magnetized diametrically. By turning the magnets with respect to each other the resulting field strength is varied. The direction of the resulting magnetic field is adjusted by turning the magnets simultaneously.

These centring magnets cannot be used for compensating the effects of non-linearity or of phase differences between the synchronization and time base, as otherwise the correction needed becomes excessive. Even if the correction is within the range of the magnets, curved lines may appear in the centre of the raster.

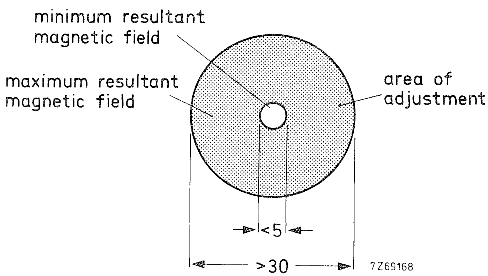


Fig. 4.

For pin-cushion distortion

Pin-cushion distortion can be corrected by two Ferroxdure magnets with pole-shoe brackets, which have been mounted on the deflection unit. Limited correction of asymmetrical pin-cushion distortion can be achieved by unequal movement of these magnets. The field strength can be adjusted by rotation of these magnets. To correct the top and bottom of the raster, two plastic-bonded Ferroxdure magnet rods* can be fitted (Fig. 1). To correct the corners of the raster, four plastic-bonded Ferroxdure magnets** (Fig. 1) can be fitted.

* Available under catalogue number 3122 104 90360.
** Available under catalogue number 3122 104 94120.

DEFLECTION UNIT

QUICK REFERENCE DATA

Monitor tube	
diagonal	17 cm (7 in)
neck diameter	28 mm
Deflection angle	70°
Line deflection current, edge to edge at 16 kV	6,7 A (p-p)
Inductance of line coils, parallel connected	87 μH
Field deflection current, edge to edge at 16 kV	0,84 A (p-p)
Resistance of field coils, parallel connected	4,2 Ω

APPLICATION

This deflection unit has been designed for use with 17 cm (7 in) 70° monochrome monitor tubes in conjunction with:

line output transformer AT2102/02;
linearity control unit AT4036;
line driver transformer AT4043/56.

DESCRIPTION

The saddle-shaped line deflection coils are moulded so that the deflection centre is well within the conical part of the monitor tube. The field deflection coils are wound on a Ferroxcube yoke ring which is flared so that the frame and line deflection centres coincide. Provisions are made for centring, and correction of pin-cushion distortion. The unit meets the self-extinguishing and non-dripping requirements of IEC 65.

MOUNTING

The unit should be mounted as far forward as possible on the neck of the monitor tube, so that it touches the cone.

To orient the raster correctly, the unit may be rotated by hand on the neck of the monitor tube, with which it makes a slip fit. A screw-tightened clamping ring permits it to be locked, both axially and radially, in the desired position.

MECHANICAL DATA

Dimensions in mm

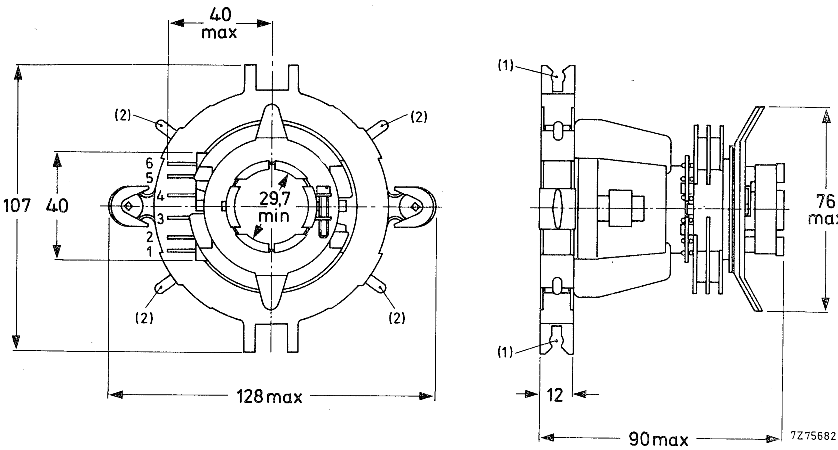


Fig. 1 Deflection unit AT1071/07. Facilities for fitting correction magnets:
(1) for plastic-bonded FXD magnet rods catalogue number 3122 104 90360;
(2) for plastic-bonded FXD magnets, catalogue number 3122 104 94120.

The unit is provided with solder pins for connection. The pin numbering in Fig. 1 corresponds to that in the connection diagram (Figs 2a and 2b).

ELECTRICAL DATA

Line deflection coils, parallel connected (Fig. 2a); terminals 3 and 4	
Inductance	87 μH
Resistance	0,14 Ω
Field deflection coils, parallel or series connected (Fig. 2b); terminals 1 and 2 for parallel connected coils (terminals 1 and 6, and 2 and 5 to be interconnected); terminals 2 and 6 for series connected coils (terminals 1 and 5 to be interconnected)	
Inductance (parallel connected coils)	10,4 mH
Inductance (series connected coils)	41,6 mH
Resistance (parallel connected coils)	4,2 Ω
Resistance (series connected coils)	16,8 Ω
Maximum d.c. voltage between terminals of line and field coils	2000 V
Maximum operating temperature	95 °C

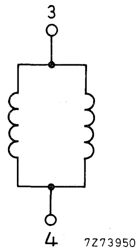


Fig. 2a Line coils.

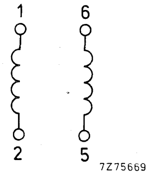


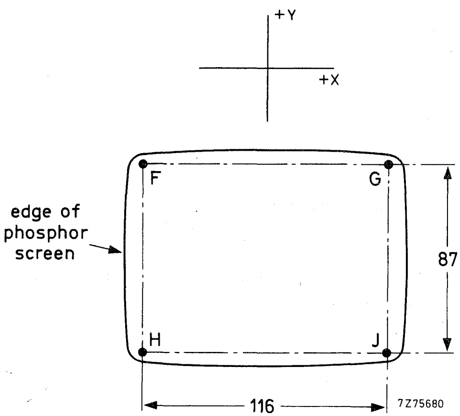
Fig. 2b Field coils.

The following characteristics are measured at an e.h.t. of 16 kV on a 17 cm (7 in) 70° reference tube.

Sensitivity

Deflection current edge to edge	
in line direction	6,7 A (p-p)
in field direction	0,84 A (p-p)

Geometric distortion measured without correction magnets on a 17 cm (7 in) 70° reference tube.



Fy	: $+0{,}75\,^{+2}_{-2}$	Fx	: $+0{,}5\,^{+1{,}5}_{-1{,}5}$
Gy	: $+0{,}75\,^{+2}_{-2}$	Gx	: $-0{,}5\,^{-1{,}5}_{+1{,}5}$
Jy	: $-0{,}75\,^{-2}_{+2}$	Jx	: $-0{,}5\,^{-1{,}5}_{+1{,}5}$
Hy	: $-0{,}75\,^{-2}_{+2}$	Hx	: $+0{,}5\,^{+1{,}5}_{-1{,}5}$

Fig. 3.

CORRECTION FACILITIES

For centring

After adjustment of the linearity of the deflection current, the eccentricity of the monitor tube and the deflection unit can be corrected by means of two independently movable centring magnets of plastic-bonded Ferroxdure. These magnets are magnetized diametrically. By turning the magnets with respect to each other the resulting field strength is varied. The direction of the resulting magnetic field is adjusted by turning the magnets simultaneously.

These centring magnets cannot be used for compensating the effects of non-linearity or of phase differences between the synchronization and time base, as otherwise the correction needed becomes excessive. Even if the correction is within the range of the magnets, curved lines may appear in the centre of the raster.

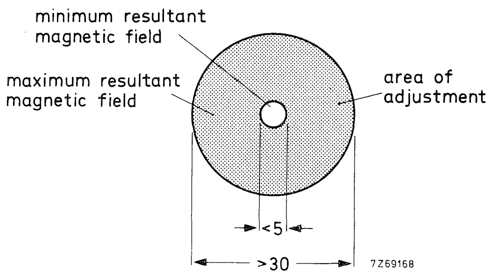


Fig. 4.

For pin-cushion distortion

Pin-cushion distortion can be corrected by two Ferroxdure magnets with pole-shoe brackets, which have been mounted on the deflection unit. Limited correction of asymmetrical pin-cushion distortion can be achieved by unequal movement of these magnets. The field strength can be adjusted by rotation of these magnets. To correct the top and bottom of the raster, two plastic-bonded Ferroxdure magnet rods* can be fitted (Fig. 1). To correct the corners of the raster, four plastic-bonded Ferroxdure magnets** (Fig. 1) can be fitted.

* Available under catalogue number 3122 104 90360.
** Available under catalogue number 3122 104 94120.

DEFLECTION UNIT

- For use with very high resolution c.r.t. M38-200.

QUICK REFERENCE DATA

Associated c.r.t.	
diagonal	38 cm (15 in)
neck diameter	36,8 mm
Deflection angle	70°
Line deflection current, edge to edge, at 18 kV	4,03 A
Inductance of line coils, parallel connected	136,5 μH
Field deflection current, edge to edge, at 18 kV	474 mA
Resistance of field coils, series connected	23,5 Ω

APPLICATION

This deflection unit is for use with 38 cm, 70° cathode ray tube M38-200, neck diameter 36,8 mm.

DESCRIPTION

The saddle-shaped line and field deflection coils are surrounded by a Ferroxcube yoke ring in such a way that the line and field deflection centres coincide. Provisions are made for centring correction, and astigmatism correction of the spot at the screen centre. The field coils have internal damping resistors. The unit has a non-magnetic metal clamping ring for fixing to the tube neck.

The deflection unit meets the self-extinguishing requirements of UL.

MECHANICAL DATA

Dimensions in mm

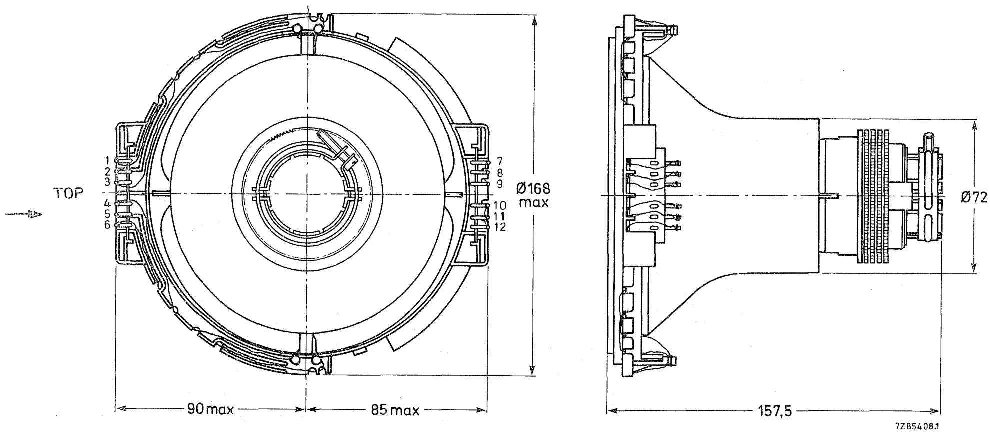


Fig. 1.

Tightening torque on clamping ring	0,6 to 0,9 Nm
Torque on centring magnets	35 to 250 mNm

Mounting

The unit should be mounted as far forward as possible on the neck of the tube, so that it touches the cone.

The tube/coil combination is optimized for use in "portrait" scan mode, with line scan frequency up to 125 kHz; H.T. contact and top of the deflection unit upwards.

To orient the raster correctly, the unit may be manually rotated around the neck. The screw-tightened clamping ring permits it to be locked, both axially and radially, in the desired position.

ENVIRONMENTAL DATA

Maximum operating temperature (average copper temperature)	95 °C
Storage temperature range	−25 to + 90 °C
Flame retardant	according to UL94, category V-1
Flammability	according to UL94, category V-1

ELECTRICAL DATA

Line deflection coils, parallel connected; terminals 3 and 4, and terminals 9 and 10 interconnected (Fig. 2)

inductance	136,5 μH ± 4,5%
resistance	0,27 Ω
Line deflection current, edge to edge, at 18 kV	4,03 A

Field deflection coils, series connected; terminals 1 and 5 interconnected (Fig. 2)

inductance	23 mH
resistance	23,5 Ω ± 8%
Field deflection current, edge to edge, at 18 kV	474 mA ± 3,5%
Maximum voltage between line and field coils	2500 V (d.c.)

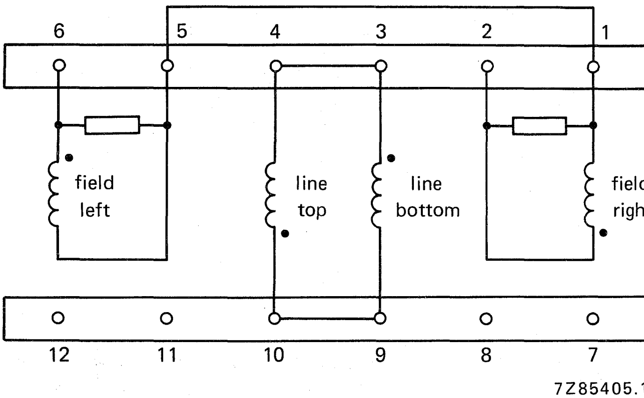
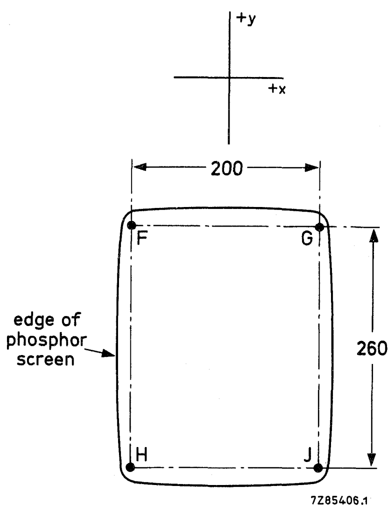


Fig. 2 Diagram of the coils. The beginning of the windings are indicated with ●.

Geometric distortion measured without centring magnets.



$Fy: +1,0^{+1,0}_{-1,0}$ $Fx: -1,0^{+1,0}_{-1,0}$

$Gy: +1.0^{+1,0}_{-1,0}$ $Gx: +1,0^{+1,0}_{-1,0}$

$Jy: -1.0^{+1,0}_{-1,0}$ $Jx: +1,0^{+1,0}_{-1,0}$

$Hy: -1,0^{+1,0}_{-1,0}$ $Hx: -1,0^{+1,0}_{-1,0}$

Fig. 3.

DEVELOPMENT SAMPLE DATA

CENTRING CORRECTION

The eccentricity of the c.r.t. and the deflection unit can be corrected by two independently movable centring magnets, which are magnetized diametrically. By turning the magnets with respect to each other the resulting field strength is varied. The direction of the resulting magnetic field is adjusted by turning the magnets simultaneously. The magnets must be adjusted so that the curvature of the horizontal and vertical axes disappears; in general the picture will be centred at the same time, otherwise this should be corrected electronically.

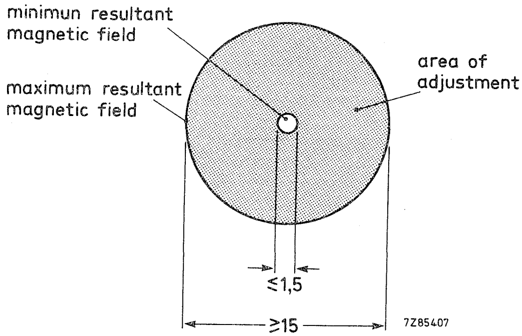


Fig. 4.

ASTIGMATISM CORRECTION

The astigmatism of the undeflected beam can be corrected by two independently movable quadripole magnets, which are placed next to the centring magnets. By turning the quadripole magnets with respect to each other the resulting four-pole field strength varies. The direction of the resulting four-pole field is adjusted by turning the quadripole magnets simultaneously. The astigmatism of the undeflected beam is examined during a slow variation of the focusing voltage; the beam is free of astigmatism when the size, and not the shape, of the beam changes when the focusing voltage is varied around its optimum (Figs 5 and 6).

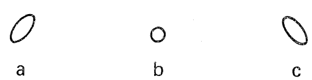


Fig. 5 Beam with astigmatism.

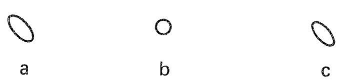
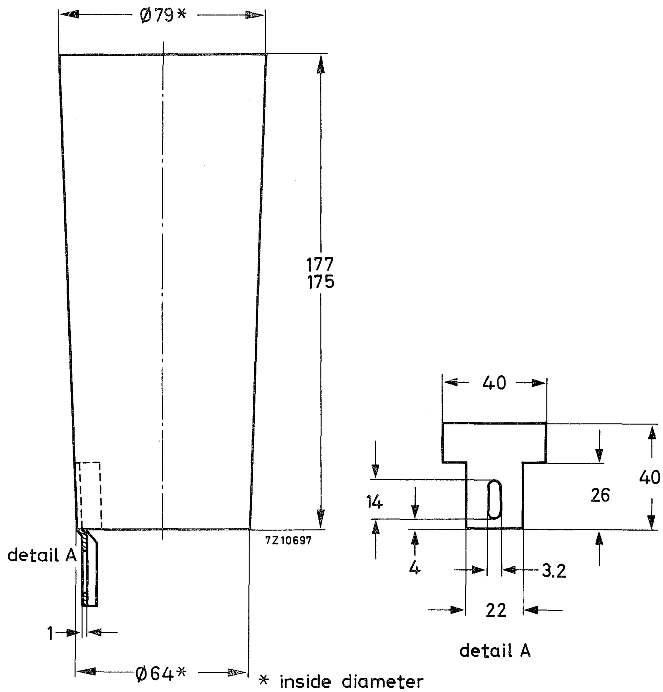


Fig. 6 Beam free of astigmatism.

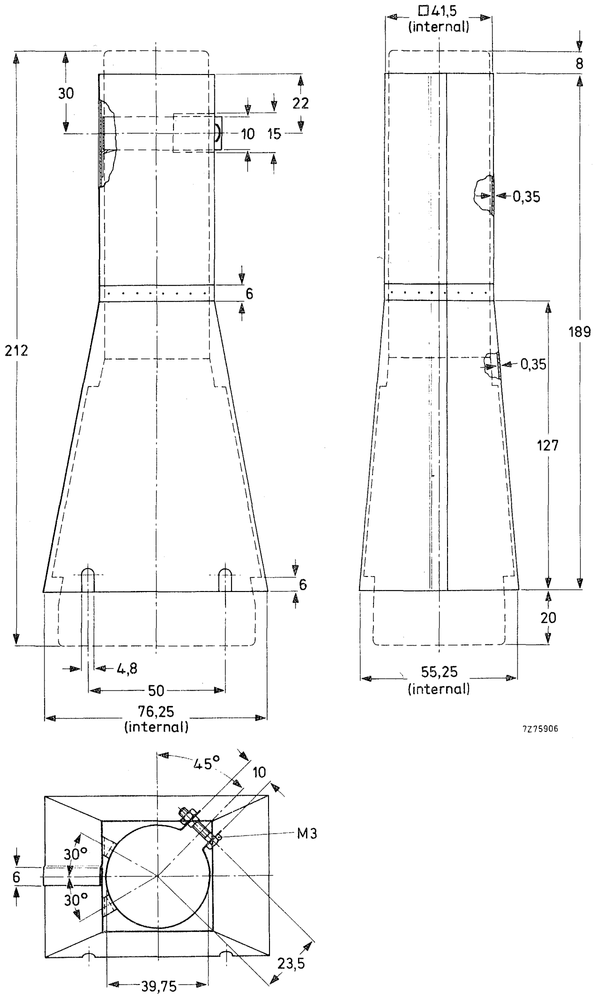
a. Focusing voltage < optimum value.
b. Focusing voltage at optimum value.
c. Focusing voltage > optimum value.

MU-METAL SCREEN

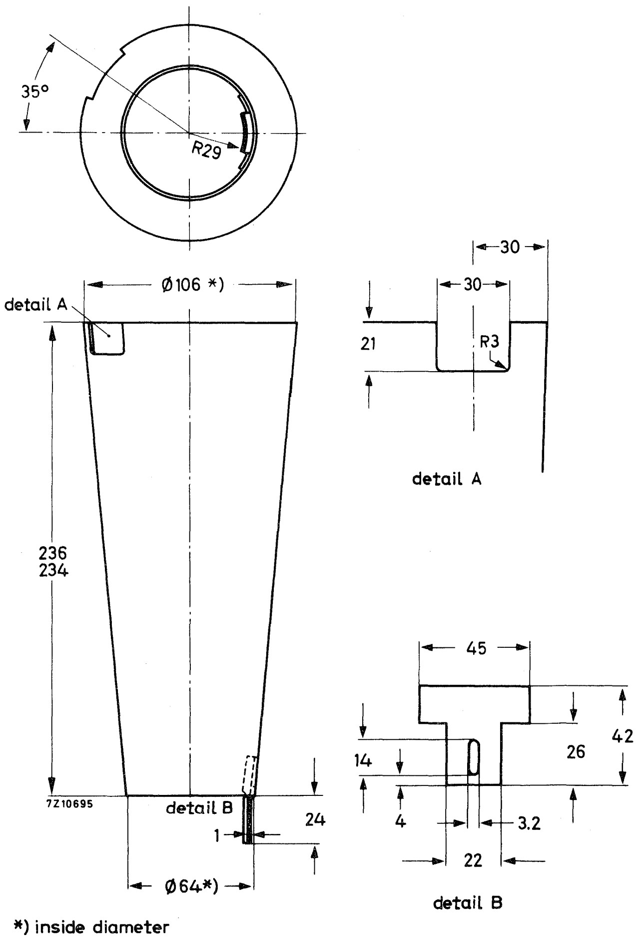


Material: Mu-metal 0,35 mm thick

MU-METAL SCREEN

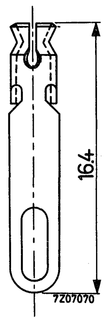


MU–METAL SCREEN



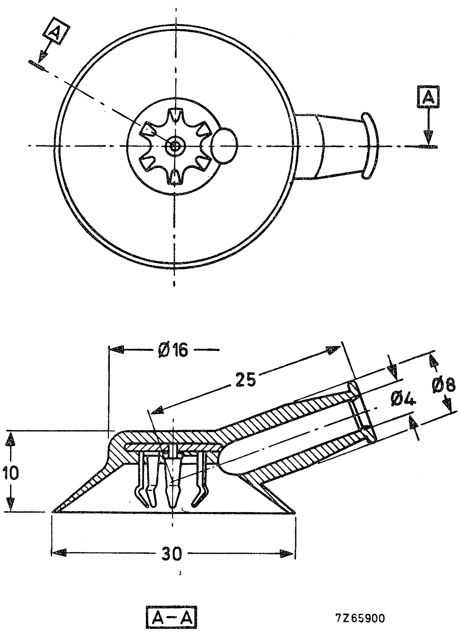
Material: Mu-metal, 0.35 mm thick

SIDE CONTACT CONNECTOR

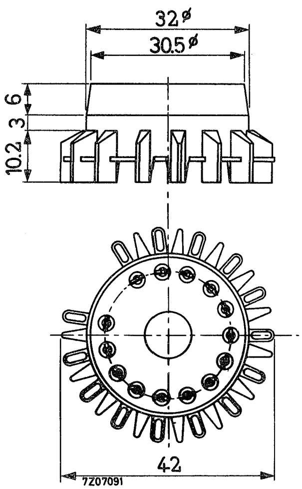


FINAL ACCELERATOR CONTACT CONNECTOR

Type 55563A supersedes type 55563.



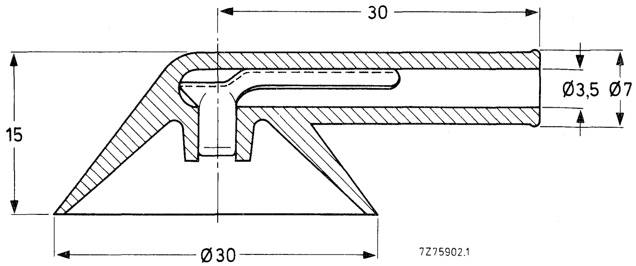
TUBE SOCKET FOR 14-PIN BASES



Material: synthetic resin insulating material

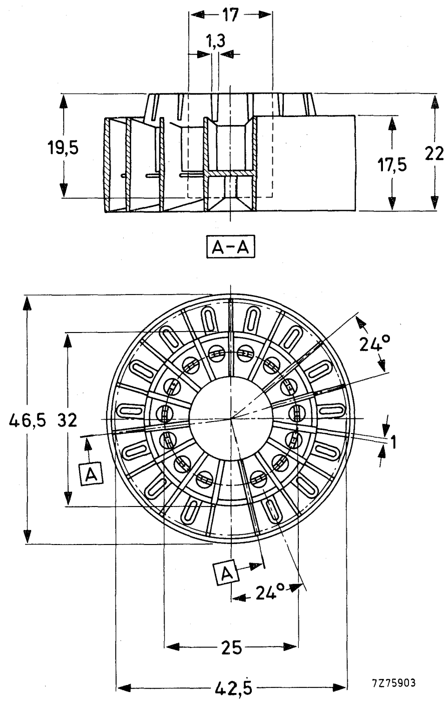
14 gold plated fork shaped contacts

FINAL ACCELERATOR CONTACT CONNECTOR



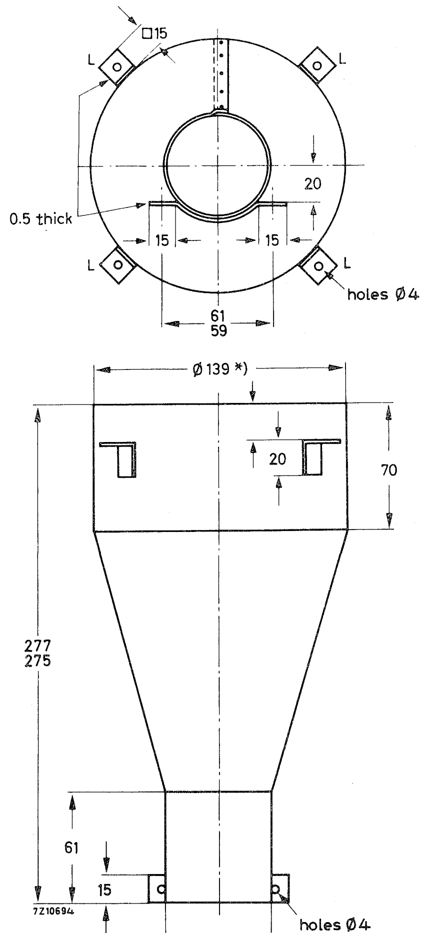
Insulating material: silicon rubber.

TUBE SOCKET



MU-METAL SCREEN

Type 55580A with 4 mounting lugs L
Type 55580 without mounting lugs L



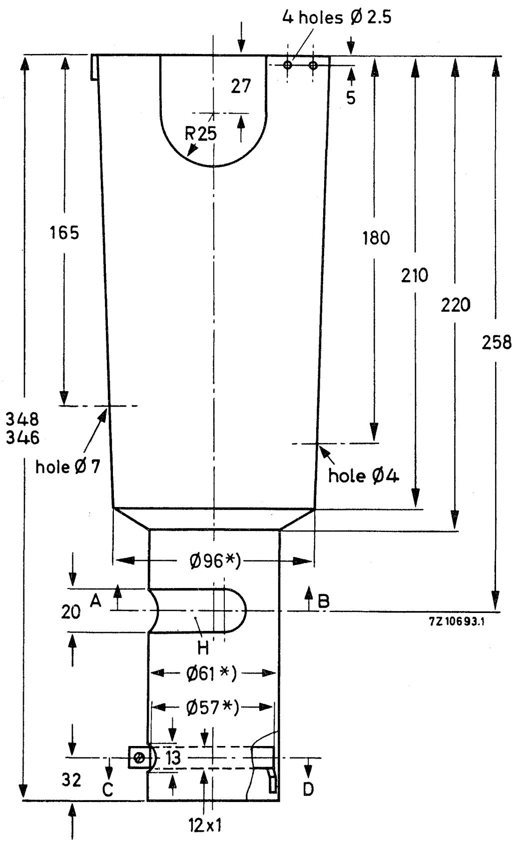
*) inside diameter

Material: Mu-metal, 0.35 mm thick

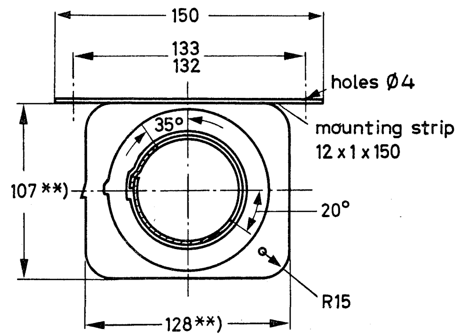
MU-METAL SCREEN

Type 55581A with hole H

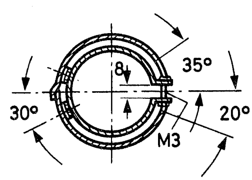
Type 55581 without hole H



*) inside diameter



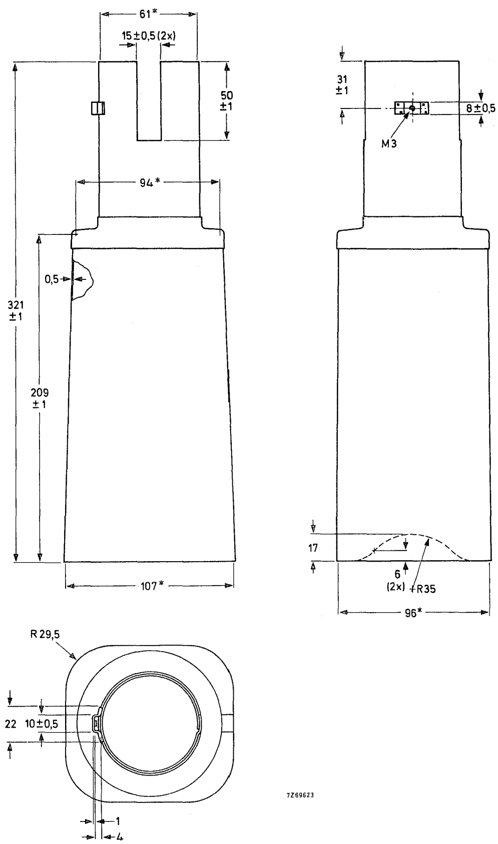
**) inside A– B



C–D

Material: Mu-metal, 0,5 mm thick.

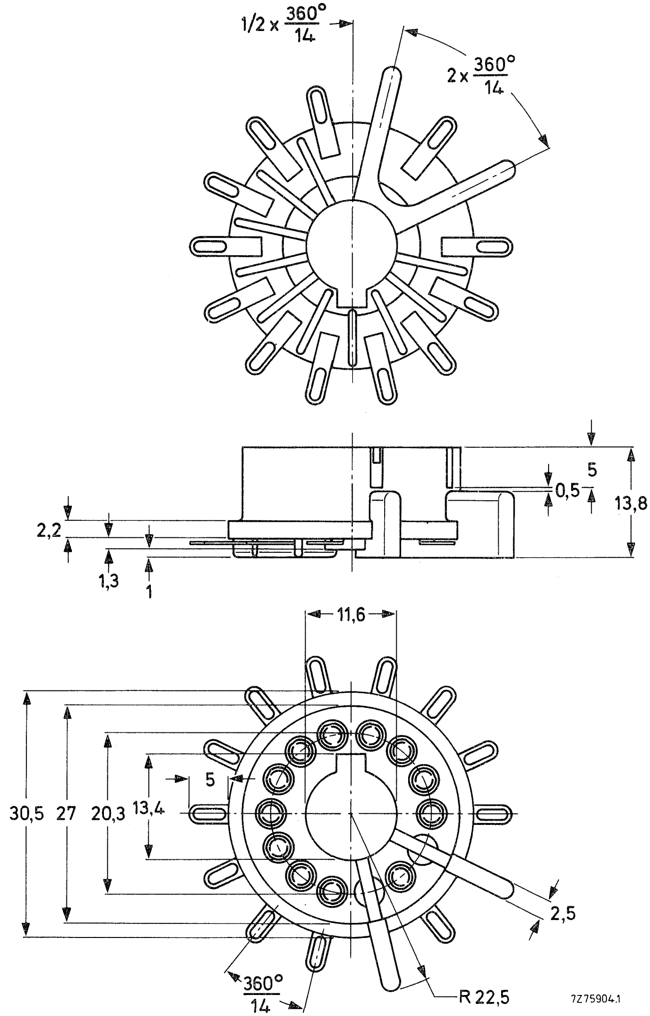
MU-METAL SCREEN



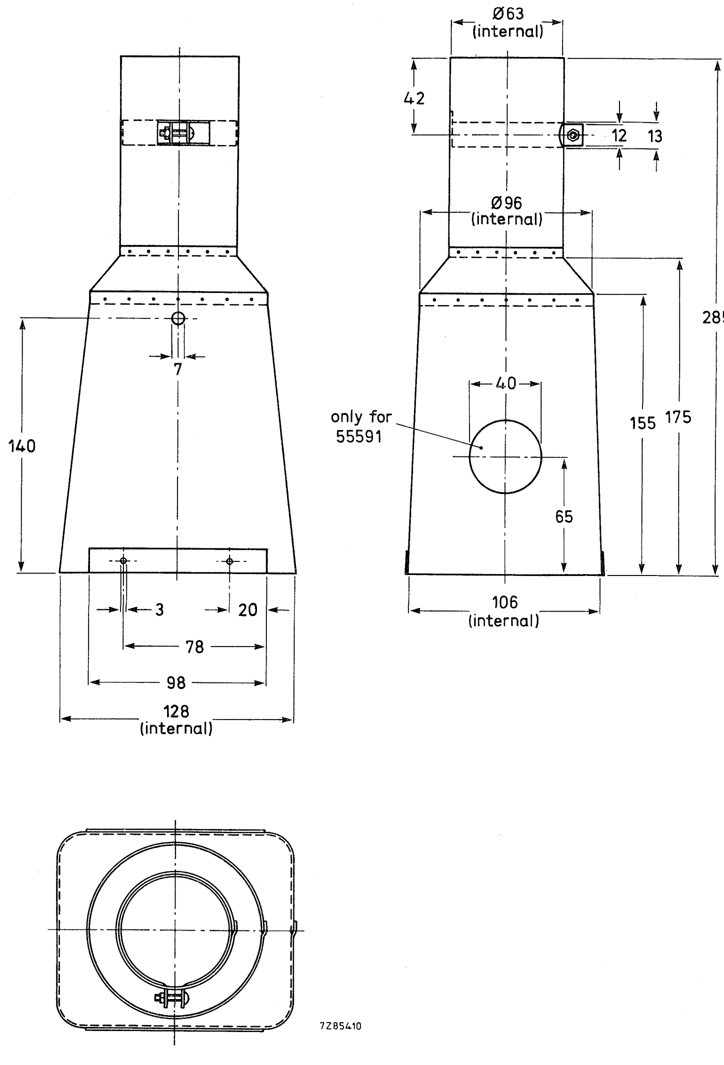
*Internal dimension

TUBE SOCKET

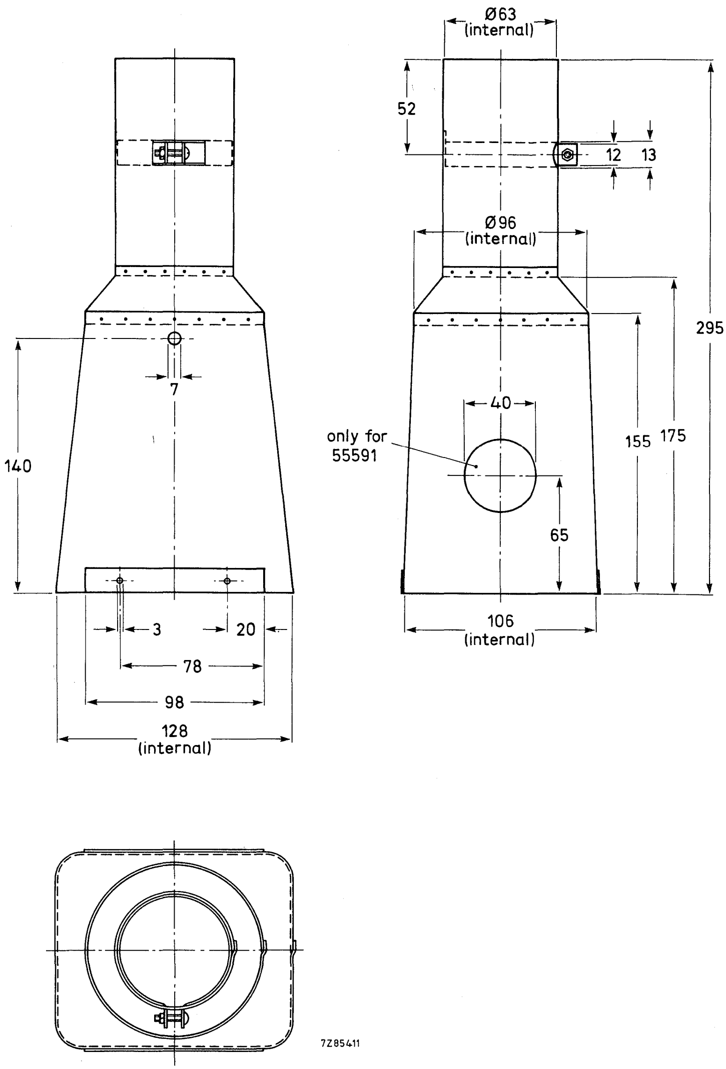
- For 12-pin all glass base



MU-METAL SCREEN

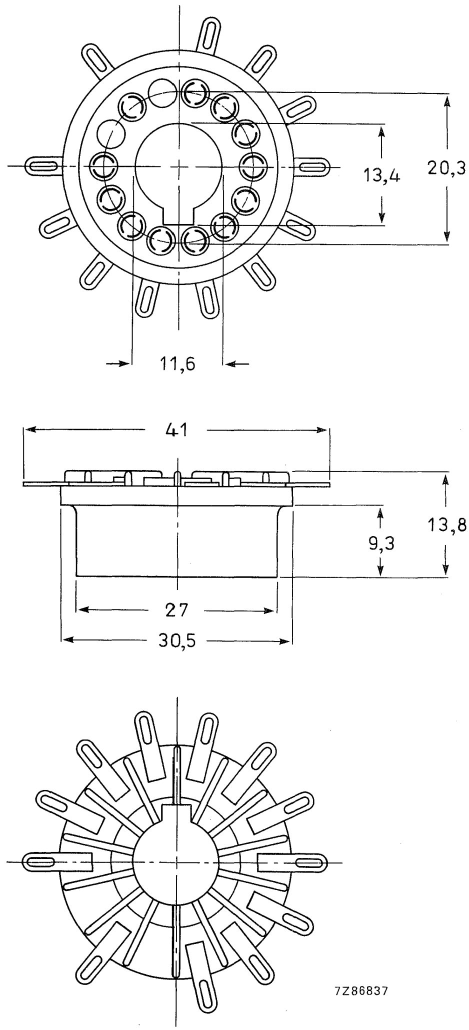


MU-METAL SCREEN



TUBE SOCKET

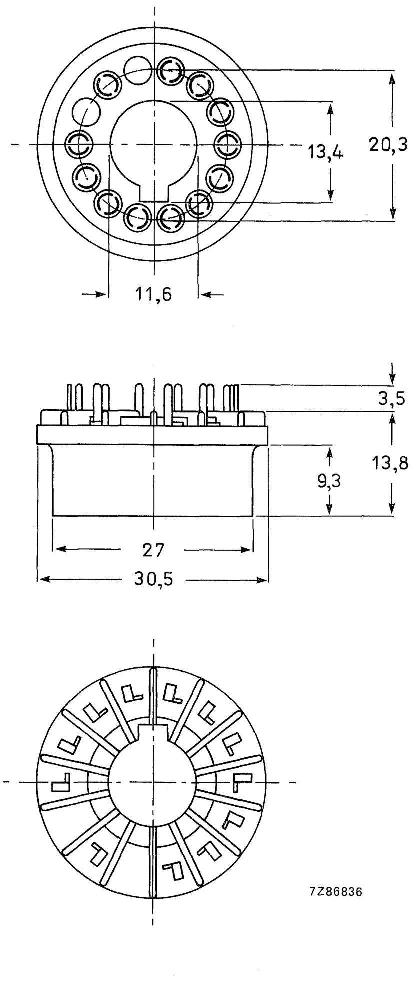
- For 12-pin all glass base, JEDEC B12-246
- Tinned contact springs
- Catalogue number for ordering: 9390 298 20008



7Z86837

TUBE SOCKET

- For 12-pin all glass base, JEDEC B12-246
- Tinned contact springs
- Catalogue number for ordering: 9390 298 30008



BEAM CENTRING MAGNET

INSTRUCTIONS FOR USE

To obtain the best performance from an electrostatically focussed tube, it is important that the axis of the beam should coincide with that of the lens. In practice this is not always so because of small errors in geometry. By means of this magnet it is possible to adjust, if necessary, the position of the beam and so produce a true alignment in every case. The effect is illustrated in Figs 1a and 1b which show enlarged views of a single element in a spot raster under the special operating conditions given in the directions for setting. With a well aligned beam, an image such as that in Fig. 1a can be seen. Very small errors will produce a spot as shown in Fig. 1b where the brightest part of the image does not appear in the centre of the diffused area or haze. In such a case, the picture quality would be good but with only a small adjustment of the beam, so that the brightest part becomes central, a noticeable improvement can be made.

The unit has a non-magnetic ring containing a diametrically magnetized Ferroxdure core and two soft-iron pole pieces covered with plastic material to protect the glass surface.

730723-23-02

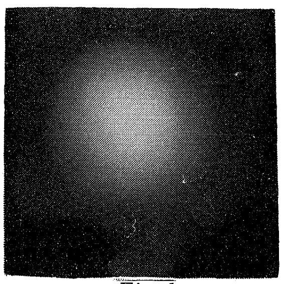


Fig. 1a

730723-23-01

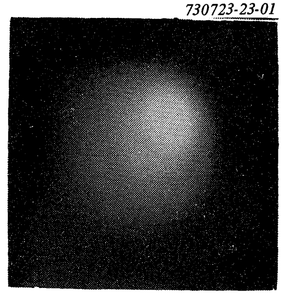


Fig. 1b

The field strength can be altered by turning the core as indicated in Fig. 2, and the direction by turning the whole unit. Moving the unit along the neck of the tube will cause a small change in the position of the beam but it is most effective at about 20 mm from the cap (Fig. 3).

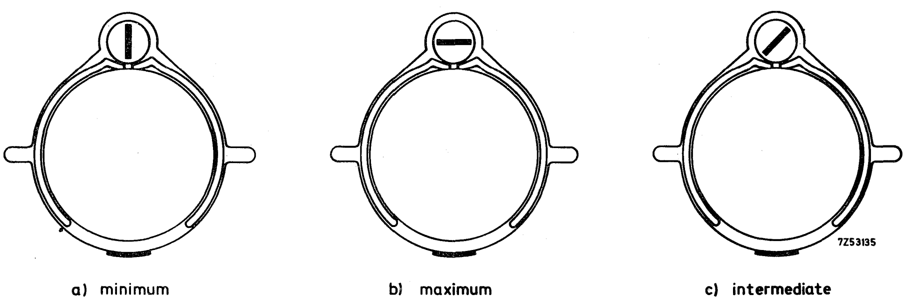


Fig. 2

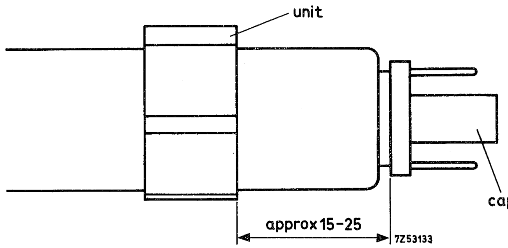


Fig.3

SETTING

This can best be done with a spot raster on the screen, and by observing one of the elements near the centre. A suitable raster would have, for instance, a spot duration of 1/6 μs with a repetition time of 6 μs and an image as in Fig. 1 can then be produced with the following conditions.

V_f	=	6.3 V	or other conditions if required
* V_{g1}	=	0	
V_{g2}	=	600 V	
$V_{g3,\,g5(1)}$	=	16 kV	
V_{g4}	=	−300 to −500 V	

*) To avoid burning the screen, adjust slowly from -50 V to zero

Set the unit on the neck at about 20 mm from the cap and turn it until the brightest part of the image appears central in the haze.

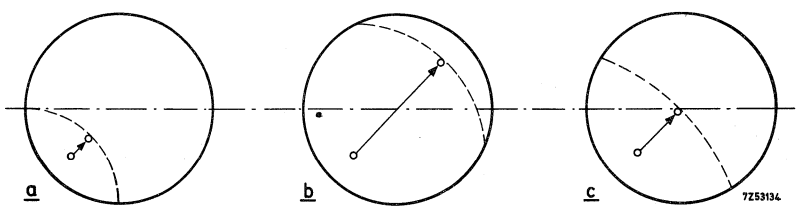
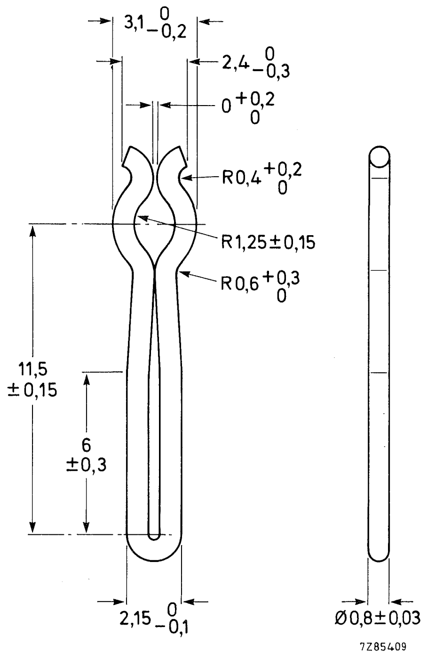


Fig.4

The diagrams in Fig. 4 show the process of adjusting the brightest part from its original position to the centre. The distance between the two points will be determined by the field strength, and the position of the new point along the dotted line will depend on the direction of the field.
If the magnet is under or over-correcting as in (Figs 4a and 4b), the field strength must be changed. To do this, remove the unit from the neck, push the core out sufficiently to get a finger grip and turn it towards maximum or minimum Figs 2a and 2b as required. Return it to the stop in the clamp and set the unit once again on the neck.

If the means of producing a spot raster are not available, a test pattern or suitable picture can be used when setting. It is not easy with this method, however, to assess the degree of change needed in field strength or direction but if a start is made with the line on the core set at about 20^{o} from the minimum position in Fig. 2, an improvement can be made in most cases where it is required. In others, it may be necessary to try one or two further core settings, but with a little experience it is not difficult to find an arrangement which gives the best vertical and horizontal resolution.
The unit should be sufficiently tight on the neck to prevent movement during transit but if, for some reason, this does not appear to be so, the bends on the ring should be compressed slightly.

SMALL BALL CONTACT CONNECTOR



NOTES

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